



Boids

COS 426

Boids



- Overall idea
 - Simulate group behavior by specifying rules for individual behavior (self-organizing distributed system)

“... and the thousands off fishes moved as a huge beast , piercing the water.

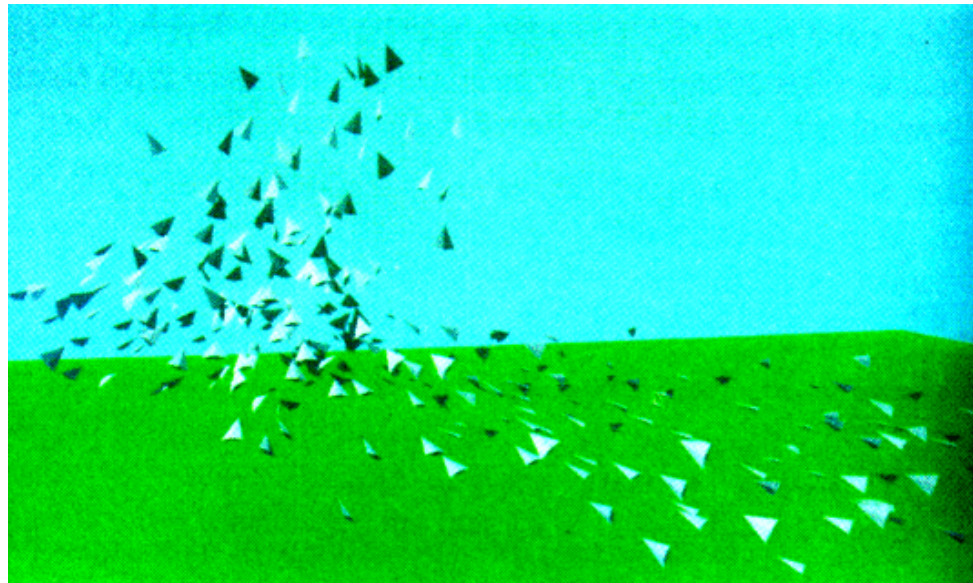
They appeared united, inexorably bound to a common fate.

How comes this unity?.. “

- Anonymous.

