7. Network Flow

Algorithm Design by Éva Tardos and Jon Kleinberg · Copyright © 2005 Addison Wesley · Slides by Kevin Wayne

Maximum Flow and Minimum Cut

Max flow and min cut.

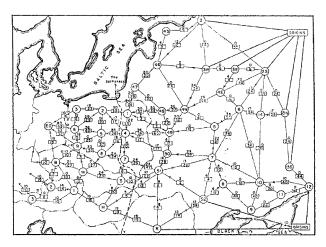
- Two very rich algorithmic problems.
- Cornerstone problems in combinatorial optimization.
- Beautiful mathematical duality.

Nontrivial applications / reductions.

- Data mining.
- Open-pit mining.
- Project selection.
- · Airline scheduling.
- Bipartite matching.
- Baseball elimination.
- Image segmentation.
- Network connectivity.

- Network reliability.
- Distributed computing.
- Egalitarian stable matching.
- Security of statistical data.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Many many more . . .

Soviet Rail Network, 1955

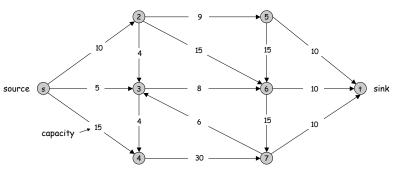


Reference: On the history of the transportation and maximum flow problems. Alexander Schrijver in Math Programming, 91: 3, 2002.

Minimum Cut Problem

Flow network.

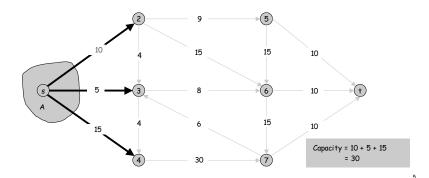
- Abstraction for material flowing through the edges.
- G = (V, E) = directed graph, no parallel edges.
- Two distinguished nodes: s = source, t = sink.
- c(e) = capacity of edge e.



Cuts

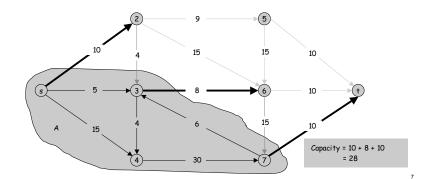
Def. An s-t cut is a partition (A, B) of V with $s \in A$ and $t \in B$.

Def. The capacity of a cut (A, B) is: $cap(A, B) = \sum_{e \text{ out of } A} c(e)$



Minimum Cut Problem

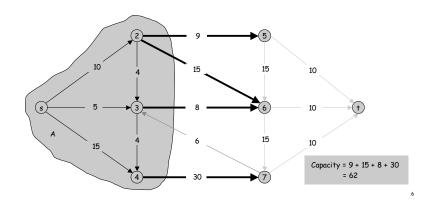
Min s-t cut: find an s-t cut of minimum capacity.



Cuts

Def. An s-t cut is a partition (A, B) of V with $s \in A$ and $t \in B$.

Def. The capacity of a cut (A, B) is: $cap(A, B) = \sum_{e \text{ out of } A} c(e)$

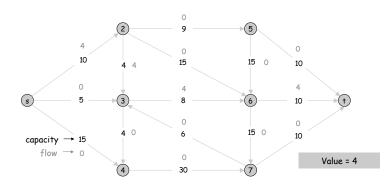


Flows

Def. An s-t flow is a function that satisfies:

• For each $e \in E$: $0 \le f(e) \le c(e)$ (capacity) • For each $v \in V - \{s, t\}$: $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$ (conservation)

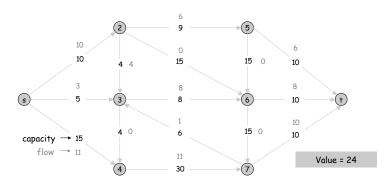
Def. The value of a flow f is: $v(f) = \sum_{e \text{ out of } s} f(e)$.



