

Connecting the dots with common sense and linear models

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Introduction

Useful things:

- understanding probabilities,
- understanding statistical learning theory,
- knowing countless statistical procedures,
- knowing countless machine learning algorithms.

Essential things:

- applying common sense,
- paying attention to details,
- being able to setup experiments,
- and to measure the outcome of experiments,
- and to measure plenty of other things,

Connecting the dots

Question:

Find y given x .

x	y
0.31	1.87
0.25	1.84
3.78	2.23
3.30	3.04
3.83	2.68
-3.29	0.01
-0.90	0.37
-3.61	0.37
0.64	2.05
-0.34	0.96
...	

Connecting the dots

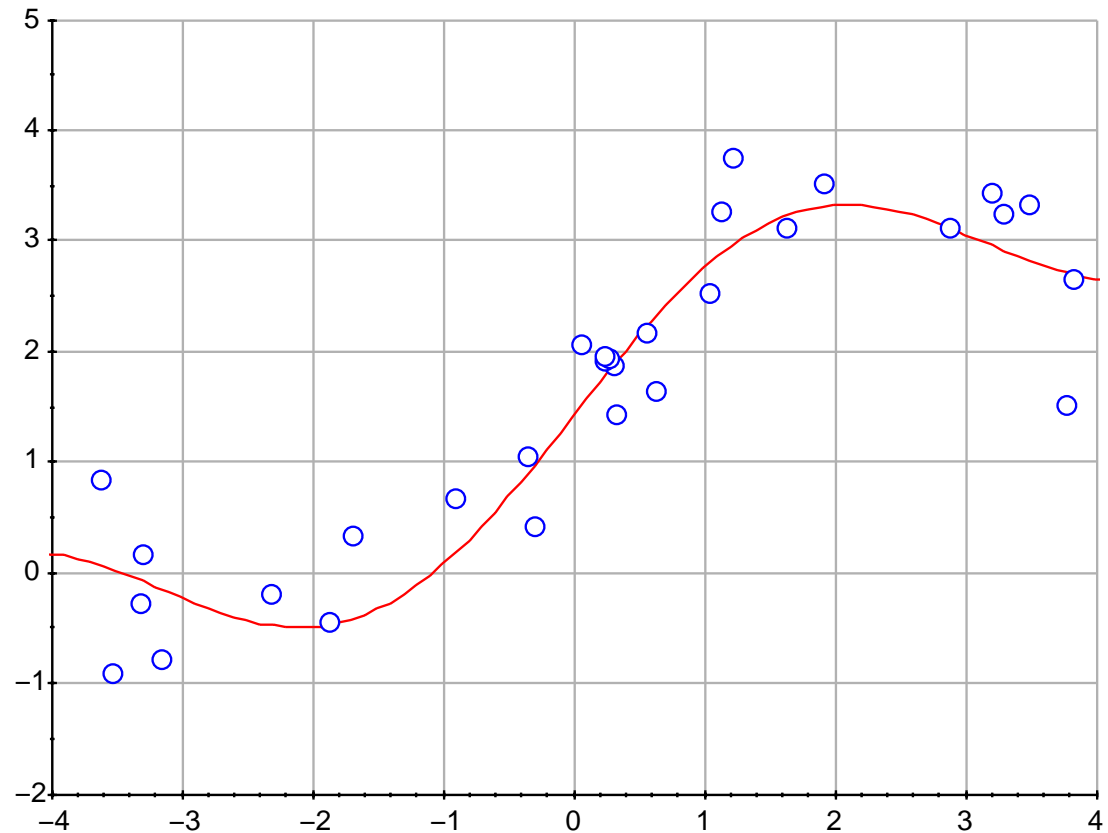
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-3.29	0.01
-0.90	0.37
-3.61	0.37
0.64	2.05
-0.34	0.96
-3.53	-0.35
1.63	3.18
.....

Answer:

Connect the dots. Read the curve.



Connecting the dots – take two

Question: Find y given x .

$[x]_1$	$[x]_2$	$[x]_3$	$[x]_4$	$[x]_5$	$[x]_6$	$[x]_7$	$[x]_8$...	$[x]_{13,123}$	$[x]_{13,124}$	$[x]_{13,125}$	y
0.39	0.50	5.84	-4.36	-0.01	7.20	-7.40	-7.16	...	-5.48	0.77	5.03	5.46
7.34	1.92	-5.66	-5.33	-6.15	-3.14	4.53	6.37	...	-2.30	6.45	5.10	5.18
2.27	4.57	4.18	-6.07	-5.47	-6.97	2.67	-3.93	...	2.77	7.46	4.84	6.97
1.09	-2.17	-6.38	5.66	-2.65	-2.81	-0.69	2.76	...	0.42	5.88	0.29	-7.13
2.85	1.79	6.22	1.34	-1.83	3.01	3.99	-1.75	...	0.03	1.55	-3.32	-5.42
-5.67	2.53	-3.47	-0.46	3.21	-2.73	6.65	-0.77	...	-1.41	-3.93	3.14	5.37
3.80	-0.00	1.89	3.24	2.30	-1.45	7.63	-2.12	...	6.47	2.04	3.58	-4.96
7.54	2.47	6.39	4.95	-2.51	-6.46	0.49	-0.61	...	5.10	1.90	1.79	3.20
-7.99	4.93	-2.13	-7.11	-5.10	2.13	6.31	7.00	...	1.71	-2.35	-7.87	-4.70
-6.80	7.33	-0.99	4.17	-7.81	-7.64	4.01	-3.37	...	7.29	-2.41	7.66	-6.70
-0.78	5.34	-5.94	-1.76	3.79	2.92	0.75	7.04	...	-3.87	-1.46	-3.37	-3.66
7.54	2.47	6.39	4.95	-2.51	-6.46	0.49	-0.61	...	5.10	1.90	1.79	3.20
-7.99	4.93	-2.13	-7.11	-5.10	2.13	6.31	7.00	...	1.71	-2.35	-7.87	-4.70
-6.80	7.33	-0.99	4.17	-7.81	-7.64	4.01	-3.37	...	7.29	-2.41	7.66	-6.70
.....												

Idea: (1) understand how we do the 2D case. (2) generalize!

A Simple Linear Model

Polynomial: $f(x) = w_0 + w_1x + w_2x^2 + \dots + w_nx^n$

Slight generalization:

$$x \longrightarrow \Phi(x) = \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \dots \\ \phi_n(x) \end{bmatrix} \longrightarrow f(x) = [w_0, w_1, \dots, w_n] \times \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \dots \\ \phi_n(x) \end{bmatrix}$$

Equivalently: $f(x) = w^\top \Phi(x)$

Lets choose a basis Φ and use the data to determine w .

Linear Least Squares

Input : x_i

Output : $w^\top \Phi(x_i)$

Desired Output : y_i

Difference : $y_i - w^\top \Phi(x_i)$

Minimize : $C(w) = \sum_{i=1}^n (y_i - w^\top \Phi(x_i))^2$

Quadratic convex function in w .

The minimum exists and is unique.

But it could be reached for multiple values of w .

A little bit of Linear Algebra

At the optimum,
$$\frac{dC}{dw} = \sum_{i=1}^n 2 (y_i - w^\top \Phi(x_i)) \Phi(x_i)^\top = 0$$

Therefore we must solve the system of equations :

$$\left[\sum_{i=1}^n \Phi(x_i) \Phi(x_i)^\top \right] \times w = \left[\sum_{i=1}^n y_i \Phi(x_i) \right]$$

Shorthand form :

$$(X^\top X) w = (X^\top Y)$$

Singularities

Almost the same as $w = (X^T X)^{-1} (X^T Y)$.

You should **never** solve a system by inverting a matrix.

Who said $X^T X$ is invertible?

Consider the case where $\phi_1(x) = \phi_8(x)$

- the matrix $X^T X$ is **singular**.
- but the minimum is unchanged.
- the minimum is reached by many w ,
as long as $w_1 + w_8$ remains constant.

Among the w that minimize $C(w)$,
compute the one with the **smallest norm**.

Numerical Procedures

Diagonalization of $X^\top X$

$$Q^\top D Q w = X^\top Y \iff w = Q^\top D^+ Q X^\top Y$$

Traditional methods: SVD or QR decomposition of X

$$V D U^\top U D V^\top w = V D U^\top Y \iff w = V D^+ U^\top Y$$

$$R^\top Q^\top Q R w = R^\top Q^\top Y \iff R w = Q^\top Y$$

and solve using back-substitution.

Simple and Fast: Regularization + Cholevsky

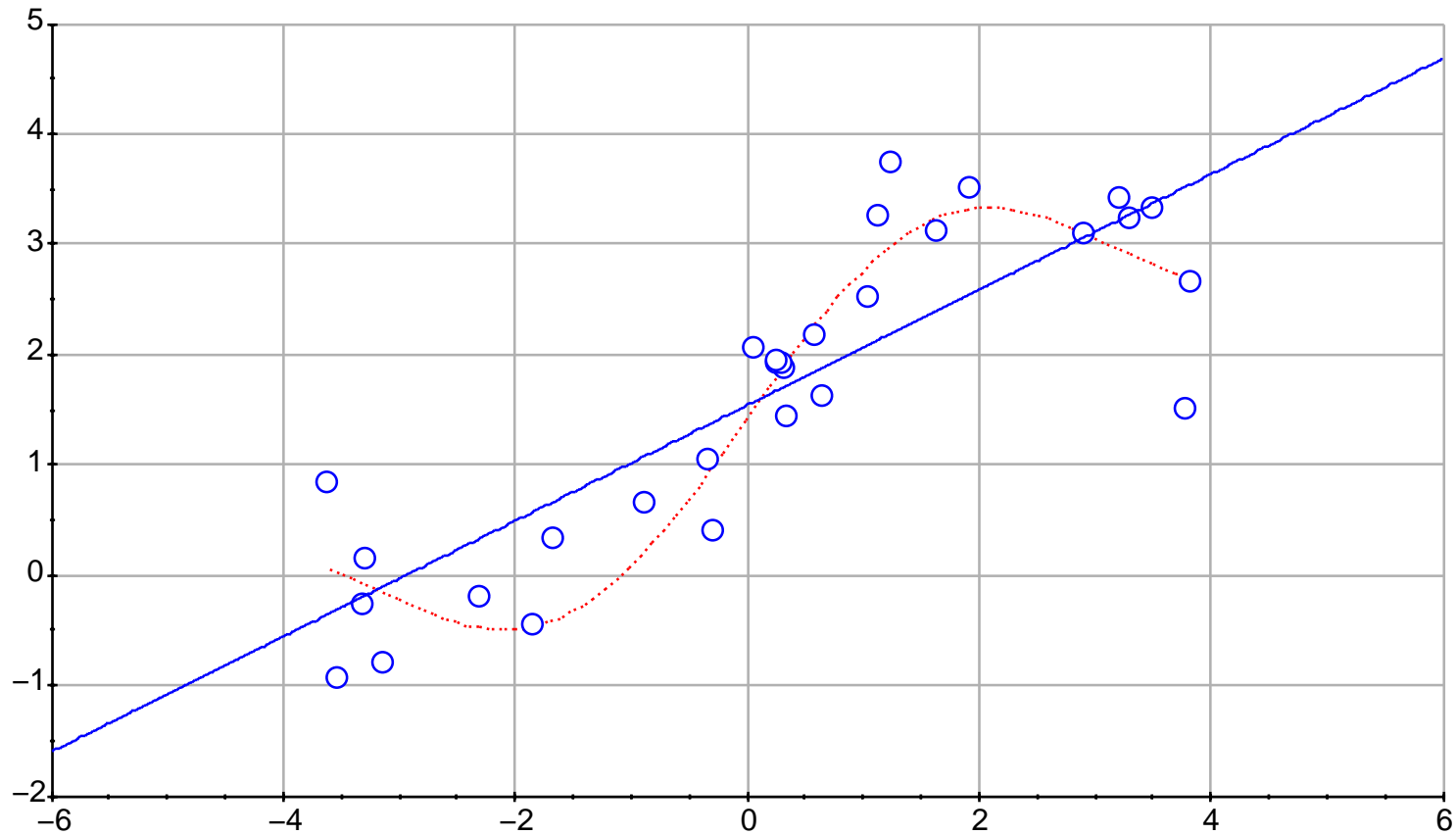
$$\begin{aligned} \min C(w) + \varepsilon w^2 &\iff (X^\top X + \varepsilon I) w = (X^\top Y) \\ &\iff U U^\top w = (X^\top Y) \end{aligned}$$

and solve using two rounds of back-substitution.

