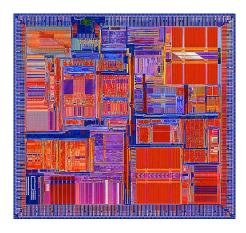
# Let's build a computer!

# Designing a CPU



 $\textbf{Introduction to Computer Science} \quad \textbf{Robert Sedgewick and Kevin Wayne} \quad \textbf{Copyright @ 2008} \quad \textbf{http://www.cs.Princeton.EDU/IntroCS}$ 

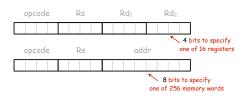
#### TOY Lite

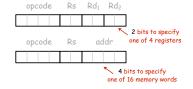
#### TOY machine.

- 256 16-bit words of memory.
- 16 16-bit registers.
- 1 8-bit program counter.
- 2 instruction types
- 16 instructions.

#### TOY-Lite machine.

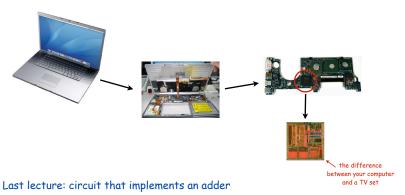
- 16 10-bit words of memory.
- 4 10-bit registers.
- 1 4-bit program counter.
- 2 instruction types
- 16 instructions.





CPU: "central processing unit"

computer: CPU + display + optical disk + metal case + power supply + ...



This lecture: circuit that implements a CPU

Primary Components of Toy-Lite CPU

Arithmetic and Logic Unit (ALU)

Memory

Toy-Lite Registers

Processor Registers: Program Counter and Instruction Register

"Control"

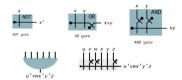
Goal: CPU circuit for TOY-Lite (same design extends to TOY, your computer)

# Review of Combinational Circuits

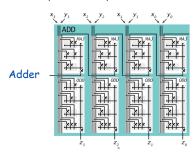
# Controlled switch.

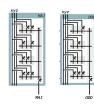


Gates.



# Sum-of products implementation of Boolean functions



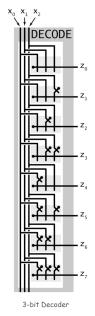


#### Decoder

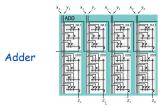
#### Decoder. [n-bit]

- n address inputs, 2<sup>n</sup> data outputs.
- Addressed output bit is 1; others are 0.
- Implements n Boolean functions

<b>x</b> <sub>0</sub>	<b>x</b> <sub>1</sub>	<b>x</b> <sub>2</sub>	z <sub>0</sub>	<b>z</b> 1	<b>z</b> <sub>2</sub>	<b>z</b> <sub>3</sub>	z <sub>4</sub>	<b>z</b> <sub>5</sub>	<b>z</b> <sub>6</sub>	<b>z</b> <sub>7</sub>
0	0	0	1	0	0	0	0	0	0	0
0	0	1	0	1	0	0	0	0	0	0
0	1	0	0	0	1	0	0	0	0	0
0	1	1	0	0	0	1	0	0	0	0
1	0	0	0	0	0	0	1	0	0	0
1	0	1	0	0	0	0	0	1	0	0
1	1	0	0	0	0	0	0	0	1	0
1	1	1	0	0	0	0	0	0	0	1



# Useful Combinational Circuits



Incrementer (easy, add 0001)



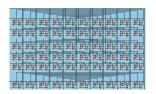
Bitwise AND, XOR (easy)



Decoder

Shifter (clever, but we'll skip details)

Multiplexer



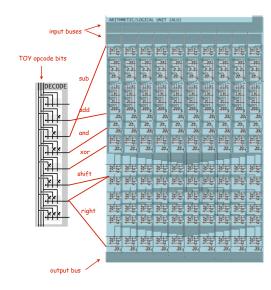
# Decoder application: ALU!

#### TOY arithmetic

- 1: add
- 2: subtract
- 3: and
- 4: xor
- 5: shift left
- 6: shift right

#### Details:

- All circuits compute their result.
- Decoder lines AND all results.
- "one-hot" OR collects answer.



# Primary Components of Toy-Lite CPU

# ✓ Arithmetic and Logic Unit (ALU)

Memory

Toy-Lite Registers

Processor Registers: Program Counter and Instruction Register

"Control"

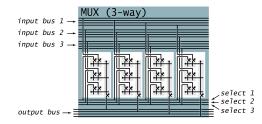
Nuts and Bolts: Buses and Multiplexers

Bus. Parallel wires connecting major component.