Def. An s-t flow is a function that satisfies:

 $\begin{array}{ll} \bullet & \text{For each } e \in \mathsf{E} : & 0 \leq f(e) \leq c(e) & \text{(capacity)} \\ \bullet & \text{For each } \mathsf{v} \in \mathsf{V} - \{\mathsf{s},\,\mathsf{t}\} : & \sum\limits_{e \text{ in to } v} f(e) & = \sum\limits_{e \text{ out of } v} f(e) & \text{(conservation)} \end{array}$

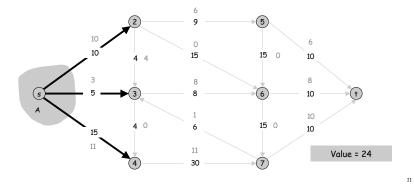
Def. The value of a flow f is: $v(f) = \sum_{e \text{ out of } s} f(e)$.



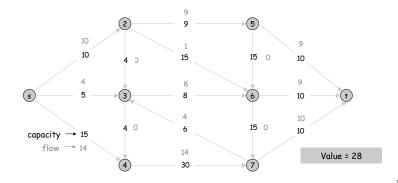
Flows and Cuts

Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to A}} f(e) = v(f)$$



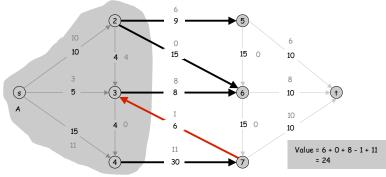
Max flow problem: find s-t flow of maximum value.



Flows and Cuts

Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

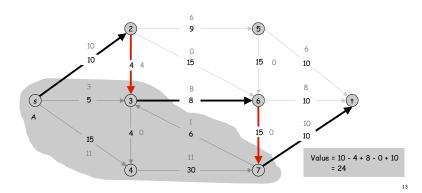
$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to A}} f(e) = v(f)$$



Flows and Cuts

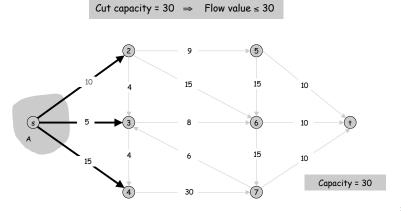
Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to A}} f(e) = v(f)$$



Flows and Cuts

Weak duality. Let f be any flow, and let (A, B) be any s-t cut. Then the value of the flow is at most the capacity of the cut.



Flows and Cuts

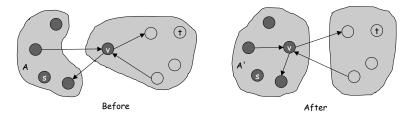
Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f).$$

Pf. (by induction on |A|)

■ Base case: $A = \{ s \}$.

- Inductive hypothesis: assume true for all cuts (A, B) with |A| < k.
 - consider cut (A', B') with |A'| = k
 - $A' = A \cup \{v\}$ for some $v \neq \{s, t\}$
 - By induction, cap(A, B) = v(f).
 - adding v to A increase cut capacity by $\sum\limits_{e \text{ out of } \nu} f(e) \sum\limits_{e \text{ in to } \nu} f(e) = 0$



Flows and Cuts

Weak duality. Let f be any flow. Then, for any s-t cut (A, B) we have $v(f) \le cap(A, B)$.

Pf.

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$

$$\leq \sum_{e \text{ out of } A} f(e)$$

$$\leq \sum_{e \text{ out of } A} c(e)$$

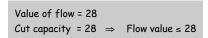
$$\leq \sum_{e \text{ out of } A} c(e)$$

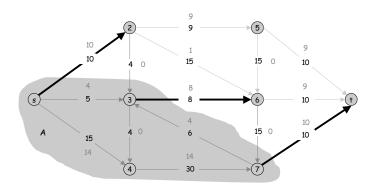
$$\leq cap(A, B)$$

15

Certificate of Optimality

Corollary. Let f be any flow, and let (A, B) be any cut. If v(f) = cap(A, B), then f is a max flow and (A, B) is a min cut.

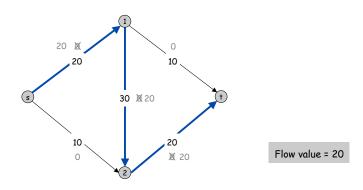




Towards a Max Flow Algorithm

Greedy algorithm.

