

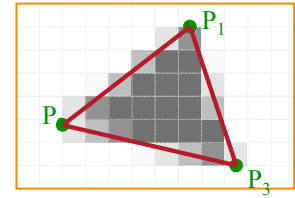
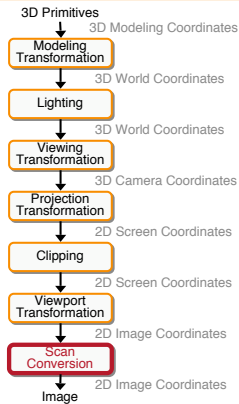


# Scan Conversion & Shading

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COS 426, Spring 2005



## 3D Rendering Pipeline (for direct illumination)



Scan Conversion & Shading



## Overview

- Scan conversion
  - Figure out which pixels to fill
- Shading
  - Determine a color for each filled pixel

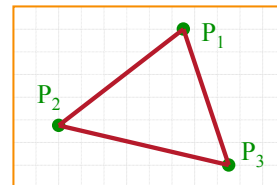


## Scan Conversion

- Render an image of a geometric primitive by setting pixel colors

```
void SetPixel(int x, int y, Color rgba)
```

- Example: Filling the inside of a triangle

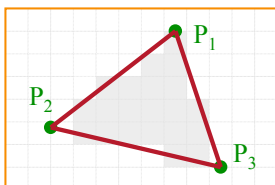


## Scan Conversion

- Render an image of a geometric primitive by setting pixel colors

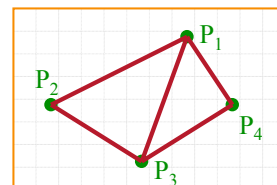
```
void SetPixel(int x, int y, Color rgba)
```

- Example: Filling the inside of a triangle



## Triangle Scan Conversion

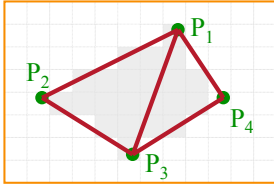
- Properties of a good algorithm
  - Symmetric
  - Straight edges
  - Antialiased edges
  - No cracks between adjacent primitives
  - MUST BE FAST!



## Triangle Scan Conversion



- Properties of a good algorithm
  - Symmetric
  - Straight edges
  - Antialiased edges
  - No cracks between adjacent primitives
  - MUST BE FAST!

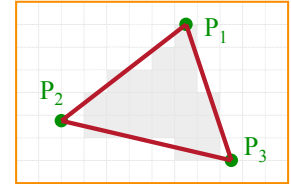


## Simple Algorithm



- Color all pixels inside triangle

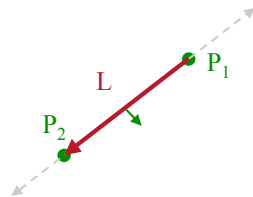
```
void ScanTriangle(Triangle T, Color rgba){
    for each pixel P at (x,y){
        if (Inside(T, P))
            SetPixel(x, y, rgba);
    }
}
```



## Line defines two halfspaces



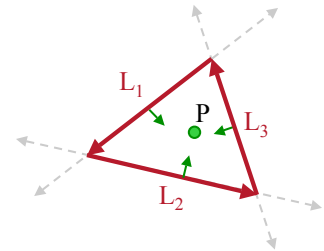
- Implicit equation for a line
  - On line:  $ax + by + c = 0$
  - On right:  $ax + by + c < 0$
  - On left:  $ax + by + c > 0$



## Inside Triangle Test



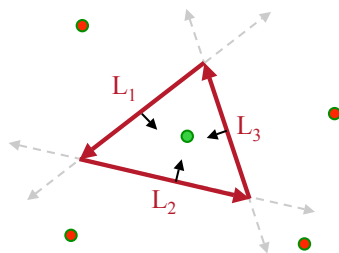
- A point is inside a triangle if it is in the positive halfspace of all three boundary lines
  - Triangle vertices are ordered counter-clockwise
  - Point must be on the left side of every boundary line



## Inside Triangle Test



```
Boolean Inside(Triangle T, Point P)
{
    for each boundary line L of T {
        Scalar d = L.a*P.x + L.b*P.y + L.c;
        if (d < 0.0) return FALSE;
    }
    return TRUE;
}
```

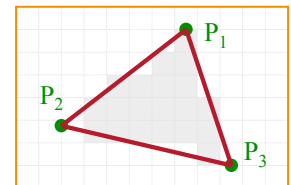


## Simple Algorithm



- What is bad about this algorithm?

