

## COS 226 Lecture 3: Quicksort

To sort an array, first divide it so that

- some element  $a[i]$  is in its final position
- no larger element left of  $i$
- no smaller element right of  $i$

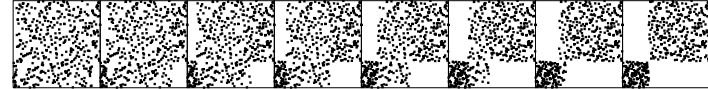
Then sort the left and right parts recursively

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## Partitioning

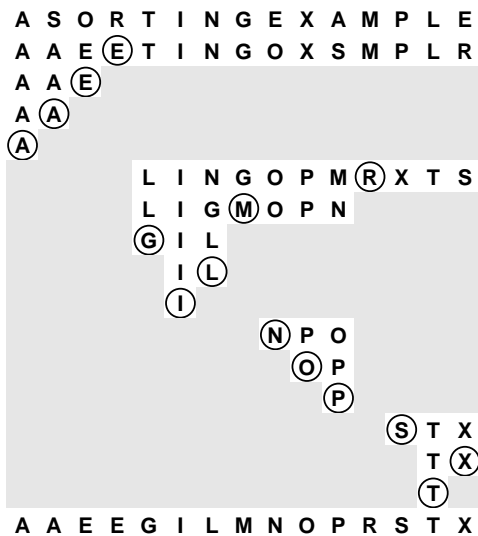
To partition an array

- pick a partitioning element
- scan from right for smaller element
- scan from left for larger element
- exchange
- repeat until pointers cross



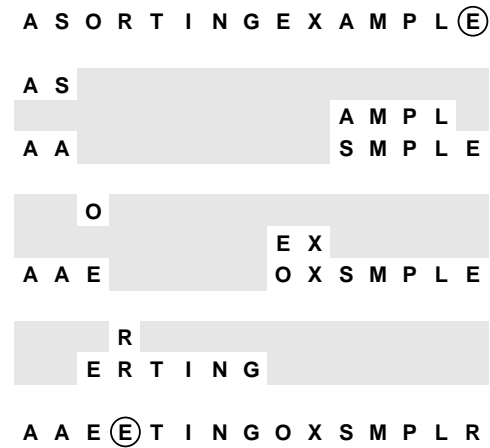
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## Quicksort example



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## Partitioning example



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## Partitioning implementation

```
int partition(Item a[], int l, int r)
{ int i, j; Item v;
  v = a[r]; i = l-1; j = r;
  for (;;)
  {
    while (less(a[++i], v)) ;
    while (less(v, a[--j])) if (j == l) break;
    if (i >= j) break;
    exch(a[i], a[j]);
  }
  exch(a[i], a[r]);
  return i;
}
```

### Issues

- stop pointers on keys equal to v?
- sentinels or explicit tests for array bounds?
- details of pointer crossing

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## Nonrecursive Quicksort

Use explicit stack instead of recursive calls  
Sort smaller of two subfiles first

```
#define push2(A, B) push(A); push(B);
void quicksort(Item a[], int l, int r)
{ int i;
  stackinit(); push2(l, r);
  while (!stackempty())
  {
    r = pop(); l = pop();
    if (r <= l) continue;
    i = partition(a, l, r);
    if (i-l > r-i)
      { push2(l, i-1); push2(i+1, r); }
    else
      { push2(i+1, r); push2(l, i-1); }
  }
}
```

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## Quicksort implementation

```
quicksort(Item a[], int l, int r)
{ int i;
  if (r > l)
  {
    i = partition(a, l, r);
    quicksort(a, l, i-1);
    quicksort(a, i+1, r);
  }
}
```

### Issues

- overhead for recursion?
- running time depends on input
- worst-case time cost (quadratic, a problem)
- worst-case space cost (linear, a serious problem)

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## Analysis of Quicksort

Total running time is sum of

- cost\*frequency

for all the basic operations

**Cost** depends on machine

**Frequency** depends on algorithm, input

For Quicksort

- A -- number of partitioning stages
- B -- number of exchanges
- C -- number of comparisons

Cost on a typical machine:  $35A + 11B + 4C$

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## Worst case analysis

Number of comparisons in the worst case

- $N + (N-1) + (N-2) + \dots = N(N-1)/2$

Worst case files

- already sorted (!)
- reverse order
- all equal? (stay tuned)

Total time proportional to  $N^2$

No better than elementary sorts?