Polynomial degree 1

$$\Phi(x) = 1, x$$

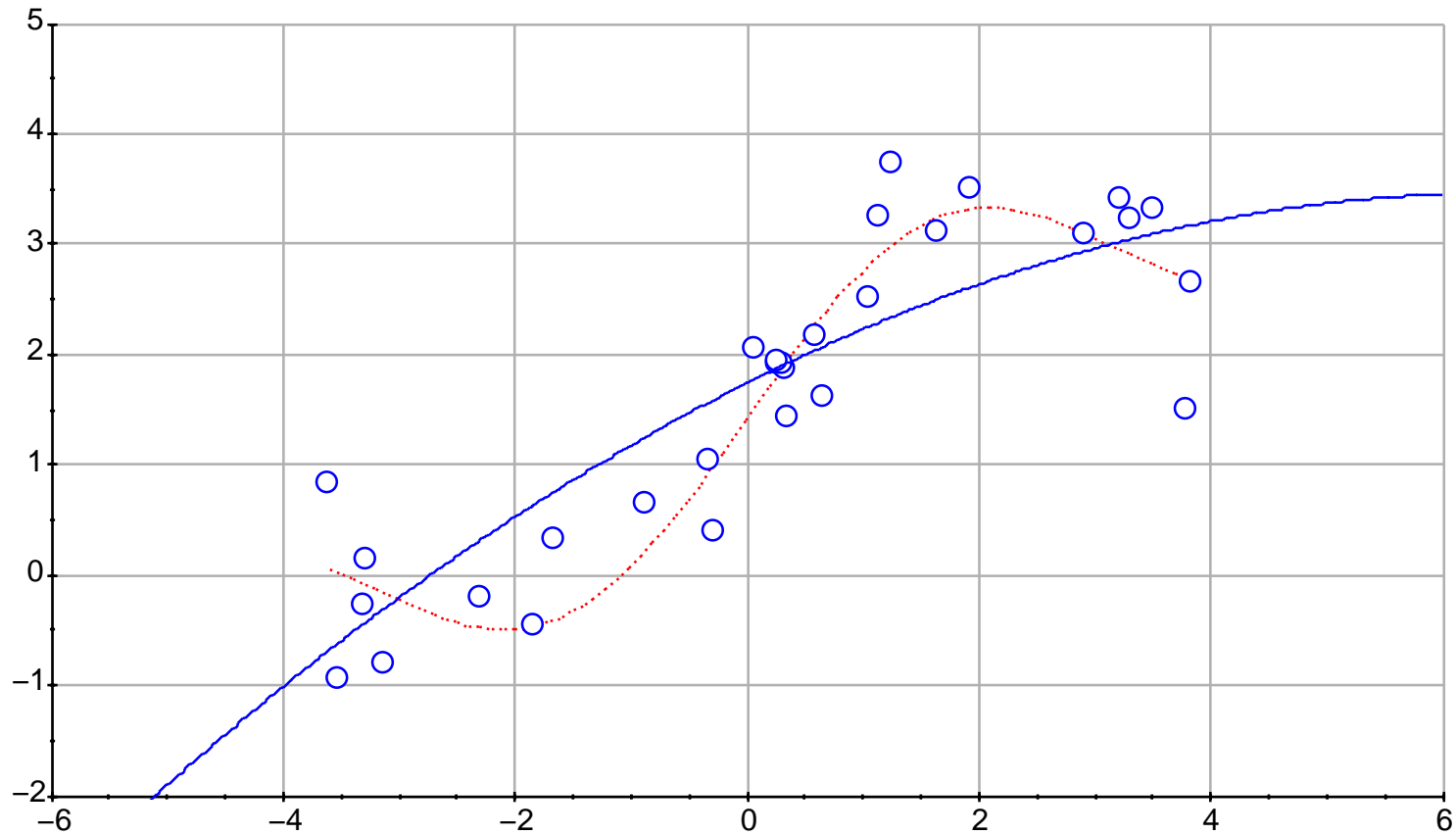
Polynomial d=1



Polynomial degree 2

$$\Phi(x) = 1, x, x^2$$

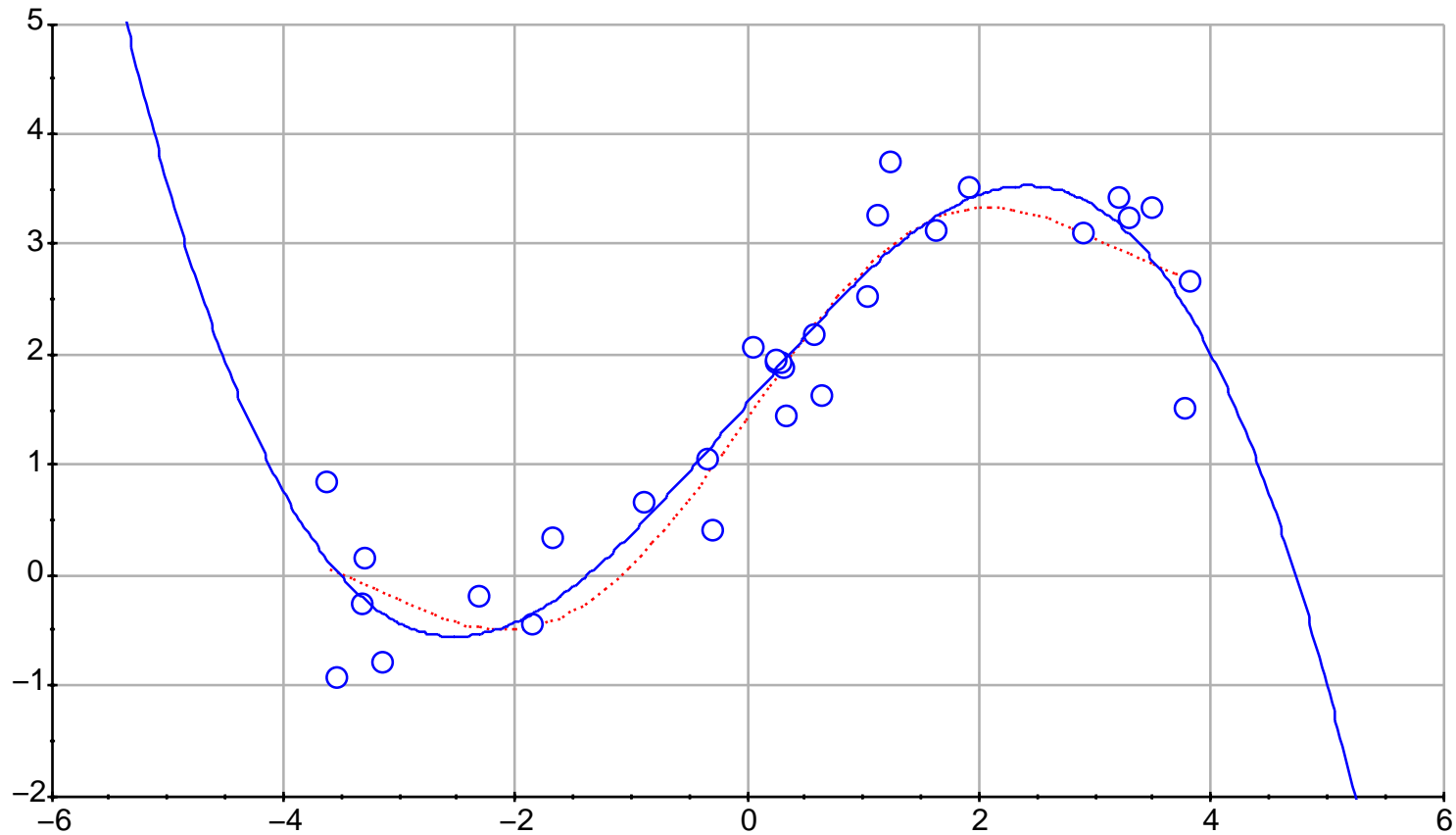
Polynomial d=2



Polynomial degree 3

$$\Phi(x) = 1, x, x^2, x^3$$

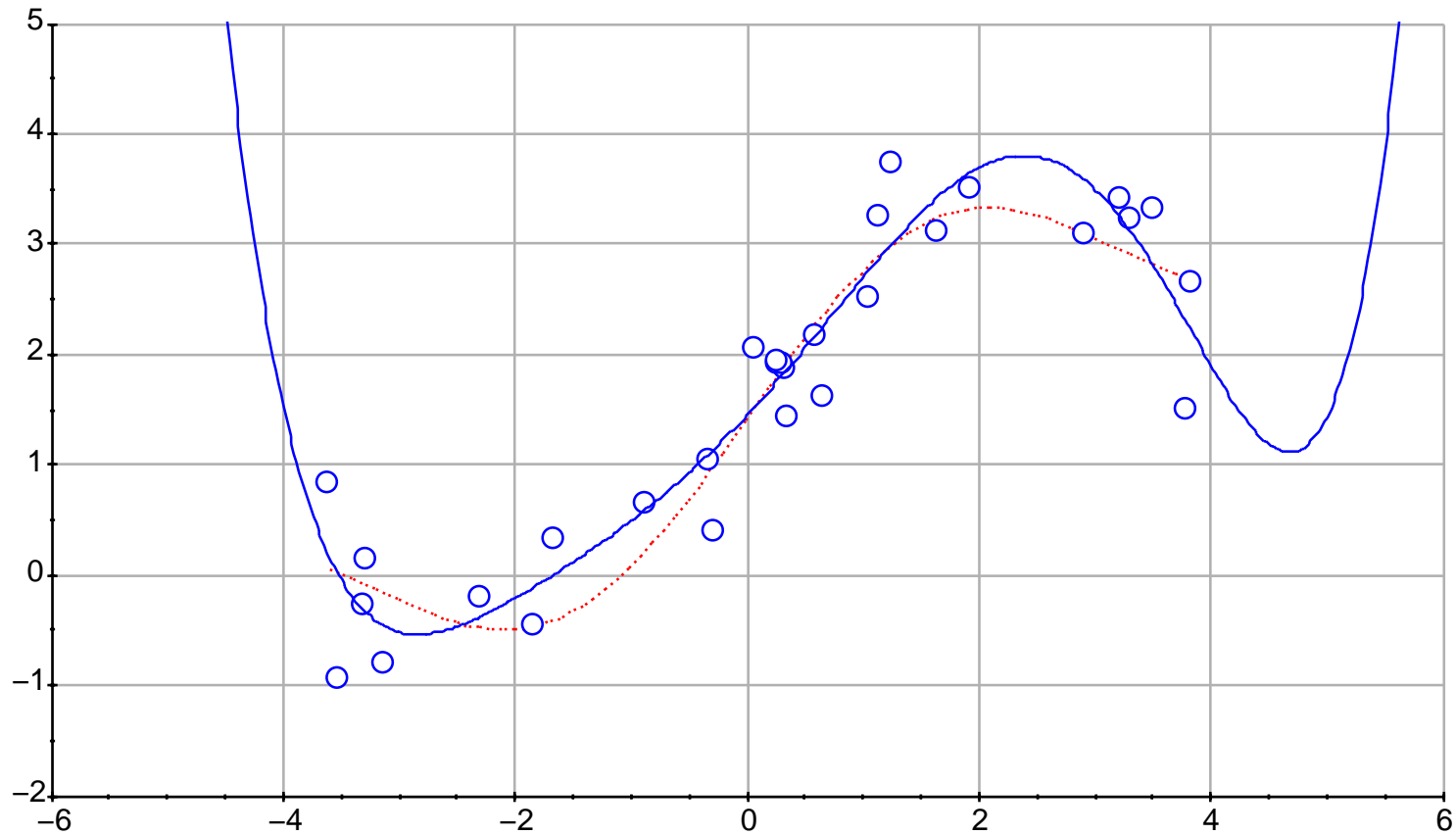
Polynomial d=3



Polynomial degree 6

$$\Phi(x) = 1, x, x^2, x^3, x^4, x^5, x^6$$

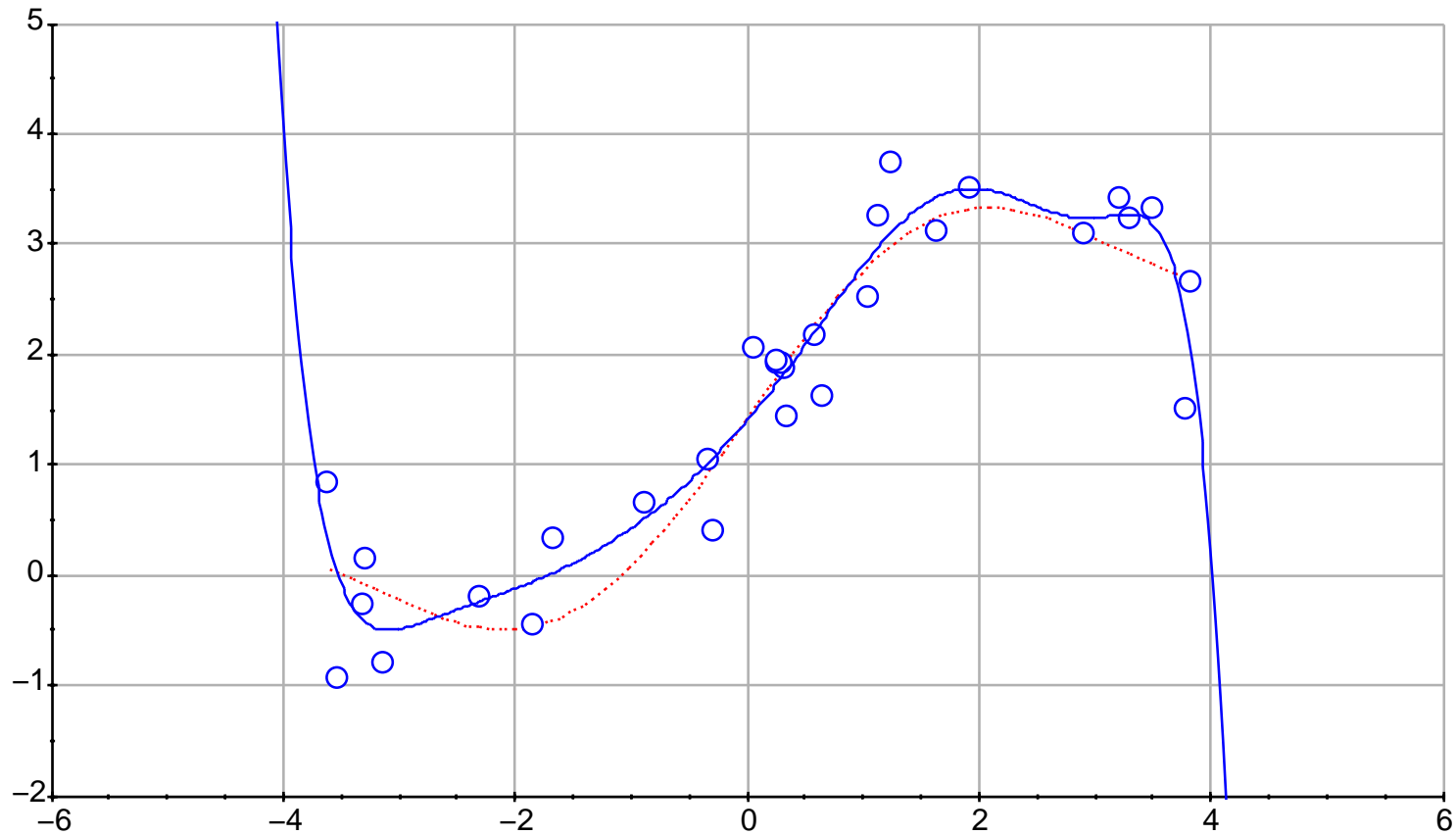
Polynomial d=6



Polynomial degree 9

$$\Phi(x) = 1, x, x^2, \dots, x^9$$

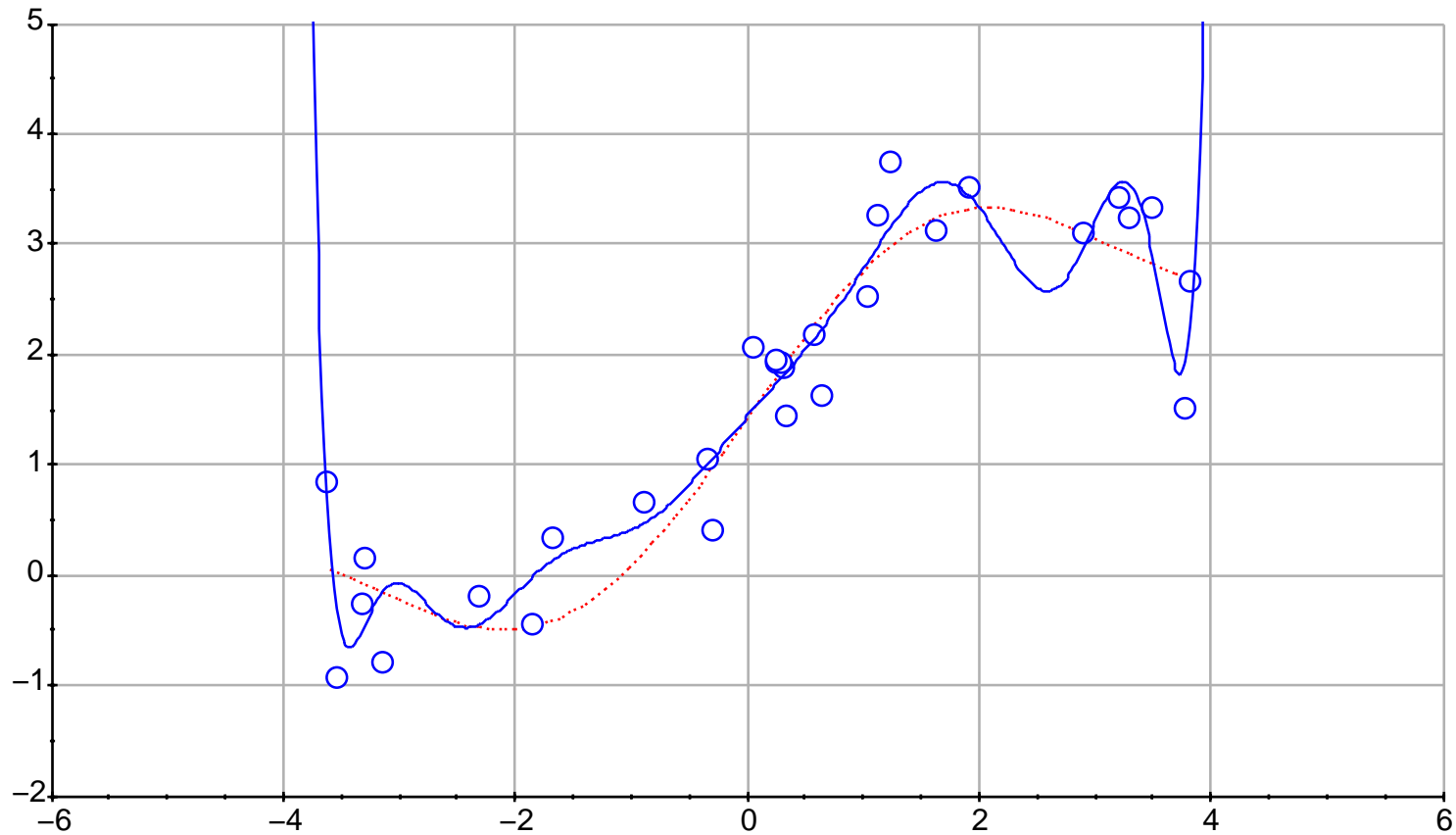
Polynomial d=9



Polynomial degree 12

$$\Phi(x) = 1, x, x^2, \dots, x^{12}$$