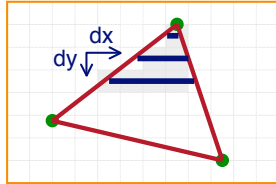
```
void ScanTriangle(Triangle T, Color rgba){
    for each pixel P at (x,y){
        if (Inside(T, P))
            SetPixel(x, y, rgba);
    }
}
```



## Triangle Sweep-Line Algorithm



- Take advantage of spatial coherence
  - Compute which pixels are inside using horizontal spans
  - Process horizontal spans in scan-line order
- Take advantage of edge linearity
  - Use edge slopes to update coordinates incrementally

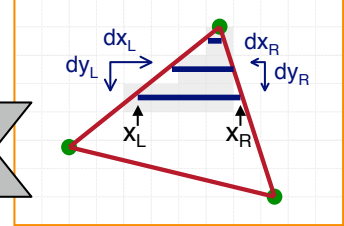


## Triangle Sweep-Line Algorithm



```
void ScanTriangle(Triangle T, Color rgba) {
    for each edge pair {
        initialize  $x_L, x_R$ ;
        compute  $dx_L/dy_L$  and  $dx_R/dy_R$ ;
        for each scanline at y
            for (int x =  $x_L$ ; x <=  $x_R$ ; x++)
                SetPixel(x, y, rgba);
             $x_L += dx_L/dy_L$ ;
             $x_R += dx_R/dy_R$ ;
    }
}
```

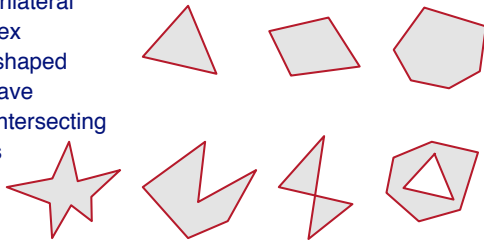
Bresenham's algorithm works the same way, but uses only integer operations!



## Polygon Scan Conversion



- Fill pixels inside a polygon
  - Triangle
  - Quadrilateral
  - Convex
  - Star-shaped
  - Concave
  - Self-intersecting
  - Holes

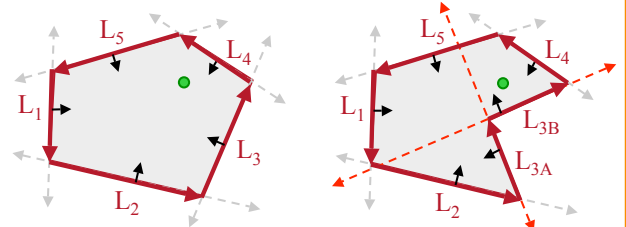


What problems do we encounter with arbitrary polygons?

## Polygon Scan Conversion



- Need better test for points inside polygon
  - Triangle method works only for convex polygons



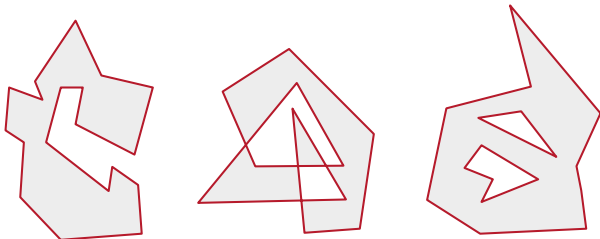
Convex Polygon

Concave Polygon

## Inside Polygon Rule



- What is a good rule for which pixels are inside?