Fix: use a random partitioning element

- "guarantees" fast performance

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## Empirical analysis

Use profiler

Inner loop

- look for highest counts
- is every line of code there necessary?

Verify analysis

- are counts in predicted range?

Streamline program by iterating process

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## Average case analysis

Assume input randomly ordered

- each element equally likely to be partitioning element
- subfiles randomly ordered if partitioning is "blind"

Average number of comparisons satisfies

$$C(N) = N+1 + (C(1) + C(N-1))/N \\ + (C(2) + C(N-2))/N \\ \dots \\ + (C(N-1) + C(1))/N$$

$$C(N) = N+1 + 2(C(1) + C(2) + \dots + C(N-1))/N$$

$$NC(N) = N(N+1) + 2(C(1) + C(2) + \dots + C(N-1))$$

$$NC(N) - (N-1)C(N-1) = 2N + 2C(N-1)$$

$$NC(N) = (N+1)C(N-1) + 2N$$

$$C(N)/(N+1) = C(N-1)/N + 2/(N+1)$$

$$= 2(1 + 1/2 + 1/3 + \dots + 1/(N+1))$$

$$= 2 \ln N + (\text{small error term})$$

**THM:** Quicksort uses about  $2N \ln N$  comparisons

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## Quicksort profile

```
quicksort(int a[], int l, int r)
<132659>{
  int v, i, j, t;
  if (<132659>r > l)
  {
    <66329>v = a[r];
    <66329>i = l-1; <66329>j = r;
    for (<66329>;<327102>;<327102>)
    {
      while (<1033228>a[++i] < v) <639797>;
      while (<1077847>a[--j] > v) <684416>;
      if (<393431>i >= j) <66329>break;
      <327102>t = a[i]; a[i] = a[j]; a[j] = t;
    }
    <66329>t = a[i]; a[i] = a[r]; a[r] = t;
    <66329>quicksort(a, l, i-1);
    <66329>quicksort(a, i+1, r);
  }
<132659>}
```

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## Ex: another partitioning method

(detailed justification omitted)

```

quicksort(int a[], int l, int r)
<133395>{
  int v, i, k, t;
  if (<133395>r <= l) return;
  <66697>v = a[l]; <66697>k = l;
  for (<66697>i=l+1; <1976624>i<=r; <1909927>i++)
    if (<1909927>a[i] < v)
      { <934565>t = a[i]; a[i] = a[++k]; a[k] = t; }
  <66697>t = a[k]; a[k] = a[l]; a[l] = t;
  <66697>quicksort(a, l, k-1);
  <66697>quicksort(a, k+1, r);
}
<133395>}

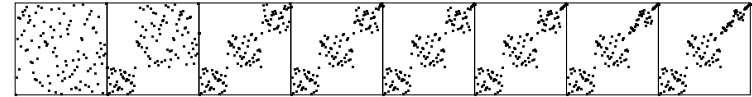
```

Not much simpler, three times as many exchanges

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## Improvements to Quicksort (examples)

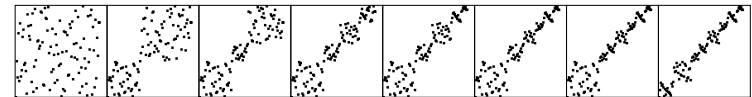
### Standard



### Cutoff for small subfiles



### Median-of-three



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## Improvements to Quicksort

### Median-of-sample

- partitioning element closer to center
- estimate median with median of sample
- number of comparisons close to  $N \lg N$
- FEWER LARGE FILES
- slightly more exchanges, more overhead