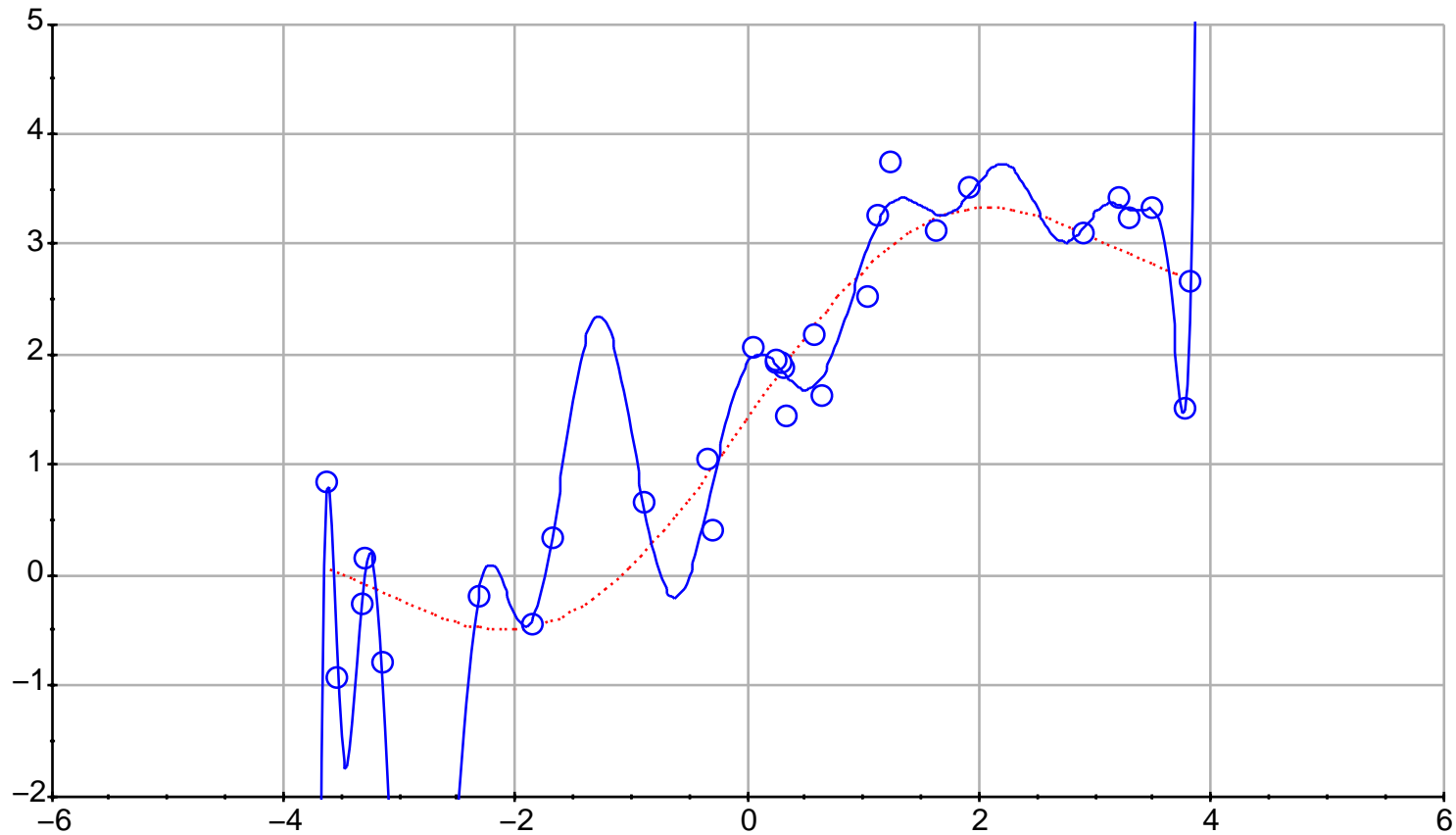
Polynomial d=12



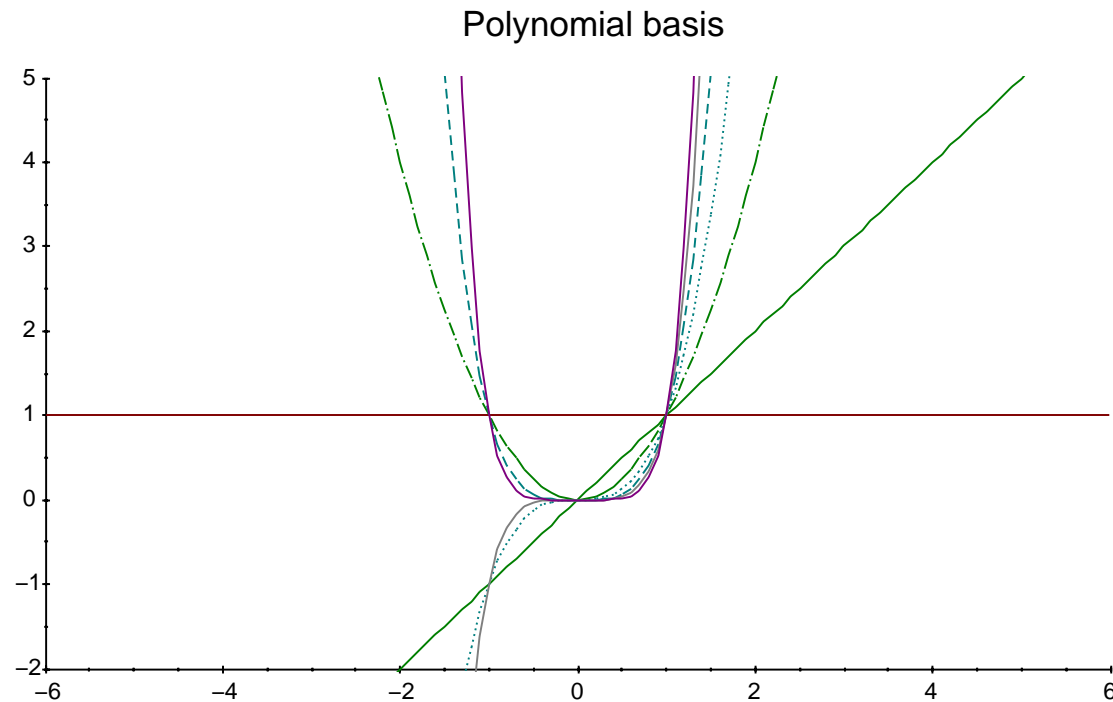
Polynomial degree 20

$$\Phi(x) = 1, x, x^2, \dots, x^{20}$$

Polynomial d=20



Polynomial Basis



Polynomials of the form x^k quickly become very steep.
There are much better polynomial bases : e.g. Chebyshev, Hermite, ...

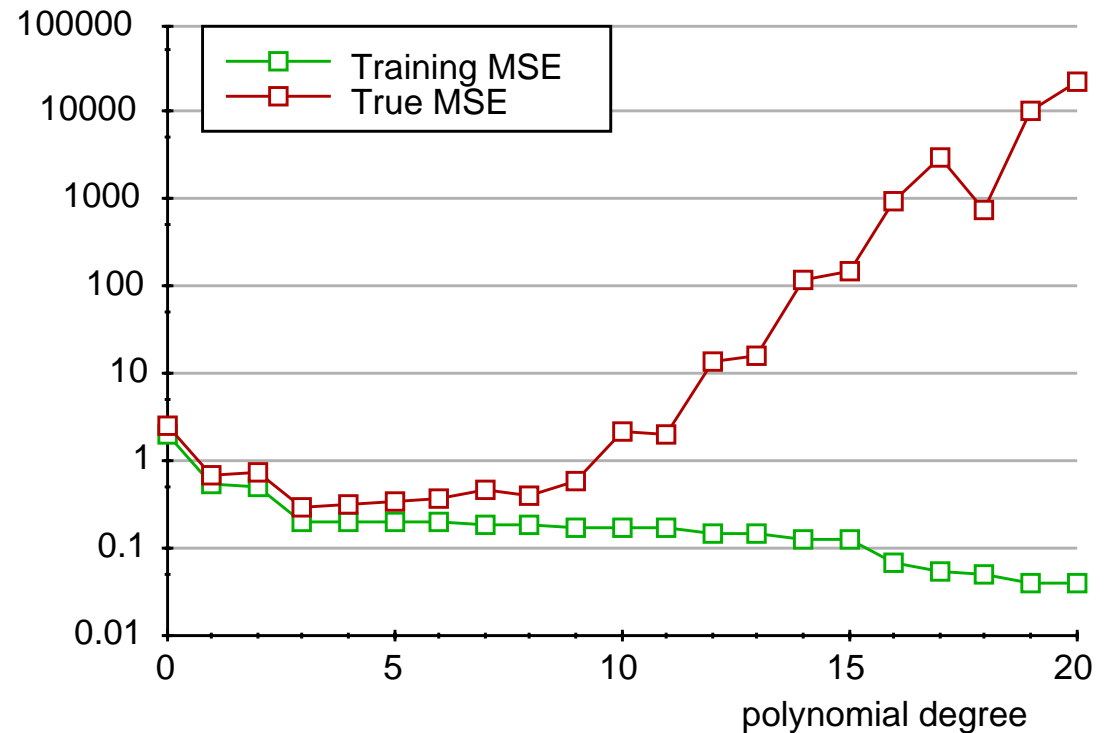
Mean squared error for polynomial models

Training set MSE:

$$\frac{1}{n} \sum_{i=1}^n (y_i - \hat{f}(x_i))^2$$

True MSE:

$$\frac{1}{8} \int_{-4}^{+4} \sigma_{\text{true}}^2 + (f_{\text{true}}(x) - \hat{f}(x))^2 dx$$



