



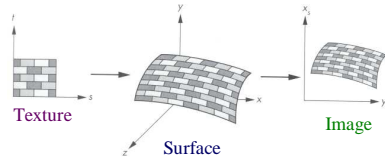
Texture Mapping & Hidden Surface Removal

Thomas Funkhouser
Princeton University
COS 426, Spring 2004



Textures

- Describe color variation in interior of 3D polygon
 - When scan converting a polygon, vary pixel colors according to values fetched from a texture

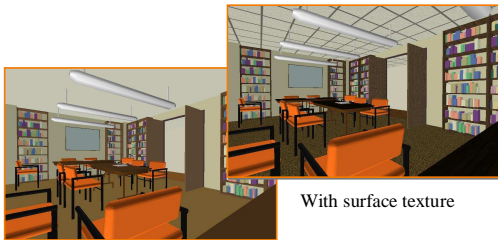


Angel Figure 9.3



Surface Textures

- Add visual detail to surfaces of 3D objects



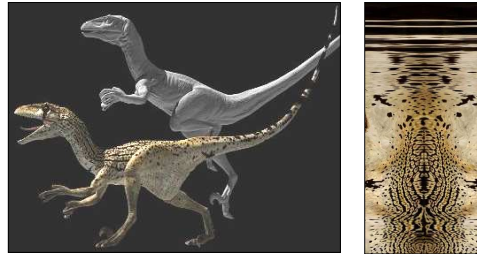
With surface texture

Polygonal model



Surface Textures

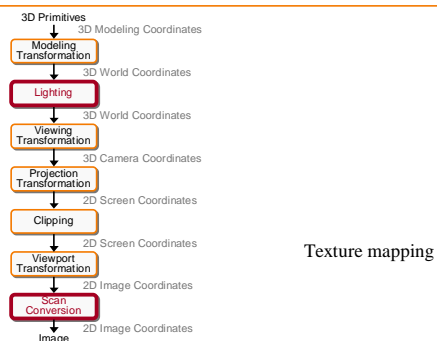
- Add visual detail to surfaces of 3D objects



[Daren Horley]



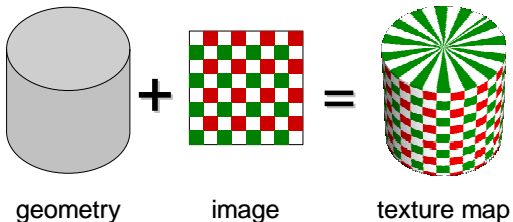
3D Rendering Pipeline (for direct illumination)



Texture Mapping Overview

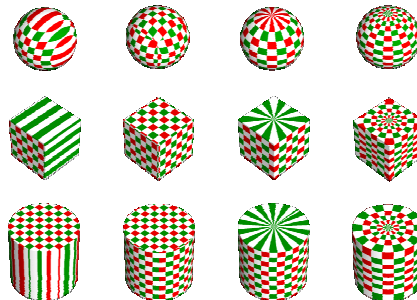
- Texture mapping methods
 - Parameterization
 - Mapping
 - Filtering
- Texture mapping applications
 - Modulation textures
 - Illumination mapping
 - Bump mapping
 - Environment mapping
 - Image-based rendering
 - Non-photorealistic rendering

Parameterization



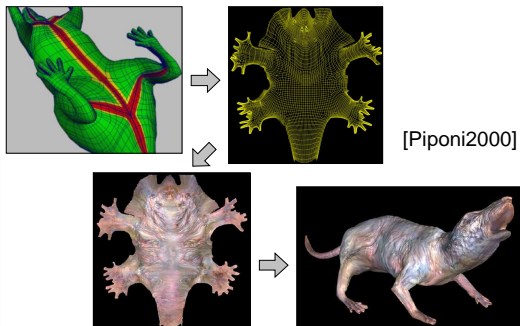
- Q: How do we decide *where* on the geometry each color from the image should go?