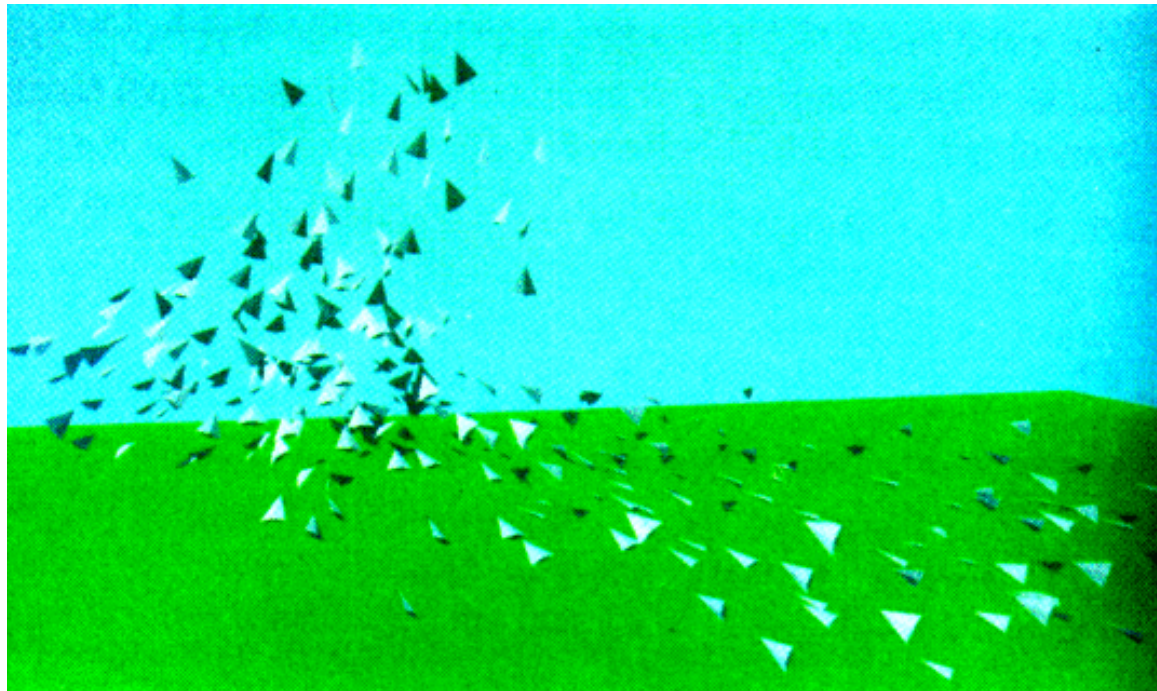
Boids

- Powerful, simple model
 - No central control
 - Only simple rules for each individual
 - Complex, emergent phenomena
 - Self-organization, swarm intelligence



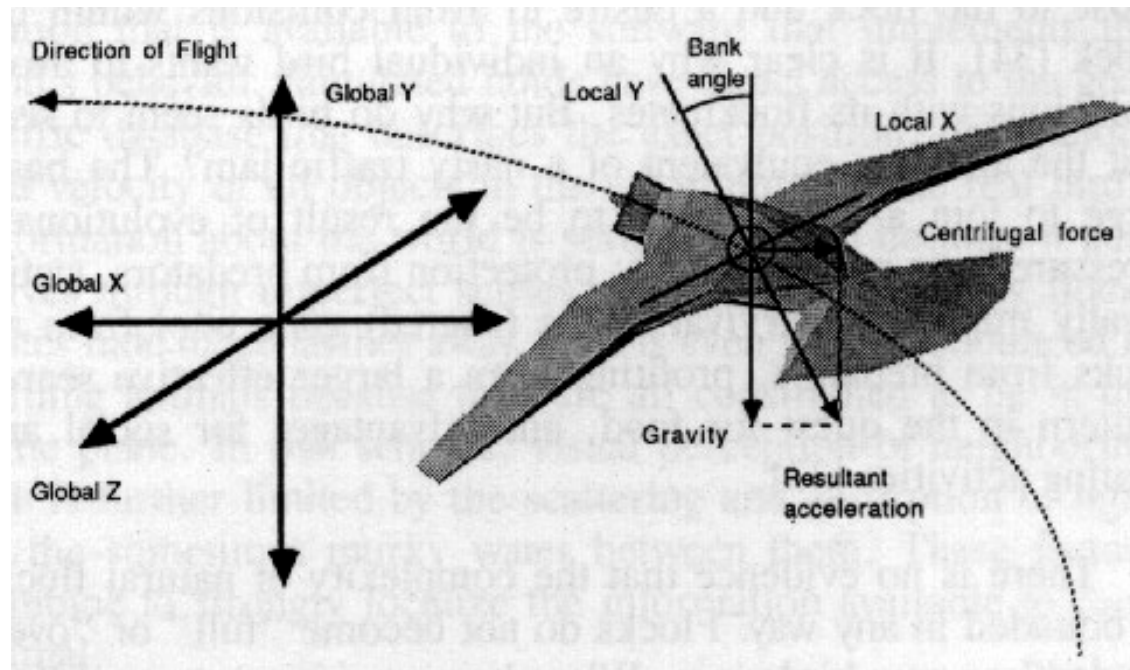
Boids

- Computer graphics motivation
 - Scripting of the path of many individual objects using traditional computer animation techniques is tedious.