Is MSE a good measure of the error ?

Why integrating on $[-4, +4]$?

About Error Measures

Domain

- should be related to the input data distribution.

Metric

- Uniform metric: L_∞
- Averaged with a L_p norm, e.g. MSE.

Derivatives

- **Very close functions** can have **very different derivatives**.
- Sobolev metrics.

Integrals

- Conversely, **very close functions** always have **very close integrals**.

Piecewise Linear Basis

Choose **knots** $r_1 \dots r_k$

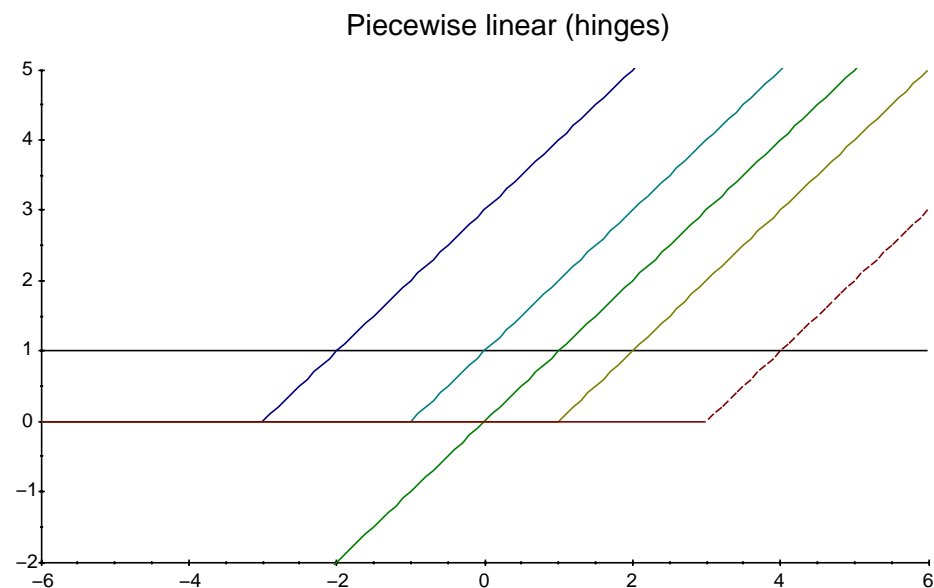
$$\phi_0(x) = 1$$

$$\phi_1(x) = x$$

$$\phi_2(x) = \max(0, x - r_1)$$

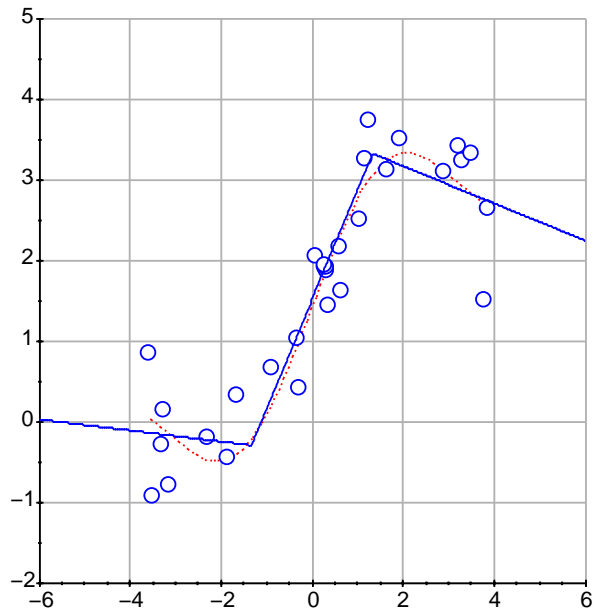
...