Option: Varieties of projections



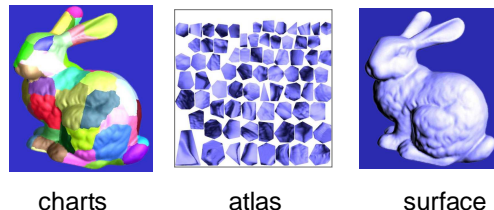
[Paul Bourke]

Option: unfold the surface



[Piponi2000]

Option: make an atlas



charts

atlas

surface

[Sander2001]

Texture Mapping Overview

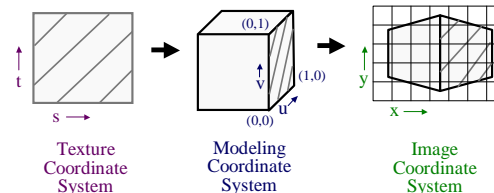


- Texture mapping methods
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Texture Mapping



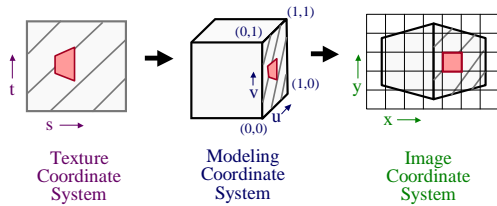
- Steps:
 - Define texture
 - Specify mapping from texture to surface
 - Lookup texture values during scan conversion



Texture Mapping



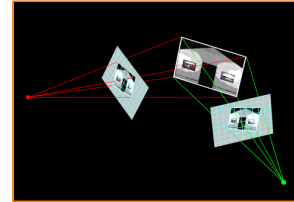
- When scan convert, map from ...
 - image coordinate system (x,y) to
 - modeling coordinate system (u,v) to
 - texture image (t,s)



Texture Mapping



- Texture mapping is a 2D projective transformation
 - texture coordinate system: (t,s) to
 - image coordinate system (x,y)

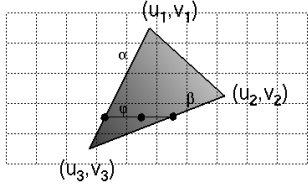


Allison Klein, Princeton

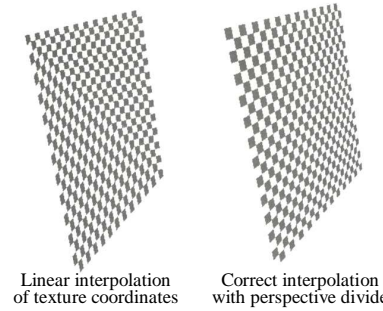
Texture Mapping



- Scan conversion
 - Interpolate texture coordinates down/across scan lines
 - Distortion due to bilinear interpolation approximation
 - » Cut polygons into smaller ones, or
 - » Perspective divide at each pixel



Texture Mapping



Hill Figure 8.42

Overview

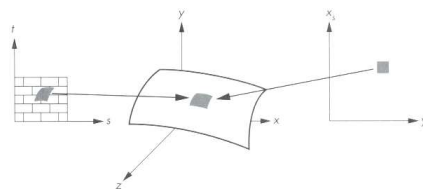


- Texture mapping methods
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Texture Filtering



- Must sample texture to determine color at each pixel in image

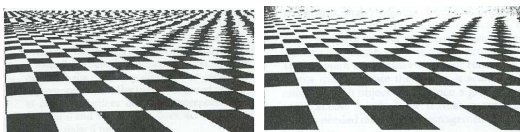


Angel Figure 9.4

Texture Filtering



- Aliasing is a problem



Point sampling

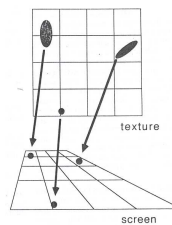
Area filtering

Angel Figure 9.5

Texture Filtering



- Ideally, use elliptically shaped convolution filters

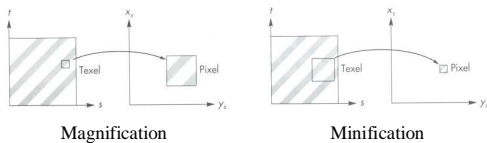


In practice, use rectangles

Texture Filtering



- Size of filter depends on projective warp
 - Can prefiltering images
 - » Mip maps
 - » Summed area tables