- Ex. Carry register bits to ALU.
- Ex. Carry register bits to memory

Multiplexer (MUX). Combinational circuit that selects among input buses.

- Exactly one select line i is activated.
- Copies bits from input bus i to output bus.



CPU is a circuit: everything is "connected" but wires that can be "on" can be selected by other wires.

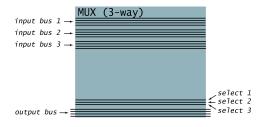
# Nuts and Bolts: Buses and Multiplexers

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CPU is a circuit: everything is "connected" but wires that can be "on" can be selected by other wires.

# A New Ingredient: Circuits With Memory

#### Combinational circuits.

- Output determined solely by inputs.
- Ex: majority, adder, decoder, MUX, ALU.

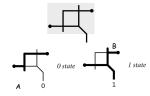
# xyz x x y + xz + yz Ma1

#### Sequential circuits.

- Output determined by inputs and current "state".
- Ex: memory, program counter, CPU.

# Ex. Simplest feedback loop.

- Two controlled switches A and B, both connected to power, each blocked by the other.
- State determined by whichever switches first.
- Stable.



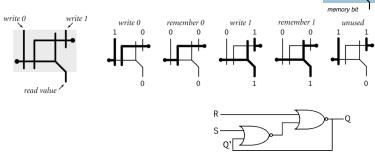
Aside. Feedback with an odd number of switches is a buzzer (not stable).

Doorbell: buzzer made with relays.

# SR Flip-Flop

# SR Flip-flop.

- Two cross-coupled NOR gates
- A way to control the feedback loop.
- Abstraction that "remembers" one bit.
- Basic building block for memory and registers.



Caveat. Timing, switching delay.

NOR gate

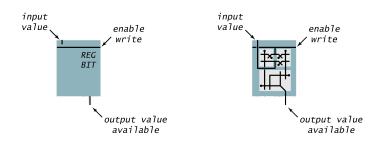
13

15

write 0

# Processor register Bit

Processor register bit. Extend a flip-flop to allow easy access to values.



# Memory Overview

# Computers and TOY have several memory components.

- Program counter and other processor registers.
- TOY registers (4 10-bit words in Toy-Lite).
- Main memory (16 10-bit words in Toy-Lite).

# memory bit write 0 write 1

#### Implementation.

- Use one flip-flop for each bit of memory.
- Use buses and multiplexers to group bits into words.

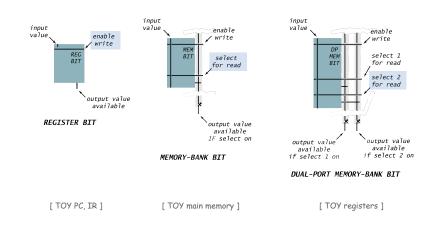
#### Access mechanism: when are contents available?

- Processor registers: enable write.
- Main memory: select and enable write.
- TOY register: dual select and enable write

need to be able to read two registers at once

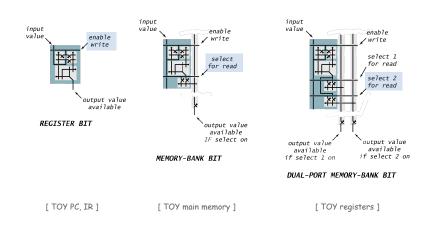
# Memory Bit Interface

Memory and TOY register bits: Add selection mechanism.



# Memory Bit: Switch Level Implementation

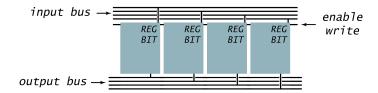
# Memory and TOY register bits: Add selection mechanism.



# Processor Register

Processor register. — don't confuse with TOY register

- · Stores k bits.
- Register contents always available on output bus.
- If enable write is asserted, k input bits get copied into register.
- Ex 1. TOY program counter (PC) holds 8-bit address.
- Ex 2. TOY instruction register (IR) holds 16-bit current instruction.



# Processor Register

Processor register. ← don't confuse with TOY register

- · Stores k bits.
- Register contents always available on output bus.
- If enable write is asserted, k input bits get copied into register.

Ex 1. TOY-Lite program counter (PC) holds 4-bit address.

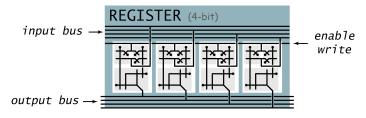
Ex 2. TOY-Lite instruction register (IR) holds 10-bit current instruction.