$$\phi_j(x) = \max(0, x - r_{j-1})$$

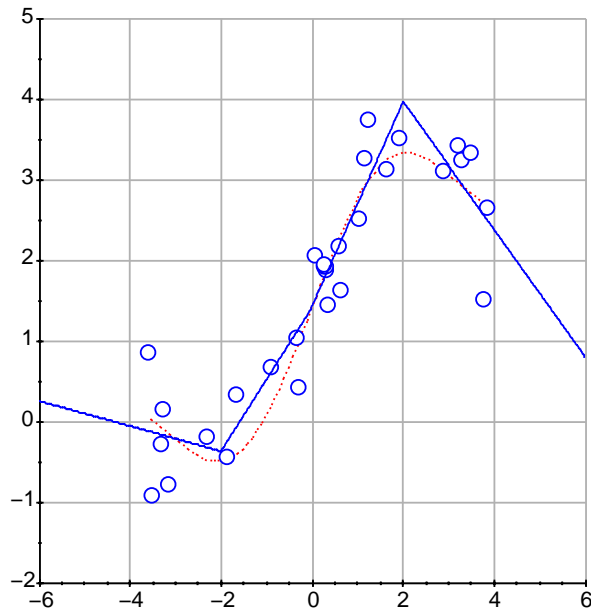


Piecewise Linear Models

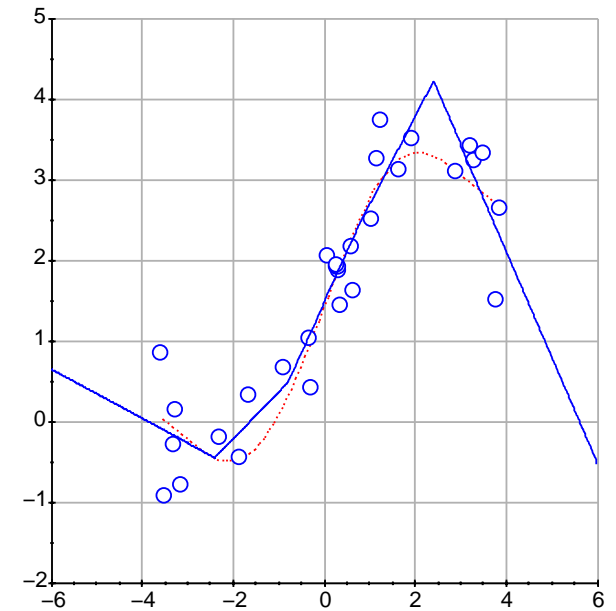
Piecewise linear with 2 knots



Piecewise linear with 3 knots

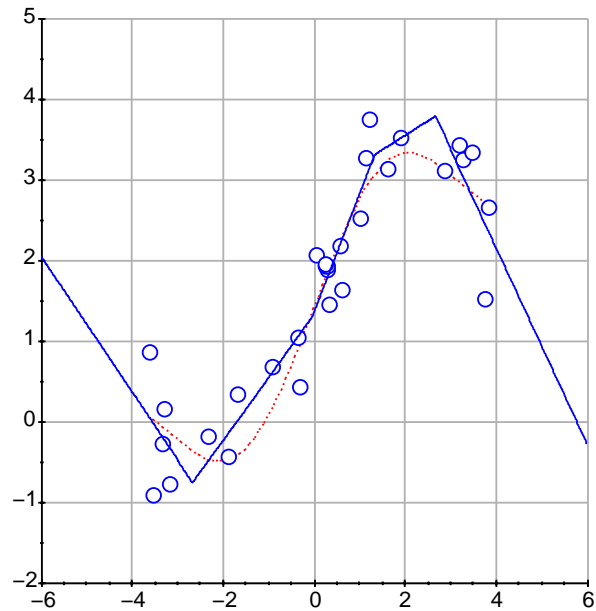


Piecewise linear with 4 knots

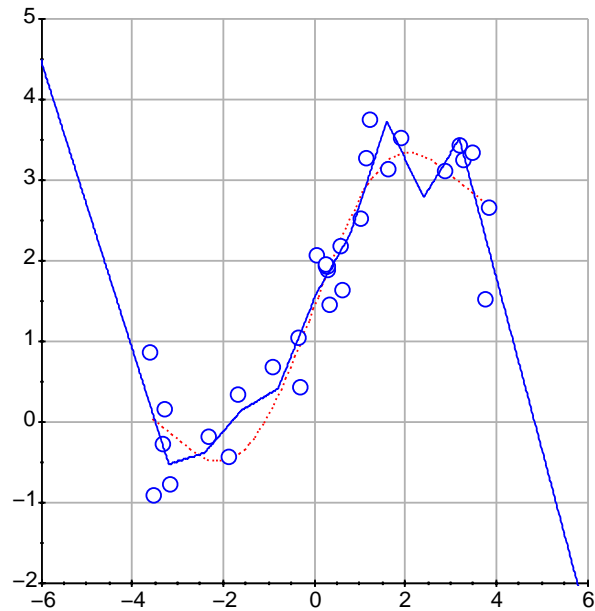


Piecewise Linear Models

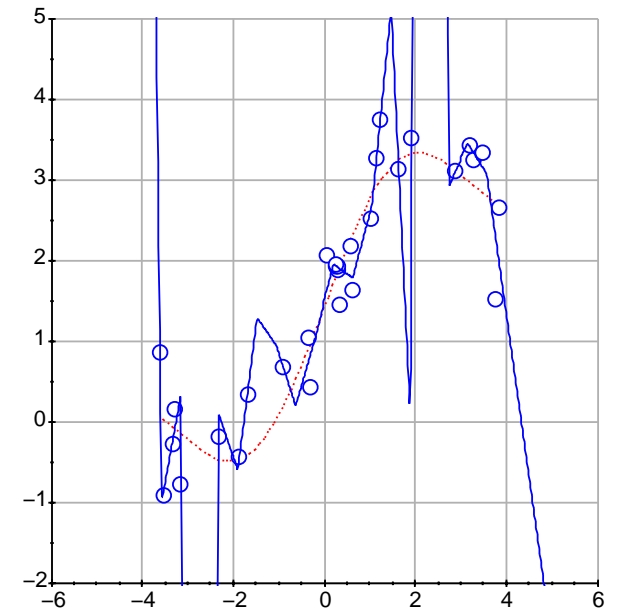
Piecewise linear with 5 knots



Piecewise linear with 9 knots



Piecewise linear with 18 knots



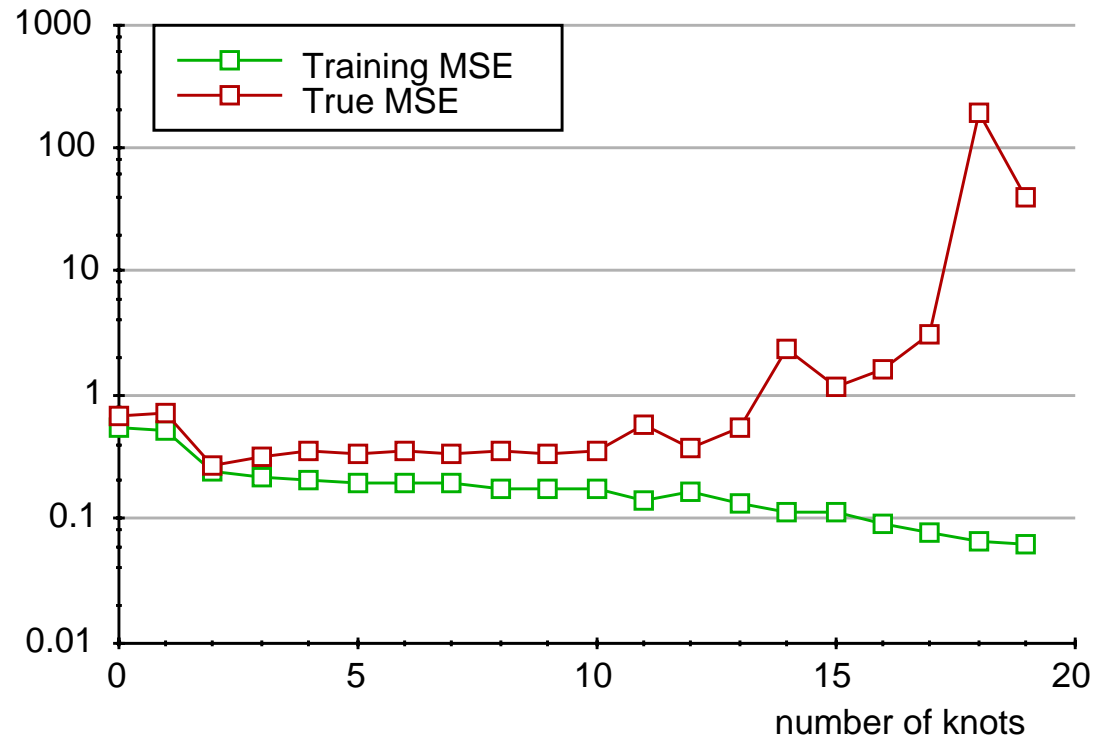
MSE for Piecewise Linear Models

Training set MSE:

$$\frac{1}{n} \sum_{i=1}^n (y_i - \hat{f}(x_i))^2$$

True MSE:

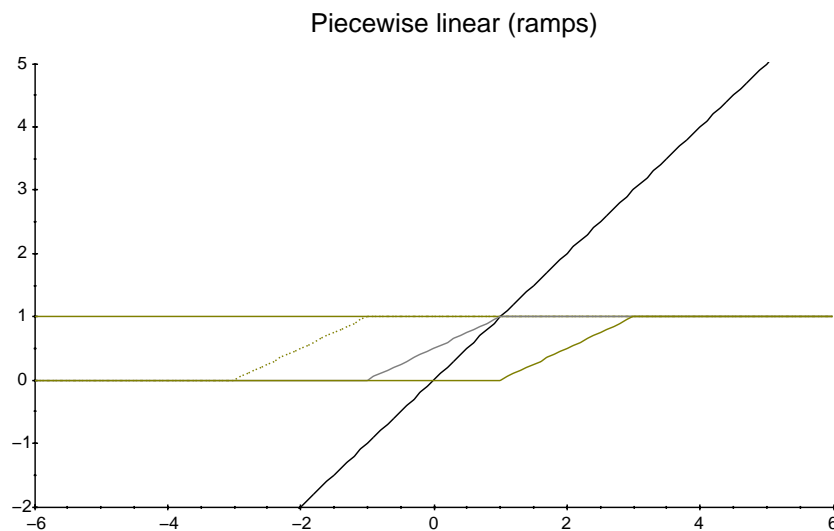
$$\frac{1}{8} \int_{-4}^{+4} \sigma_{\text{true}}^2 + (f_{\text{true}}(x) - \hat{f}(x))^2 dx$$



Piecewise Linear Variants

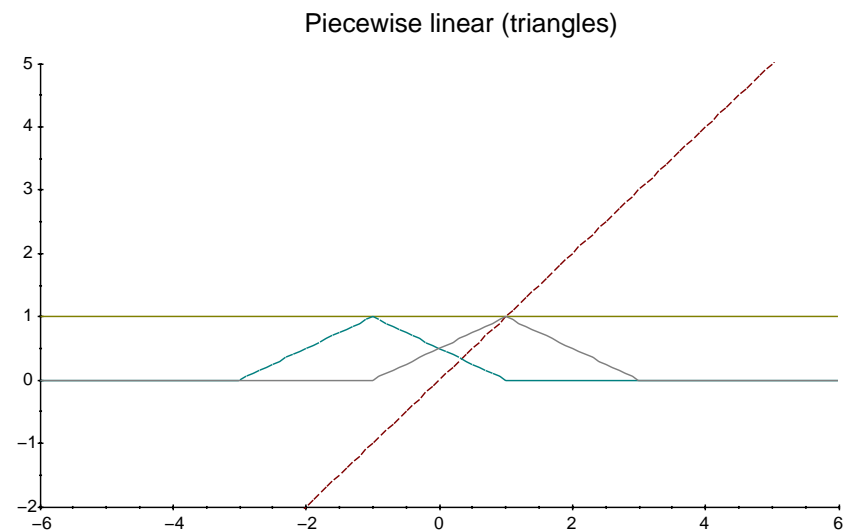
Counting the dimensions

- Linear functions on $K + 1$ segments: $2K + 2$ parameters.
- Continuity constraints: K constraints.
- Other constraints: 0 (hinges), 1 (ramps), 2 (triangles).