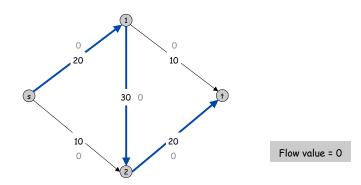
- Start with f(e) = 0 for all edge $e \in E$.
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.



Towards a Max Flow Algorithm

Greedy algorithm.

- Start with f(e) = 0 for all edge $e \in E$.
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.



Towards a Max Flow Algorithm

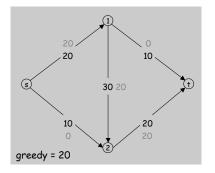
Greedy algorithm.

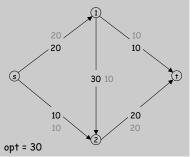
17

19

- Start with f(e) = 0 for all edge $e \in E$.
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.

locally optimality \Rightarrow global optimality



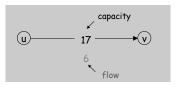


18

Residual Graph

Original edge: $e = (u, v) \in E$.

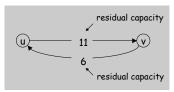
Flow f(e), capacity c(e).



Residual edge.

- "Undo" flow sent.
- e = (u, v) and $e^R = (v, u)$.
- Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$



Residual graph: $G_f = (V, E_f)$.

- Residual edges with positive residual capacity.
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : c(e) > 0\}.$

Max-Flow Min-Cut Theorem

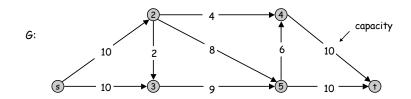
Augmenting path theorem. Flow f is a max flow iff there are no augmenting paths.

Max-flow min-cut theorem. [Ford-Fulkerson, 1956] The value of the max flow is equal to the value of the min cut.

Proof strategy. We prove both simultaneously by showing the TFAE:

- (i) There exists a cut (A, B) such that v(f) = cap(A, B).
- (ii) Flow f is a max flow.
- (iii) There is no augmenting path relative to f.
- (i) \Rightarrow (ii) This was the corollary to weak duality lemma.
- (ii) \Rightarrow (iii) We show contrapositive.
- Let f be a flow. If there exists an augmenting path, then we can improve f by sending flow along path.

Ford-Fulkerson Algorithm



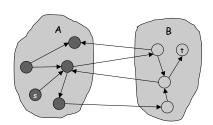


Proof of Max-Flow Min-Cut Theorem

$(iii) \Rightarrow (i)$

- Let f be a flow with no augmenting paths.
- Let A be set of vertices reachable from s in residual graph.
- By definition of $A, s \in A$.
- By definition of f, $t \notin A$.

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$
$$= \sum_{e \text{ out of } A} c(e)$$
$$= cap(A, B) \quad \blacksquare$$



original network

Augmenting Path Algorithm

```
Augment(f, c, P) {
  b ← bottleneck(P)
  foreach e ∈ P {
    if (e ∈ E) f(e) ← f(e) + b forward edge
    else f(e<sup>R</sup>) ← f(e) - b
  return f
}
```

```
Ford-Fulkerson(G, s, t, c) { foreach \ e \in E \ f(e) \leftarrow 0 G_f \leftarrow residual \ graph while (there exists augmenting path P) { f \leftarrow Augment(f, c, P) update \ G_f } return \ f}
```

7.3 Choosing Good Augmenting Paths

Running Time

Assumption. All capacities are integers between 1 and C.

Invariant. Every flow value f(e) and every residual capacities $c_f(e)$ remains an integer throughout the algorithm.

Theorem. The algorithm terminates in at most $v(f^*) \le nC$ iterations. Pf. Each augmentation increase value by at least 1.

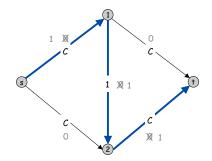
Corollary. If C = 1, Ford-Fulkerson runs in O(mn) time.

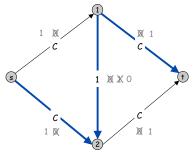
Integrality theorem. If all capacities are integers, then there exists a max flow f for which every flow value f(e) is an integer.