# Processor Register

Processor register. — don't confuse with TOY register

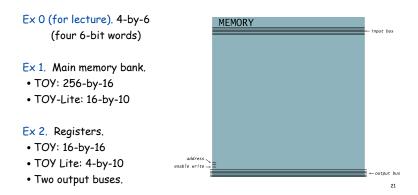
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- Ex 2. TOY instruction register (IR) holds 16-bit current instruction.



Memory Bank Memory: Interface

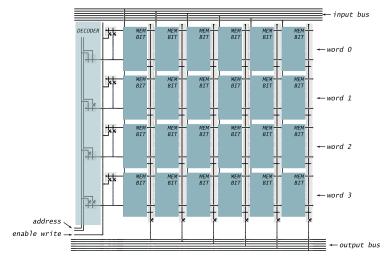
# Memory bank.

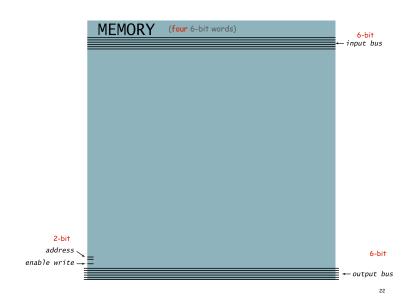
- Bank of n registers; each stores k bits.
- Read and write information to one of n registers.
- Address inputs specify which one. \_\_\_\_\_ log\_n address bits needed
- Addressed bits always appear on output.
- If write enabled, k input bits are copied into addressed register.



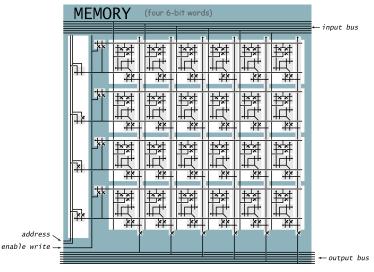
Memory: Component Level Implementation

Decoder plus memory selection: connect only to addressed word.





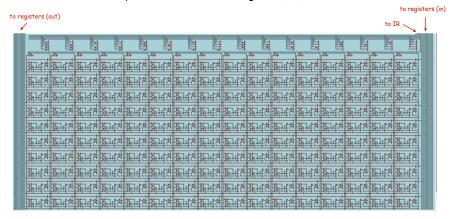
Memory: Switch Level Implementation



# TOY-Lite Memory

#### 16 10-bit words

- input connected to registers for "store"
- output connected to registers for "load"
- addr connect to processor Instruction Register (IR)



Primary Components of Toy-Lite CPU

- ✓ ALU
- ✓ Memory
- ✓ Registers
- ✓ Processor Registers: Program Counter and Instruction Register

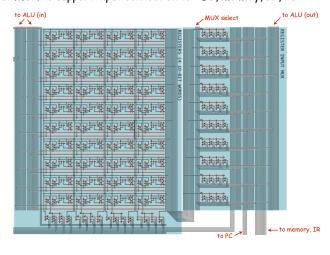
Not quite done.

"Control"

# Toy-Lite Registers

#### 4 10-bit words

- Dual-ported to support connecting two different registers to ALU
- Input MUX to support input connection to ALU, memory, IR, PC



How To Design a Digital Device

#### How to design a digital device.

- Design interface: input buses, output buses, control wires.
- Determine components.
- Determine datapath requirements: "flow" of bits.
- Establish control sequence.

Warmup. Design a program counter (3 devices, 3 control wires).

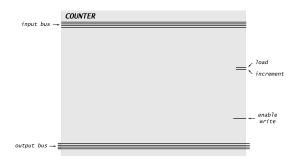
Goal. Design TOY-Lite computer (10 devices, 27 control wires).

# Program Counter: Interface

Counter. Holds value that represents a binary number.

- Load: set value from input bus.
- Increment: add one to value.
- Enable Write: make value available on output bus.

Ex. TOY-Lite program counter (4-bit).



Program Counter: Datapath and Control

#### Datapath.

- Layout and interconnection of components.
- Connect input and output buses.

Control. Choreographs the "flow" of information on the datapath.

Program Counter: Components

# Components.

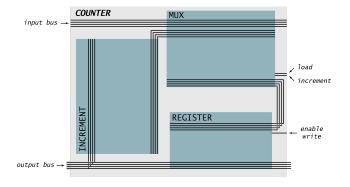
- Register.
- Incrementer.
- Multiplexer (to provide connections for both load and increment).

Program Counter: Datapath and Control

#### Datapath.

- Layout and interconnection of components.
- Connect input and output buses.

Control. Choreographs the "flow" of information on the datapath.