Ramps

$$\dim(\Phi) = K + 1$$

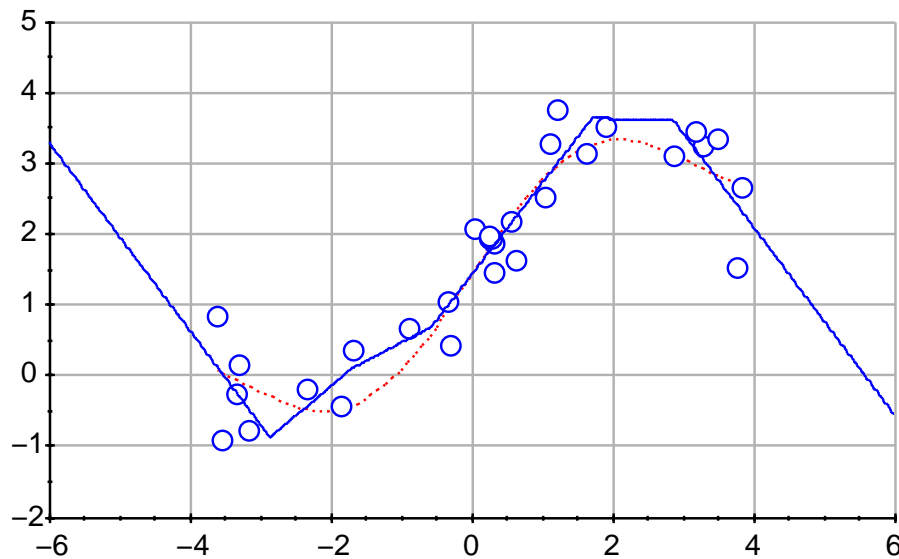


Triangles

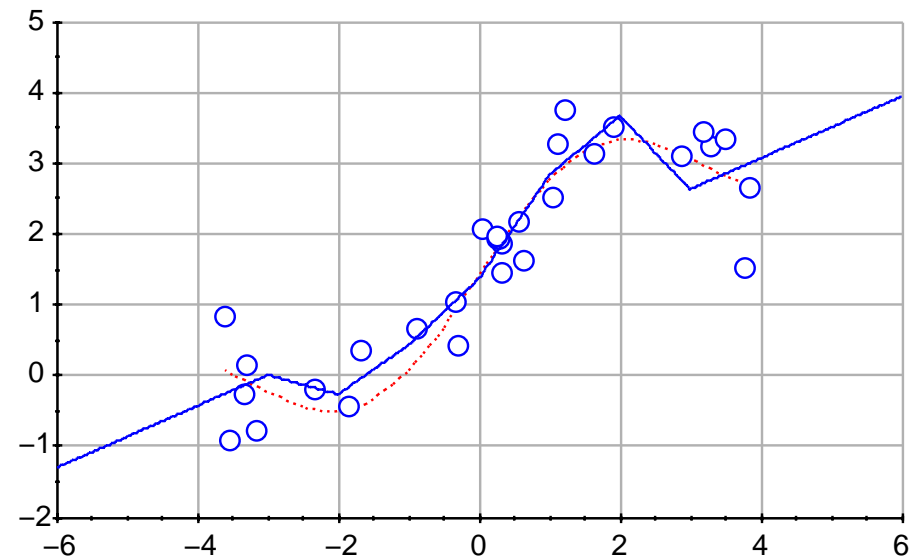
$$\dim(\Phi) = K$$

Piecewise Linear Variants

Piecewise ramps with 6 knots

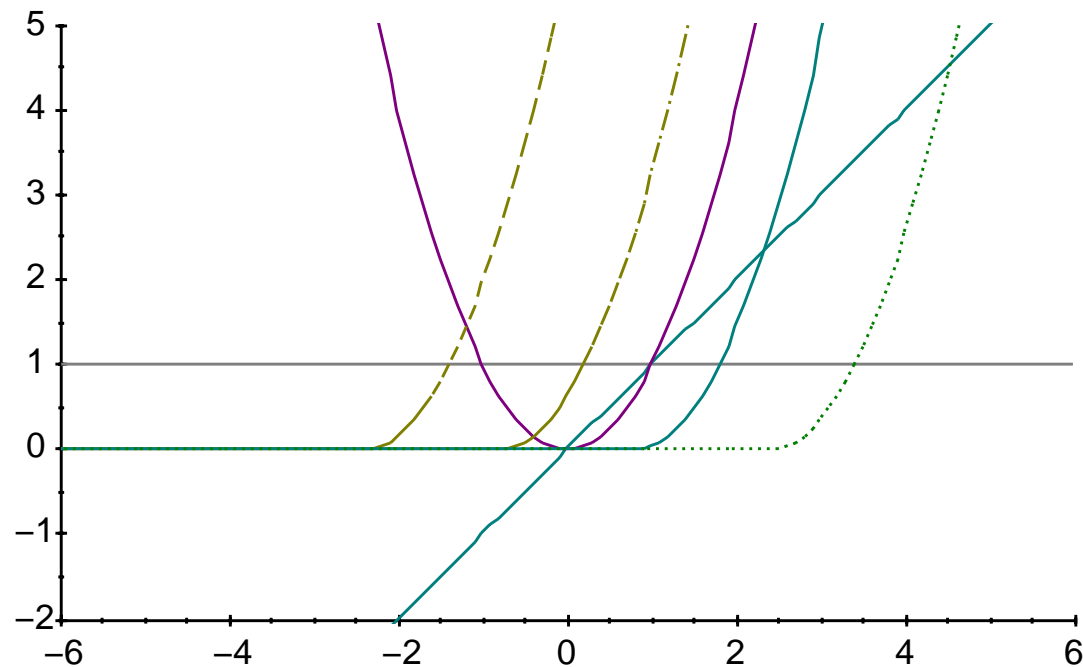


Piecewise triangles with 7 knots



Piecewise Polynomial (Splines)

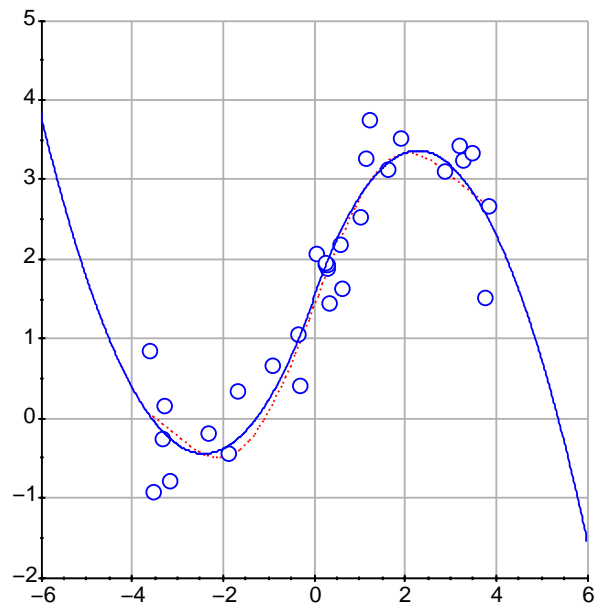
Piecewise quadratic



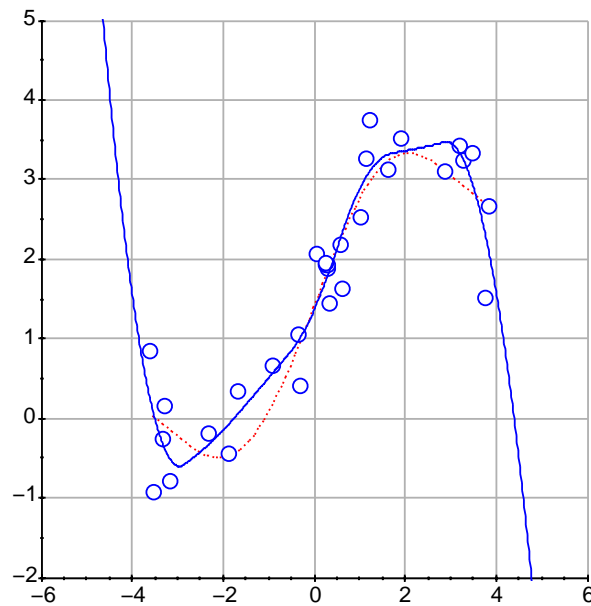
- Quadratic splines : $\Phi(x) = 1, x, x^2, \dots, \max(0, x - r_k)^2, \dots$
- Cubic splines : $\Phi(x) = 1, x, x^2, x^3, \dots, \max(0, x - r_k)^3, \dots$

Quadratic Splines

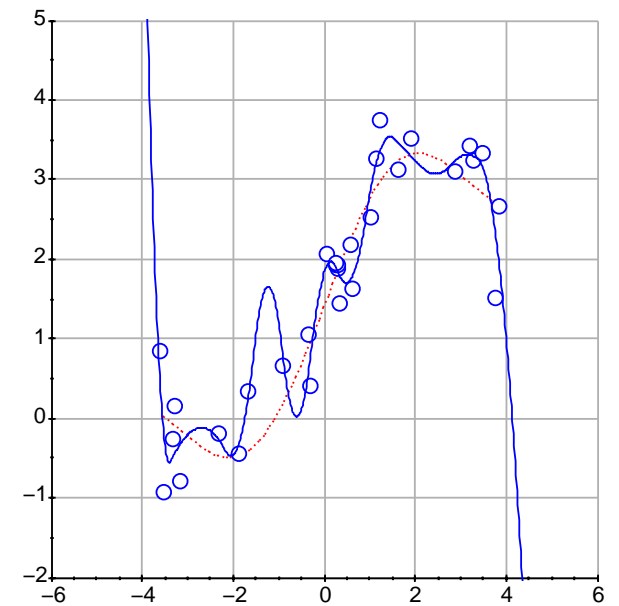
Piecewise quadratic with 1 knot



Piecewise quadratic with 6 knots



Piecewise quadratic with 12 knots



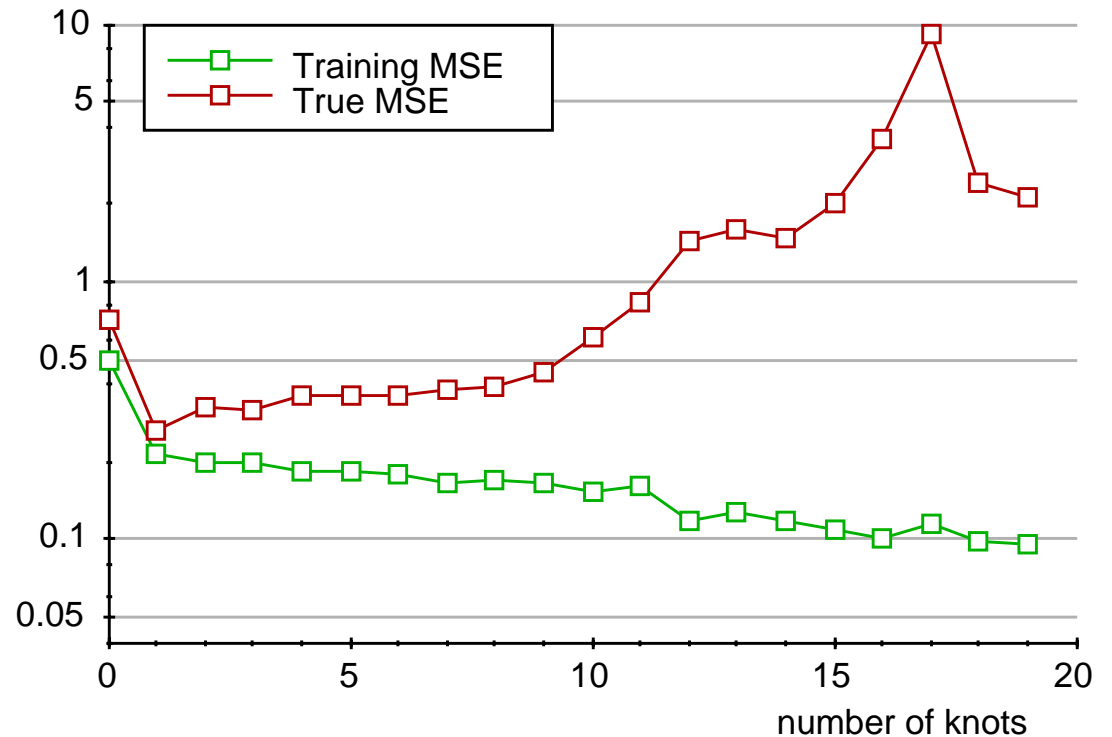
MSE for Quadratic Splines

Training set MSE:

$$\frac{1}{n} \sum_{i=1}^n (y_i - \hat{f}(x_i))^2$$

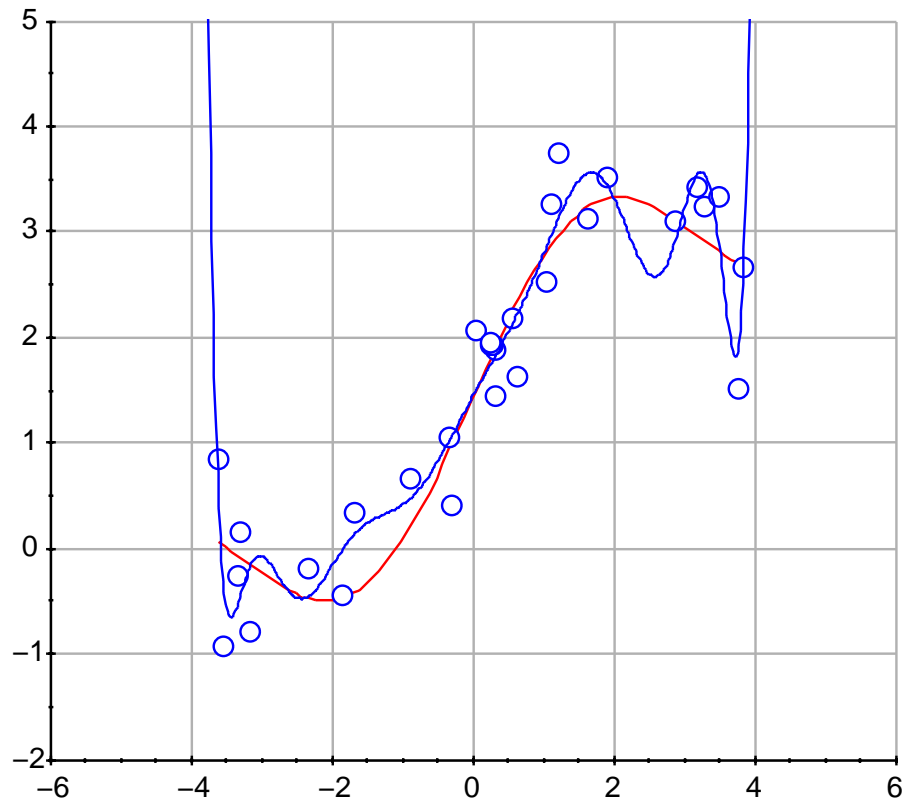
True MSE:

$$\frac{1}{8} \int_{-4}^{+4} \sigma_{\text{true}}^2 + (f_{\text{true}}(x) - \hat{f}(x))^2 dx$$