Concave

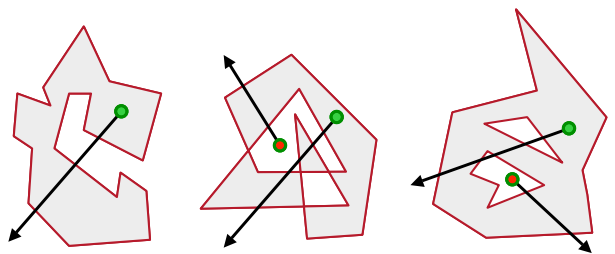
Self-Intersecting

With Holes

## Inside Polygon Rule



- Odd-parity rule
  - Any ray from P to infinity crosses odd number of edges



Concave

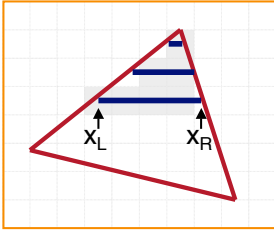
Self-Intersecting

With Holes

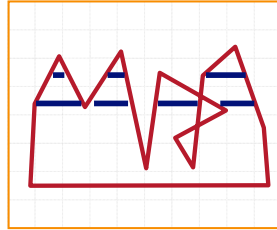
## Polygon Sweep-Line Algorithm



- Incremental algorithm to find spans, and determine insideness with odd parity rule
  - Takes advantage of scanline coherence



Triangle

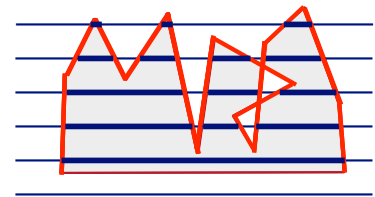


Polygon

## Polygon Sweep-Line Algorithm



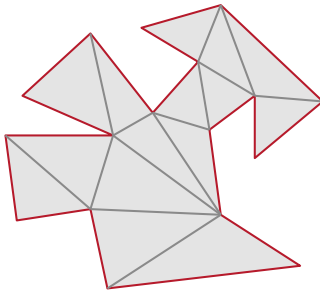
```
void ScanPolygon(Triangle T, Color rgba){
    sort edges by maxy
    make empty "active edge list"
    for each scanline (top-to-bottom) {
        insert/remove edges from "active edge list"
        update x coordinate of every active edge
        sort active edges by x coordinate
        for each pair of active edges (left-to-right)
            SetPixels(xi, xi+1, y, rgba);
    }
}
```



## Hardware Scan Conversion



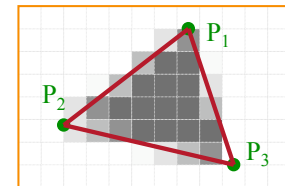
- Convert everything into triangles
  - Scan convert the triangles



## Hardware Antialiasing



- Supersample pixels
  - Multiple samples per pixel
  - Average subpixel intensities (box filter)
  - Trades intensity resolution for spatial resolution



## Overview



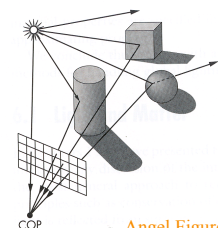
- Scan conversion
  - Figure out which pixels to fill
- Shading
  - Determine a color for each filled pixel

## Shading



- How do we choose a color for each filled pixel?
  - Each illumination calculation for a ray from the eyepoint through the view plane provides a radiance sample
    - How do we choose where to place samples?
    - How do we filter samples to reconstruct image?

Emphasis on methods that can be implemented in hardware

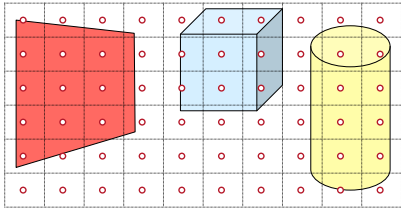




## Ray Casting



- Simplest shading approach is to perform independent lighting calculation for every pixel
  - When is this unnecessary?