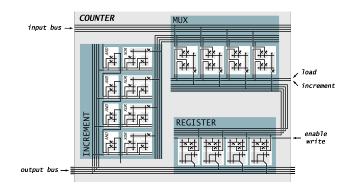
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# Program Counter: Datapath and Control

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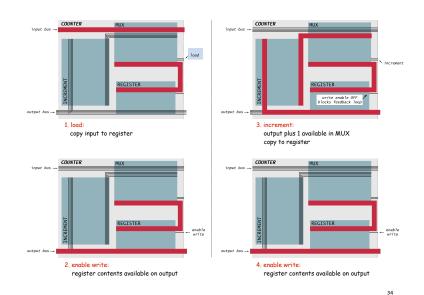
33

# Primary Components of Toy-Lite CPU

- ✓ ALU
- ✓ Memory
- ✓ Toy-Lite Registers
- ✓ Processor Registers: Program Counter and Instruction Register

"Control"

# Program Counter: Datapath and Control



How To Design a Digital Device

#### How to design a digital device.

- Design interface: input buses, output buses, control wires.
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- Establish control sequence.

Warmup. Design a program counter (3 devices, 3 control wires).

Next. Design TOY-Lite computer (10 devices, 27 control wires).

TOY-Lite: Interface TOY-Lite: Components

#### CPU is a circuit.

# Interface: switches and lights.

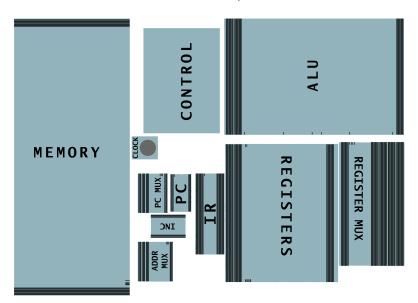
- set memory contents
- set PC value
- press RUN
- [details of connection to circuit omitted]





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TOY-Lite: Layout



# TOY-Lite Datapath Requirements: Fetch

# Basic machine operation is a cycle.

- Fetch
- Execute

# Fetch.

- Memory[PC] to IR
- Increment PC

# Execute.

• Datapath depends on instruction

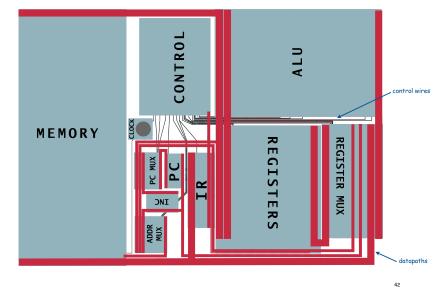


# TOY-Lite Datapath Requirements: Execute

Instructions determine datapaths and control sequences for execute

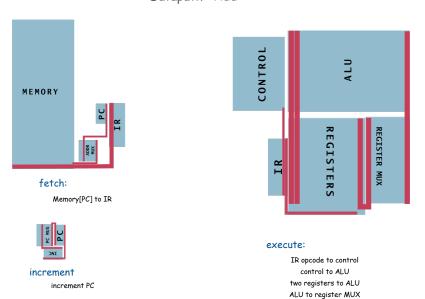
0	halt					
1	add					
2	subtract	IR opcode to control				
3	and	control to ALU two registers to ALU				
4	xor					
5	shift left	ALU to register MUX				
6	shift right					
7	load address					
8	load					
9	store					
Α	load indirect					
В	store indirect					
С	branch zero					
D	branch positive					
Ε	jump register					
F	jump and link					

TOY-Lite: Datapaths and Control



Datapath: Load

Datapath: Add



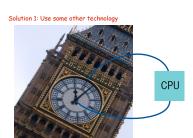
CONTROL MEMORY MEMORY REGISTERS fetch: Memory[PC] to IR execute: IR opcode to control IR to addr MUX increment memory to register MUX increment PC

Last step

Clock

Control. Each instruction corresponds to a sequence of control signals.

- Q. How do we create the sequence?
- A. Need a "physical" clock.



Solution 2: Use a buzzer [need sufficiently long cycle to cover CPU switching] **CPU** 

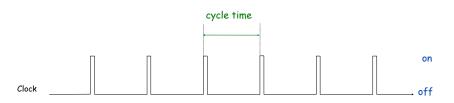
Clock.

• Fundamental abstraction: regular on-off pulse.

-on: fetch phase -off: execute phase

- "external" device.
- Synchronizes operations of different circuit elements.
- Requirement: clock cycle longer than max switching time.

Solution 32 Fetch Execute



How much does it Hert?