Magnification

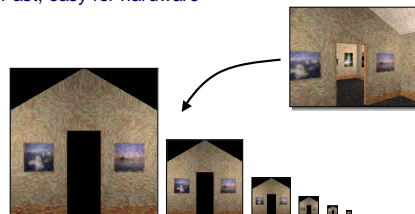
Minification

Angel Figure 9.14

Mip Maps



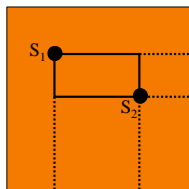
- Keep textures prefiltered at multiple resolutions
 - For each pixel, linearly interpolate between two closest levels (e.g., trilinear filtering)
 - Fast, easy for hardware



Summed-area tables



- At each texel keep sum of all values down & right
 - To compute sum of all values within a rectangle, simply subtract two entries
 - Better ability to capture very oblique projections
 - But, cannot store values in a single byte



Overview

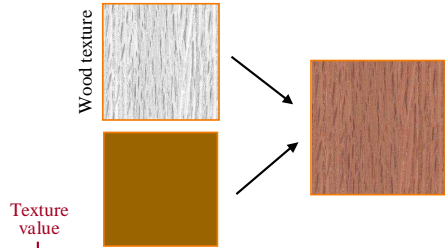


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Modulation textures



Map texture values to scale factor



$$I = T(s, t)(I_E + K_A I_A + \sum_L (K_D(N \cdot L) + K_S(V \cdot R)^n)S_L I_L + K_T I_T + K_S I_S)$$

Illumination Mapping



Map texture values to surface material parameter

- K_A
- K_D
- K_S
- K_T
- n



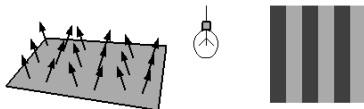
$$K_T = T(s, t)$$

$$I = I_E + K_A I_A + \sum_L (K_D(N \cdot L) + K_S(V \cdot R)^n)S_L I_L + K_T I_T + K_S I_S$$

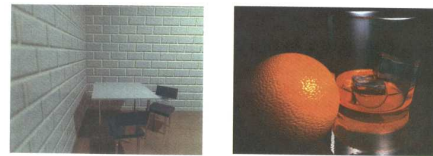
Bump Mapping



Texture values perturb surface normals



Bump Mapping

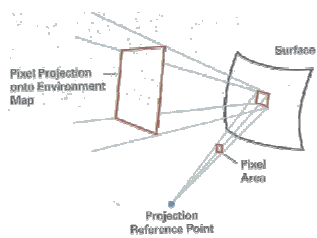


H&B Figure 14.100

Environment Mapping



Texture values are reflected off surface patch

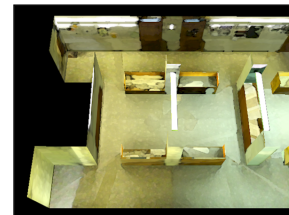


H&B Figure 14.93

Image-Based Rendering



Map photographic textures to provide details for coarsely detailed polygonal model



Solid textures

Texture values indexed by 3D location (x,y,z)

- Expensive storage, or
- Compute on the fly, e.g. Perlin noise

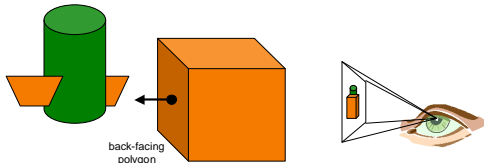


Texture Mapping Summary

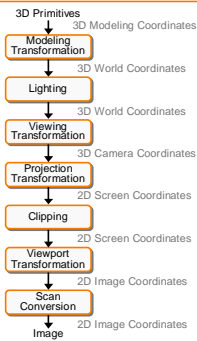
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Hidden Surface Removal (HSR)

- Surfaces may be back-facing.
- Surfaces may be occluded.
- Surfaces may overlap in the image plane.
- Surfaces may intersect.