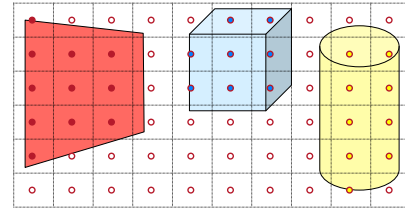


$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

## Polygon Shading



- Can take advantage of spatial coherence
  - Illumination calculations for pixels covered by same primitive are related to each other



$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

## Polygon Shading Algorithms



- Flat Shading
- Gouraud Shading
- Phong Shading

## Polygon Shading Algorithms

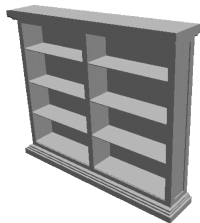


- **Flat Shading**
- Gouraud Shading
- Phong Shading

## Flat Shading



- What if a faceted object is illuminated only by directional light sources and is either diffuse or viewed from infinitely far away

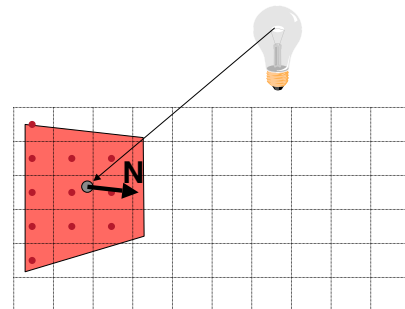


$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

## Flat Shading



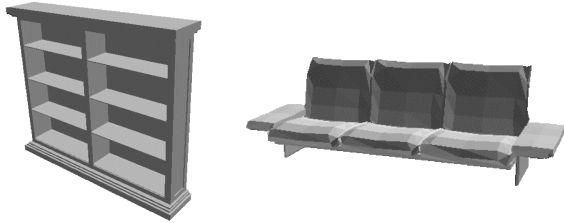
- One illumination calculation per polygon
  - Assign all pixels inside each polygon the same color



## Flat Shading



- Objects look like they are composed of polygons
  - OK for polyhedral objects
  - Not so good for smooth surfaces



## Polygon Shading Algorithms

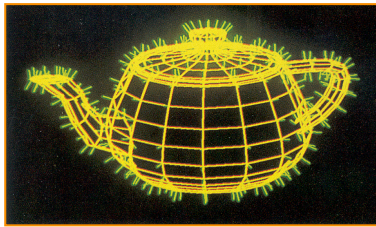


- Flat Shading
- **Gouraud Shading**
- Phong Shading

## Gouraud Shading



- What if smooth surface is represented by polygonal mesh with a normal at each vertex?



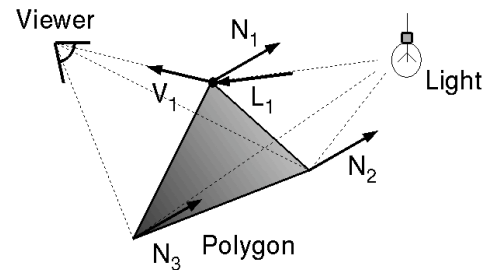
Watt Plate 7

$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

## Gouraud Shading



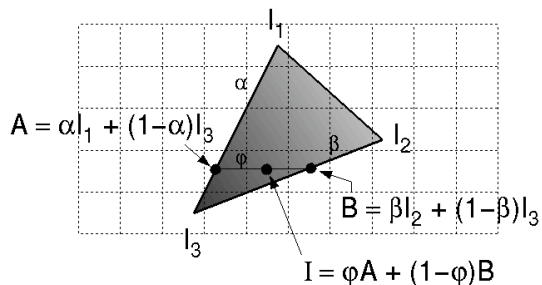
- Method 1: One lighting calculation per vertex
  - Assign pixels inside polygon by interpolating colors computed at vertices



## Gouraud Shading



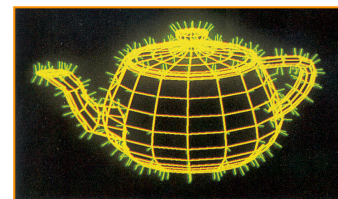
- Bilinearly interpolate colors at vertices down and across scan lines