Pf. Since algorithm terminates, theorem follows from invariant.

Ford-Fulkerson: Exponential Number of Augmentations

- Q. Is generic Ford-Fulkerson algorithm polynomial in input size? $m_{n,n,and \log c}$
- A. No. If max capacity is C, then algorithm can take C iterations.





Choosing Good Augmenting Paths

Use care when selecting augmenting paths.

- Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- If capacities are irrational, algorithm not guaranteed to terminate!

Goal: choose augmenting paths so that:

- Can find augmenting paths efficiently.
- Few iterations.

Choose augmenting paths with: [Edmonds-Karp, 1972]

- Max bottleneck capacity.
- Sufficiently large bottleneck capacity.
- Fewest number of edges.

Capacity Scaling

```
Scaling-Max-Flow(G, s, t, c) {
    foreach e \in E f(e) \leftarrow 0
    \Delta \leftarrow smallest power of 2 greater than or equal to C
    G_f \leftarrow residual graph

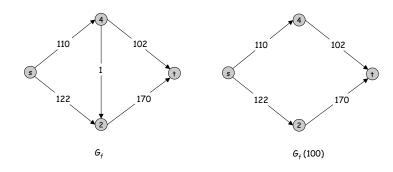
while (\Delta \ge 1) {
    G_f(\Delta) \leftarrow \Delta-residual graph
    while (there exists augmenting path P in G_f(\Delta)) {
        f \leftarrow augment(f, c, P)
        update G_f(\Delta)
    }
    \Delta \leftarrow \Delta / 2
}

return f
```

Capacity Scaling

Intuition. Choosing path with highest bottleneck capacity increases flow by max possible amount.

- Don't worry about finding exact highest bottleneck path.
- Maintain scaling parameter Δ .
- Let $G_f(\Delta)$ be the subgraph of the residual graph consisting of only arcs with capacity at least Δ .



Capacity Scaling: Correctness

Assumption. All edge capacities are integers between 1 and C.

Integrality invariant. All flow and residual capacity values are integral.

Correctness. If the algorithm terminates, then ${\bf f}$ is a max flow. Pf.

- By integrality invariant, when $\Delta = 1 \Rightarrow G_f(\Delta) = G_f$.
- Upon termination of Δ = 1 phase, there are no augmenting paths. ■

Capacity Scaling: Running Time

Lemma 1. The outer while loop repeats $1 + \lceil \log_2 C \rceil$ times. Pf. Initially $C \le \Delta < 2C$. Δ decreases by a factor of 2 each iteration.

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then the value of the maximum flow is at most $v(f) + m \Delta$. \leftarrow proof on next slide

Lemma 3. There are at most 2m augmentations per scaling phase.

- Let f be the flow at the end of the previous scaling phase.
- L2 \Rightarrow v(f*) \leq v(f) + m (2 Δ).
- Each augmentation in a Δ -phase increases v(f) by at least Δ . •

Theorem. The scaling max-flow algorithm finds a max flow in $O(m \log C)$ augmentations. It can be implemented to run in $O(m^2 \log C)$ time. •

Capacity Scaling: Running Time

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then value of the maximum flow is at most v(f) + m Δ .

Pf. (almost identical to proof of max-flow min-cut theorem)

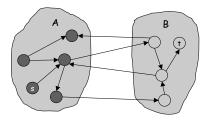
- We show that at the end of a Δ -phase, there exists a cut (A, B) such that cap(A, B) $\leq v(f) + m \Delta$.
- Choose A to be the set of nodes reachable from s in $G_f(\Delta)$.
- By definition of $A, s \in A$.
- By definition of f, $t \notin A$.

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$

$$\geq \sum_{e \text{ out of } A} (c(e) - \Delta) - \sum_{e \text{ in to } A} \Delta$$

$$= \sum_{e \text{ out of } A} c(e) - \sum_{e \text{ out of } A} \Delta - \sum_{e \text{ in to } A} \Delta$$

$$\geq cap(A, B) - m\Delta$$



original network