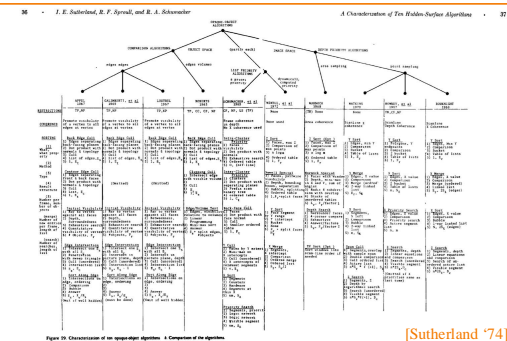


3D Rendering Pipeline



Somewhere in here we have to decide which objects are visible, and which objects are hidden.

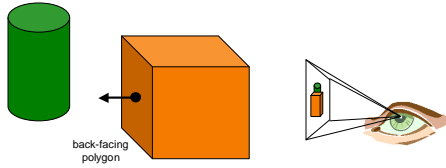
HSR Algorithms



Hidden Surface Removal Algorithms

- Object space
 - Back-face detection
 - Depth sort
- Screen space
 - Ray casting
 - Scan-line
 - Z-buffer
 - Area subdivision

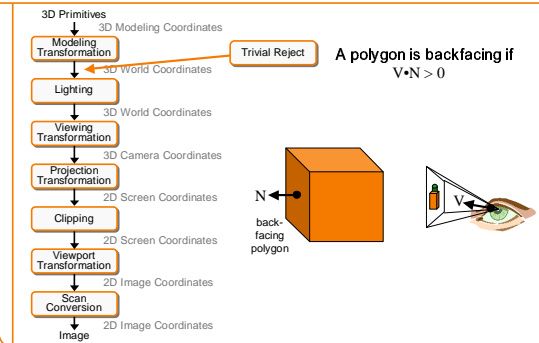
Back-face detection



Q: How do we test for back-facing polygons?

A: Dot product of the normal and view directions.

3D Rendering Pipeline

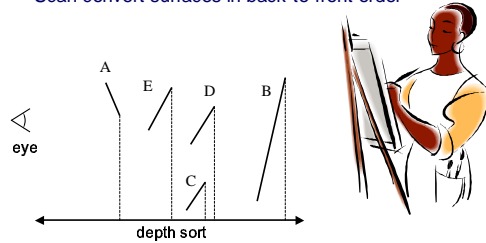


Depth sort

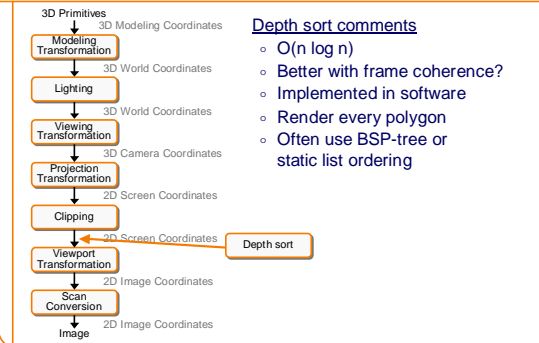


“Painter's algorithm”

- Sort surfaces in order of decreasing maximum depth
- Scan convert surfaces in back-to-front order



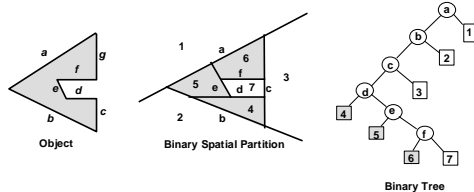
3D Rendering Pipeline



BSP Tree



- Binary space partition with solid cells labeled
 - Constructed from polygonal representations
 - Provides linear-time depth sort for arbitrary view



(We'll come back to this...)