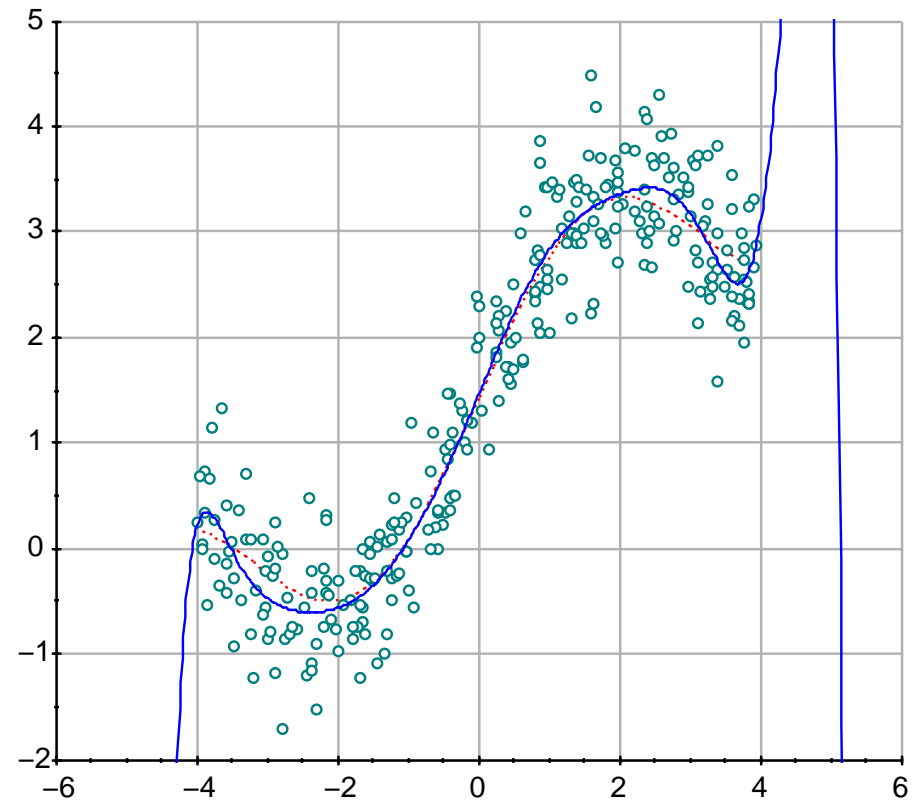
Changing the training data: more examples

Polynomial $d=12$



30 examples

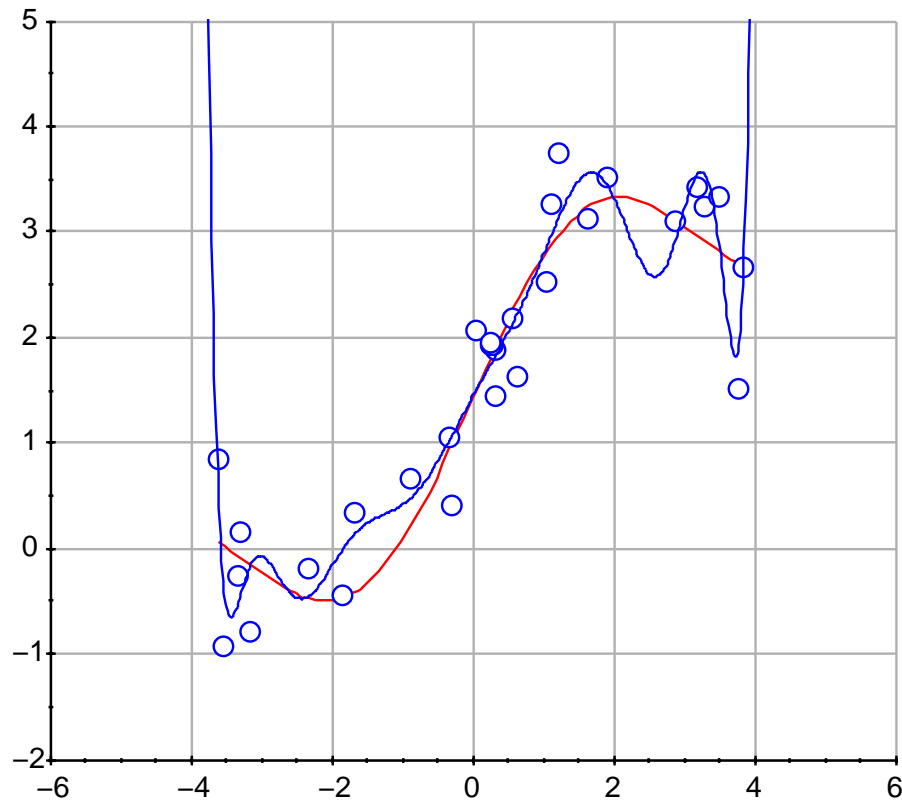
Polynomial $d=12$ (more examples)



300 examples

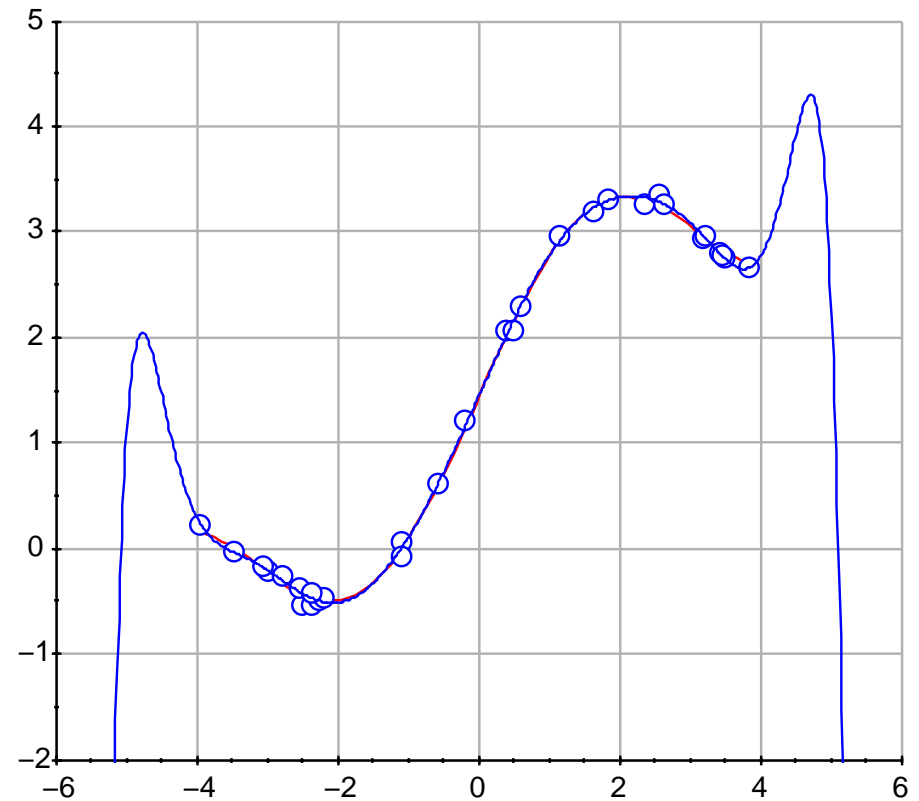
Changing the training data: less noise

Polynomial $d=12$



Noise sdev=0.5

Polynomial $d=12$ (less noise)



Noise sdev=0.1

First Conclusions

The fancier the models, the higher the price.

- We can pay with more data.
- We can pay with better data.

In practice we do the converse.

- Changing the data is usually more costly than changing the model.
- Adapt the model “**capacity**” to the data.
- No shortage of methods.

The validation questions.

- We have too many options. How to choose one?
- How to estimate the quality of our work?

Estimate the quality of our work

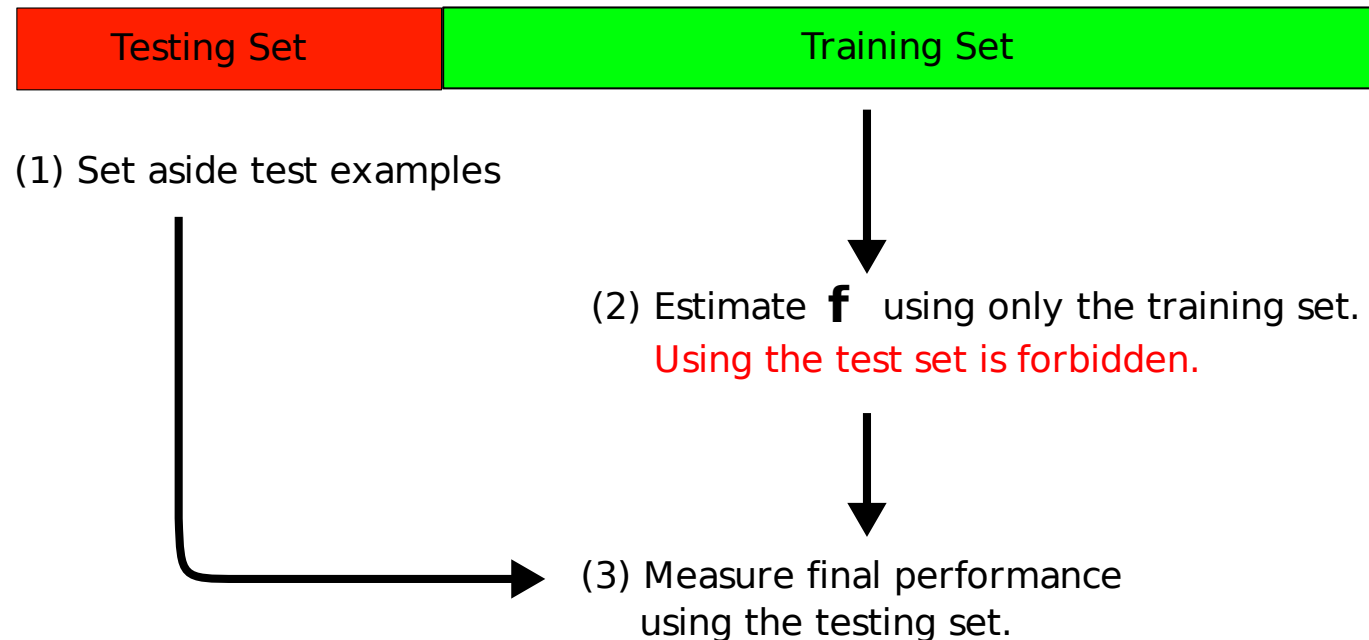
Performance on the training data is not convincing

- Cannot distinguish between learning by rote and understanding.
- Understanding leads to more useful predictions than learning by rote.
- Therefore **we need fresh data** to evaluate our work.
- **Testing examples set aside before starting the work.**
 - Statistics work for randomly picked testing examples.
 - Real life suggests selected testing examples (e.g. time series.)
- **Testing data of a different nature.**
 - New perspective on the same phenomenon.
 - Often more instructive and convincing.

What about the “elegance” of a model ?

- Einstein: *“Make everything as simple as possible, but not simpler.”*
- How do you define “simple” ?

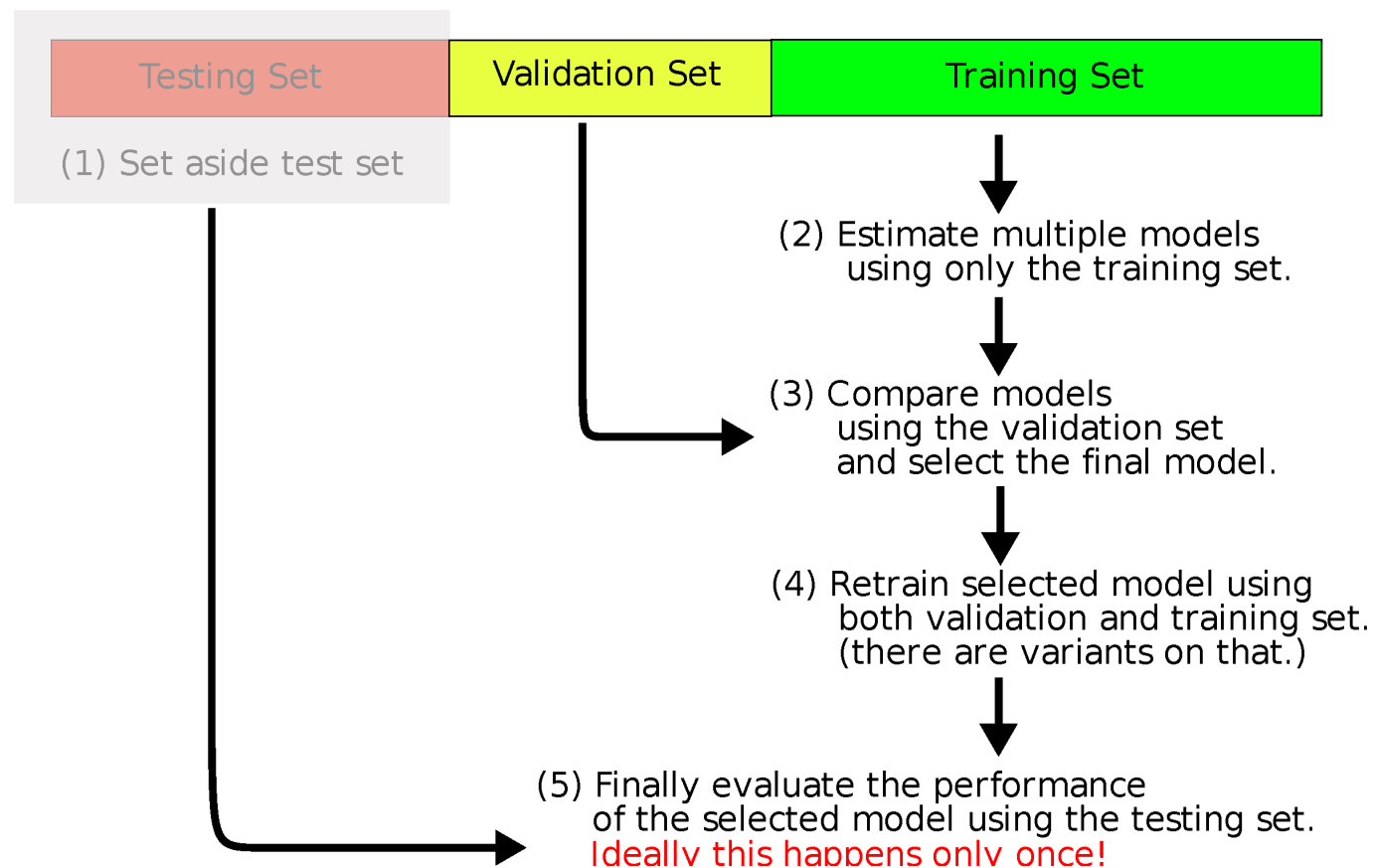
The “training set/testing set” paradigm



- One should only **use the testing set once!** Of course. . .
- The more we look at the testing set, the less convincing we are.
- Public benchmarks and their problems.