### Insertion sort small subfiles

- even Quicksort has too much overhead for files of a few elements
- use insertion sort for tiny files (can wait until the end)

### Optimize parameters

- median of 3 elements
- cut to insertion sort for  $< 10$  elements

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## Selection

Use partitioning to find the k-th smallest element

- (don't need to sort the whole file)

```

select(Item a[], int l, int r, int k)
{ int i;
  if (r <= l) return;
  i = partition(a, l, r);
  if (i > k) select(a, l, i-1, k);
  if (i < k) select(a, i+1, r, k);
}

```

Ex: to find median

```
select(a, l, r, (l+r)/2);
```

Also puts k smallest elements in first k positions

Running time is LINEAR on the average

linear time guarantee possible?

- old theorem says yes; not useful in practice
- randomized guarantee just about as good

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## Equal keys

Equal keys can adversely affect performance

**One** key value (all keys are the same)

- plain quicksort takes  $N \lg N$  comparisons (!)
- change partitioning to take  $N$  comparisons
- naive method might use  $N^2$  comparisons (!!)

**Two** distinct key values

- reduces to above case for one subfile
- better to complete sort with one partition  
stop right ptr on  $o$ ; stop left ptr on  $i$ ; exchange

**Several** distinct key values

- reduces to above cases

Serious performance bug in widely-used implementations

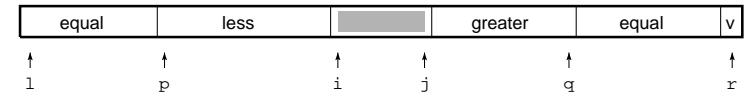
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## Three-way partitioning solution

**Four-part** partition

- some elements between  $i$  and  $j$  equal to  $v$
- no larger element left of  $i$
- no smaller element right of  $j$
- more elements between  $i$  and  $j$  equal to  $v$

Swap equal keys into center



All the right properties

- easy to implement
- linear if keys all equal
- no extra cost if no equal keys

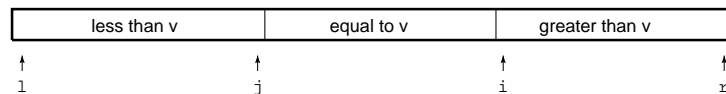
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## Three-way partitioning problem

Natural way to deal with equal keys

Partition into three parts

- elements between  $i$  and  $j$  equal to  $v$
- no larger element left of  $i$
- no smaller element right of  $j$



Dutch National Flag problem

- Not easy to implement efficiently (try it!)
- Not done in practical sorts before mid-1990s

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## Three-way partitioning implementation

```

void quicksort(Item a[], int l, int r)
{
    int i, j, k, p, q; Item v;
    if (r <= l) return;
    v = a[r]; i = l-1; j = r; p = l-1; q = r;
    for (;;)
    {
        while (less(a[++i], v)) ;
        while (less(v, a[--j])) if (j == l) break;
        if (i >= j) break;
        exch(a[i], a[j]);
        if (eq(a[i], v)) { p++; exch(a[p], a[i]); }
        if (eq(v, a[j])) { q--; exch(a[q], a[j]); }
    }
    exch(a[i], a[r]); j = i-1; i = i+1;
    for (k = l ; k < p; k++, j--) exch(a[k], a[j]);
    for (k = r-1; k > q; k--, i++) exch(a[k], a[i]);
    quicksort(a, l, j);
    quicksort(a, i, r);
}

```

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## Significance of three-way partitioning

Equal keys omnipresent in applications

- ex: sort population by age
- ex: sort job applicants by college attended

Purpose of sort: bring records with equal keys together

Typical application

- Huge file
- Small number of key values

randomized 3-way Quicksort is LINEAR time (try it!)

**THM:** Quicksort with 3-way partitioning is OPTIMAL

Proof: (beyond the scope of 226) ties cost to entropy

[this fundamental fact was not known until 2000!]