Naylor

Hidden Surface Removal Algorithms

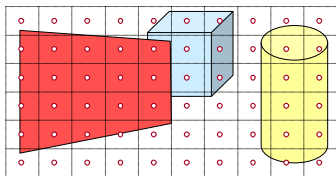


- Object space
 - Back-face detection
 - Depth sort
- Screen space
 - Ray casting
 - Scan-line
 - Z-buffer
 - Area subdivision

Ray Casting



- Fire a ray for every pixel
 - If ray intersects multiple objects, take the closest

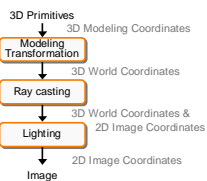


Ray Casting Pipeline



Ray casting comments

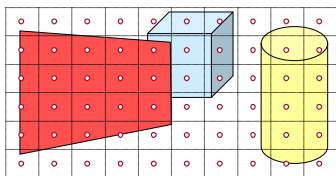
- $O(p \log n)$ for p pixels
- May (or not) use pixel coherence
- Simple, but generally not used



Z-Buffer



- Color & depth of closest object for every pixel
 - Update only pixels whose depth is closer than in buffer
 - Depths are interpolated from vertices, just like colors

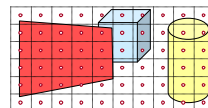
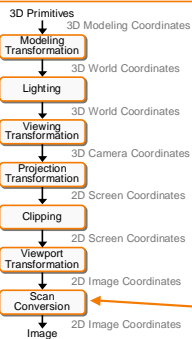


3D Rendering Pipeline



Z-buffer comments

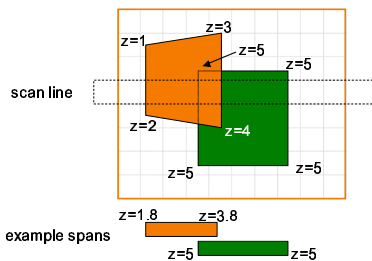
- Polygons rasterized in any order
- Requires lots of memory
 - $1K \times 1K \times 24bits$
 - Was expensive, cheap now
- Subject to aliasing (A-buffer)
- Commonly in hardware



Scan-Line Algorithm



- For each scan line, construct spans
 - Sort by depth

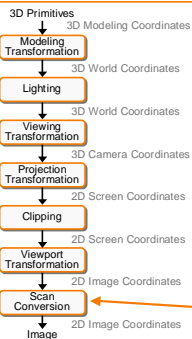


3D Rendering Pipeline



Scan-line comments

- Fully compute only visible pixels
- Coherence among along scans
- Commonly in software

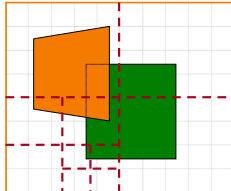


Area Subdivision

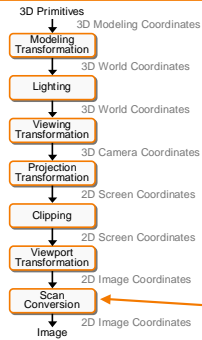


Warnock's algorithm

- Fill area if:
 - » All surfaces are outside area, or
 - » Only one surface intersects area, or
 - » One surface occludes other surfaces in area
- Otherwise, subdivide



3D Rendering Pipeline



Area subdivision comments

- Augments scan conversion
- Polygon coherence
- Commonly in software

Area subdiv.

Summary



- Texture Mapping
 - Add detail during scan conversion
- Hidden surface removal
 - Find visible surfaces