#### Frequency is inverse of cycle time.

- Expressed in hertz.
- Frequency of 1 Hz means that there is 1 cycle per second.
  - -1 kilohertz (kHz) means 1000 cycles/sec.
  - -1 megahertz (MHz) means 1 million cycles/sec.
  - -1 gigahertz (GHz) means 1 billion cycles/sec.
  - -1 terahertz (THz) means 1 trillion cycles/sec.

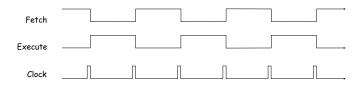
Heinrich Rudolf Hertz (1857-1894)

# Clocking Methodology

#### Two-cycle design.

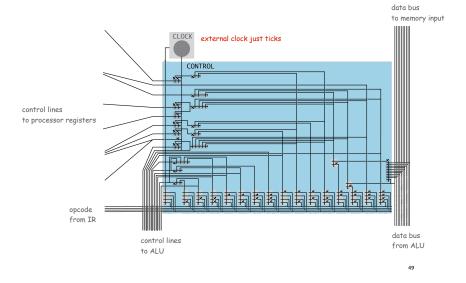
• Each control signal is in one of four epochs.

-fetch [set memory address from pc] - fetch and clock [write instruction to IR] [set ALU inputs from registers] - execute - execute and clock [write result of ALU to registers]



Control Tick-Tock

# Control. Circuit that determines control line sequencing.



CPU is a circuit, driven by a clock.

Switches initialize memory, PC contents

#### Clock ticks

- fetch instruction from memory[PC] to IR
- increment PC
- execute instruction

[details of instruction execution differ]

- fetch next instruction
- ..

That's all there is to it!





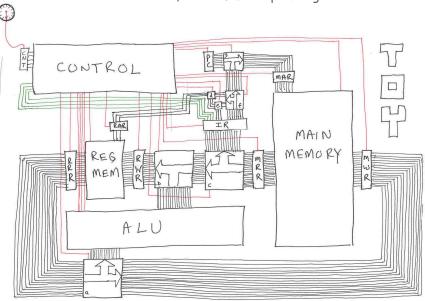




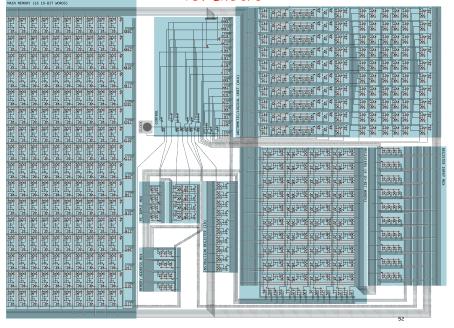


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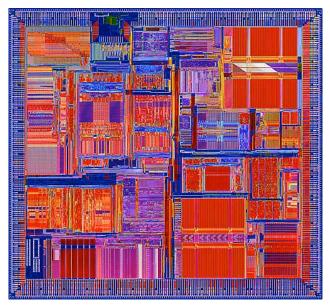
# TOY "Classic", Back Of Envelope Design



# TOY-Lite CPU



# Real Microprocessor (MIPS R10000)



# Layers of Abstraction

Abstraction	Built From	Examples		
Abstract Switch	raw materials	transistor, relay		
Connector	raw materials	wire		
Clock	raw materials	crystal oscillator		
Logic Gates	abstract switches, connectors	AND, OR, NOT		
Combinational Circuit	logic gates, connectors	decoder, multiplexer, adder, ALU		
Sequential Circuit	logic gates, clock, connector	flip-flop		
Components	decoder, multiplexer, adder, flip-flop	registers, ALU, counter, control		
Computer	components	ТОУ		

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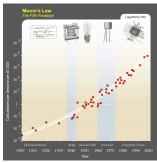
# History + Future

#### Computer constructed by layering abstractions.

- Better implementation at low levels improves everything.
- Ongoing search for better abstract switch!

#### History.

- 1820s: mechanical switches.
- 1940s: relays, vacuum tubes.
- 1950s: transistor, core memory.
- 1960s: integrated circuit.
- 1970s: microprocessor.
- 1980s: VLSI.
- 1990s: integrated systems.
- 2000s: web computer.
- Future: quantum, optical soliton, ...



Ray Kurzweil http://en.wikipedia.org/wiki/Image:PPTMooresLawai.jpg

#### Overview

#### What is COS 126?

Broad, but technical, intro to CS.
 No prerequisites, intended for novices.

#### Goals.

- Demystify computer systems.
- Empower you to exploit available technology.
- Build awareness of substantial intellectual underpinnings.

#### Topics.

- Programming in Java.
- Machine architecture.
- Theory of computation.
- Applications to science, engineering, and commercial computing.