The “validation set”

How to select the right model without looking at the testing set ?



Potential problems

All this consumes valuable examples!

- This is a serious problem when examples are rare!

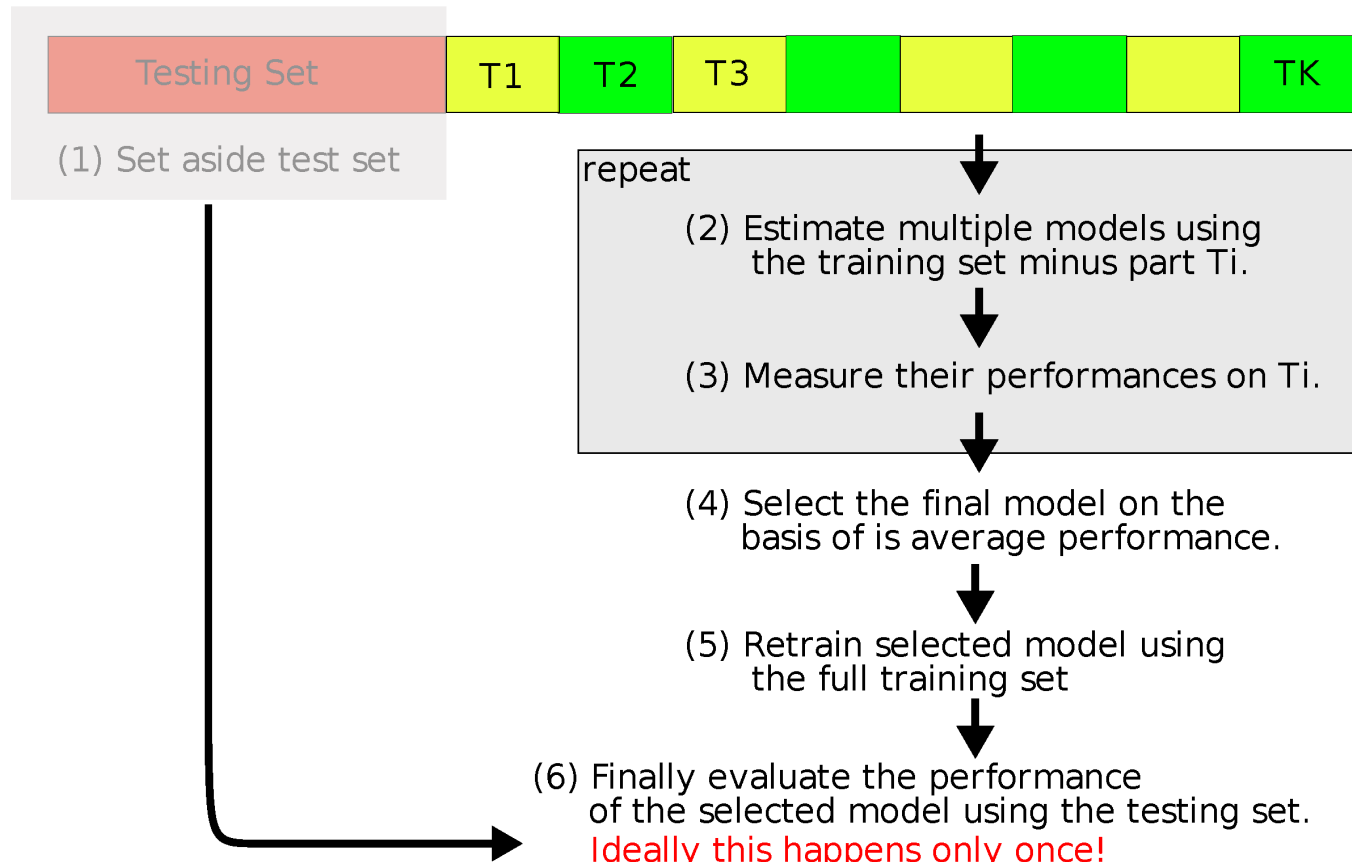
What is the optimal size of the testing set ?

- Large enough to measure the performance with sufficient accuracy.

What is the optimal size of the validation set ?

- Large enough to justify our model selection, but not larger !
- Depends on the number of models to compare.
- Depends on the data needs of the models we compare.
- Depends on the total size of the data set.
- Trial and errors. . .

K-fold cross validation



Potential problems

All this consumes valuable computing time!

- This is a serious problem when examples are abundant.

How accurate is k-fold cross-validation?

- More than using a single partition as validation set.
- Less than using a validation set as large as the training set.
- The statistical properties of the procedure are **unclear**.

Suggestions

- Avoid k-fold cross validation for very large datasets.
- Observe the variations of measured performances on the folds.

Subtleties

- Evaluating the performance of a trained model.
- Evaluation the performance of a training procedure.

Beyond Curve Fitting

$$x \longrightarrow \Phi(x) = \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \dots \\ \phi_n(x) \end{bmatrix} \longrightarrow f(x) = [w_0, w_1, \dots, w_n] \times \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \dots \\ \phi_n(x) \end{bmatrix}$$

Given suitable basis functions Φ , the inputs x could be anything.

- numerical variables, e.g. **3.1415**
- categorical variables, e.g. **blue, green, yellow, ...**
- ordered variables, e.g. **small, medium, large**.
- complex data structures, such as trees, graphs, etc.
- any combination of the above.

This does not mean that constructing the features $\phi_i(x)$ will be easy.

The “adult” dataset

Predict whether income exceeds \$50K/year ($y = +1$) or not ($y = -1$).

<http://archive.ics.uci.edu/ml/datasets/Adult>

Input variables

- 6 continuous variables :
 - age, years of education, hours-per-week, capital-gains, capital-losses, fnlwgt(?).
- 8 categorical variables :
 - workclass, education, marital status, sex, occupation, race, relationship, native country.

Training and testing sets

- Training set: 32561 examples
- Testing set: 16281 examples

Creating $\Phi(\mathbf{x})$ for the adult dataset

Coding on 1+123 binary features $\phi_i(\mathbf{x})$

- First feature is always $\phi_1(\mathbf{x}) = 1$.
- One feature for each possible value of each categorical variable.
- Five features for each continuous variable (quantified on 5 quantiles).

copied from (Platt, 1998)

Split

- 28000 training + 4562 validation examples.
- 16281 testing examples.

Results

Experiment	Misclassification
Validation set (after training on 28K)	15.98 %
Testing set (after training on 32K)	15.47 %

A quadratic basis for the adult dataset

Coding on 1+123+7503 features

- Additional features for quadratic models.

$$\forall i \in 1 \dots 123 \quad \forall j \in 1 \dots i - 1 \quad \phi_{ij}(x) = \phi_i(x)\phi_j(x)$$

Remarks

- Feature count grows quickly.
- This is slow (X is sparse, but $X^\top X$ is not.)

Results

Experiment	Misclassification
Validation set (after training on 28K)	16.40 %
Testing set (after training on 32K)	— %

Weighting the quadratic terms

Idea

Remember the regularization + cholevsky trick?

$$\min C(w) + \varepsilon w^2 \iff (X^\top X + \varepsilon I) w = (X^\top Y)$$

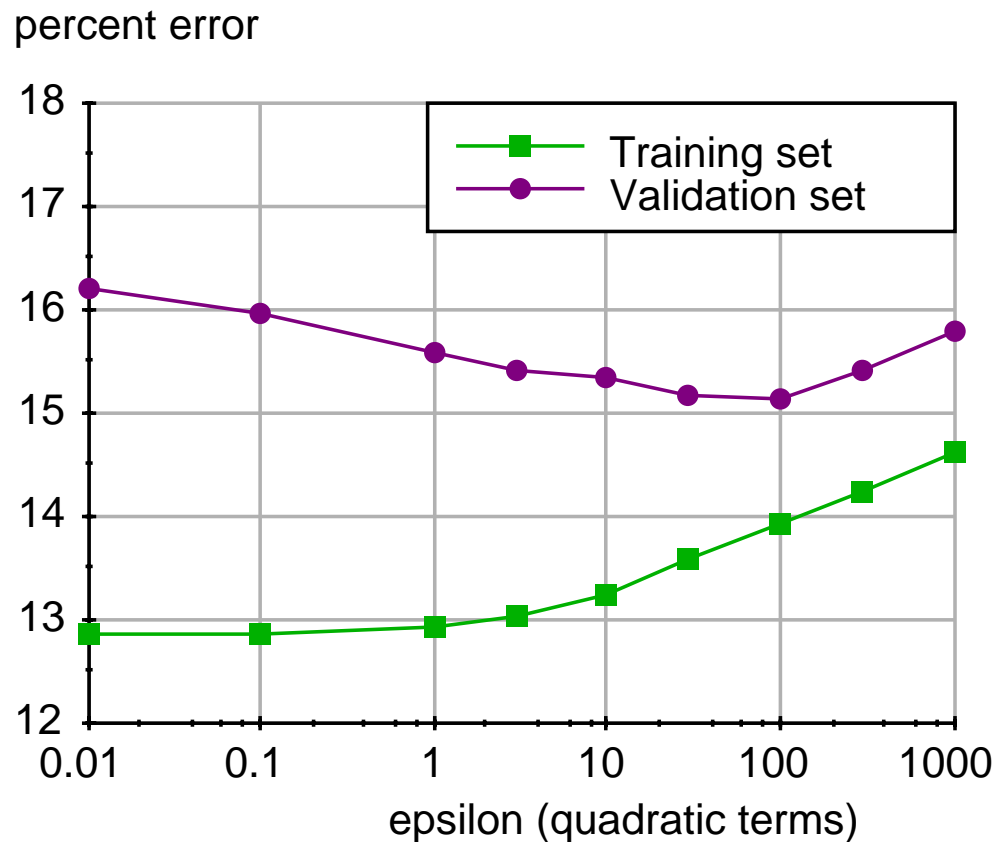
Let's penalize more the coefficients of the quadratic terms.

$$\min C(w) + w^\top \Lambda w \iff (X^\top X + \Lambda) w = (X^\top Y)$$

Details

- $\varepsilon = 10^{-5}$ for constant and linear terms.
- $\varepsilon \in [10^{-5}, 10^5]$ for quadratic terms.

Weighting the quadratic terms



We get the **linear result** when $\varepsilon \rightarrow \infty$.

We get the **quadratic result** when $\varepsilon \rightarrow 0$.

After retraining with $\varepsilon = 100$ on all 32K examples:

Testing set error: 14.93 %.

Coming next

Homework 1

- Due on Tue Feb 23rd.
- Something about splines.

Next lectures

- Tuesday Feb 9th: R tutorial (Sean Gerrish)
- Thursday Feb 11th: Review of probabilities