## Gouraud Shading



- Smooth shading over adjacent polygons
  - Curved surfaces
  - Illumination highlights
  - Soft shadows

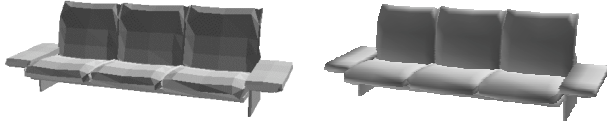


Mesh with shared normals at vertices

## Gouraud Shading



- Produces smoothly shaded polygonal mesh
  - Piecewise linear approximation
  - Need fine mesh to capture subtle lighting effects



Flat Shading

Gouraud Shading

## Polygon Shading Algorithms

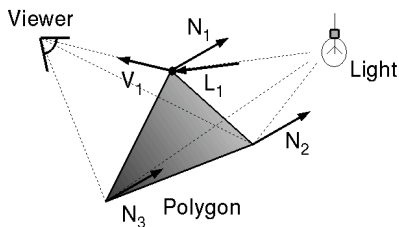


- Flat Shading
- Gouraud Shading
- **Phong Shading**

## Phong Shading



- What if polygonal mesh is too coarse to capture illumination effects in polygon interiors?

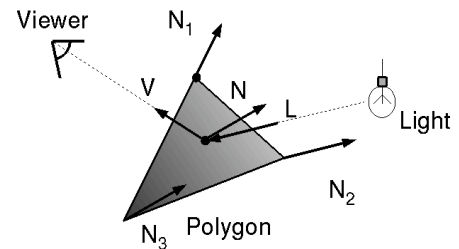


$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

## Phong Shading



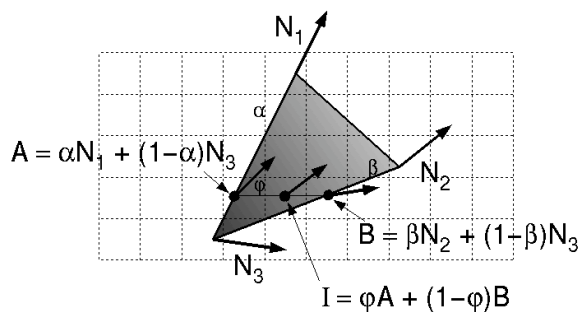
- One lighting calculation per pixel
  - Approximate surface normals for points inside polygons by bilinear interpolation of normals from vertices



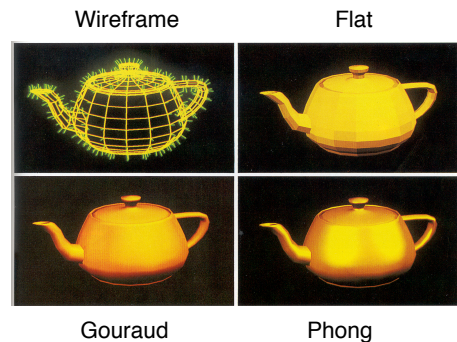
## Phong Shading



- Bilinearly interpolate surface normals at vertices down and across scan lines



## Polygon Shading Algorithms



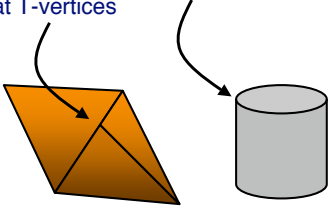
Gouraud

Phong

## Shading Issues



- Problems with interpolated shading:
  - Polygonal silhouettes
  - Perspective distortion
  - Orientation dependence (due to bilinear interpolation)
  - Problems computing shared vertex normals
  - Problems at T-vertices



## Summary



- 2D polygon scan conversion
    - Paint pixels inside primitive
    - Sweep-line algorithm for polygons
  - Polygon Shading Algorithms
    - Flat
    - Gouraud
    - Phong
    - Ray casting
  - Key ideas:
    - Sampling and reconstruction
    - Spatial coherence
- ↑ Less expensive  
↓ More accurate