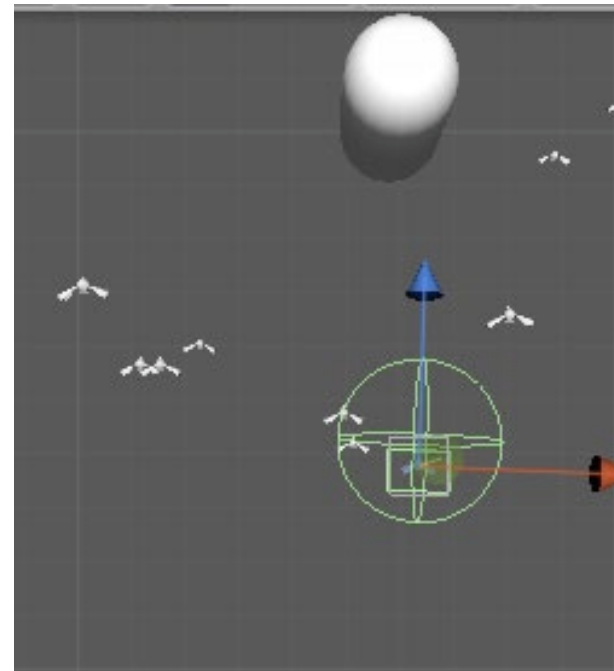
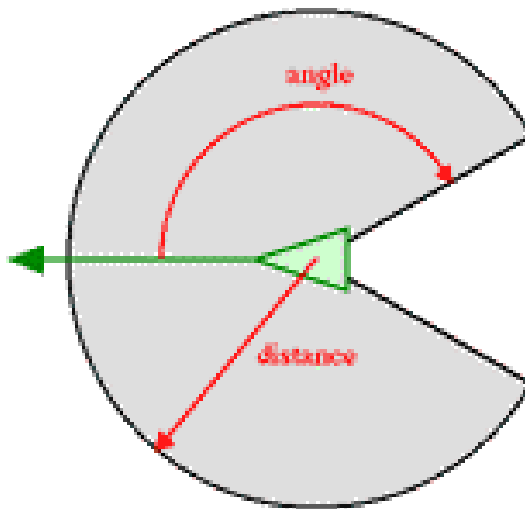
Boids

- Like a particle system, except ...
 - Each boid may be an entire polygonal object with a local coordinate system (rather than a point)



Boids

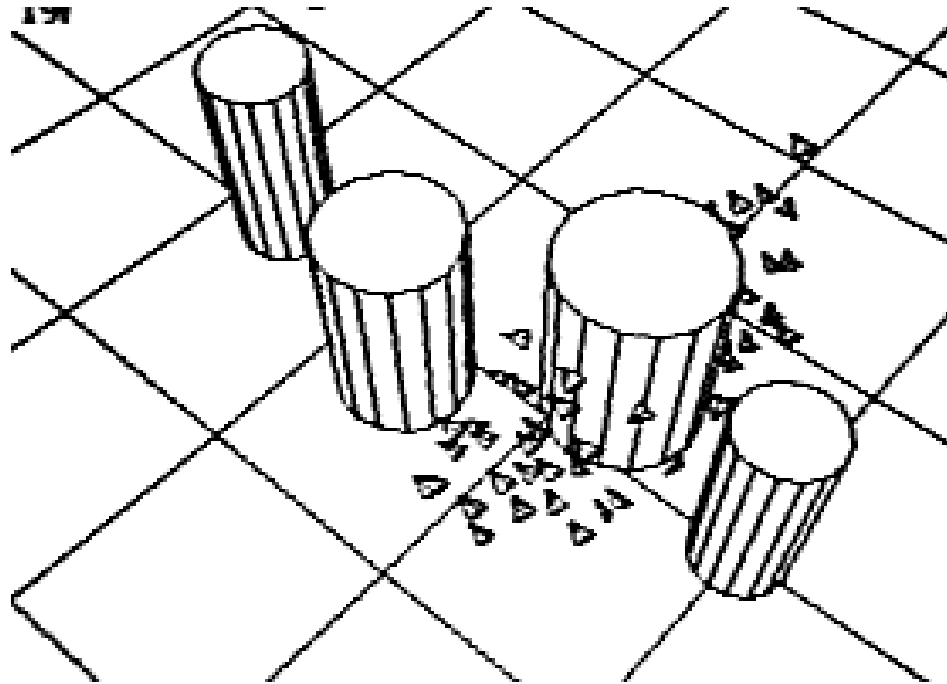
- Like a particle system, except ...
 - Each boid can “perceive” a local region around it, e.g., a spherical neighborhood



Boids



- Like a particle system, except ...
 - Each boid exerts “intentional forces”



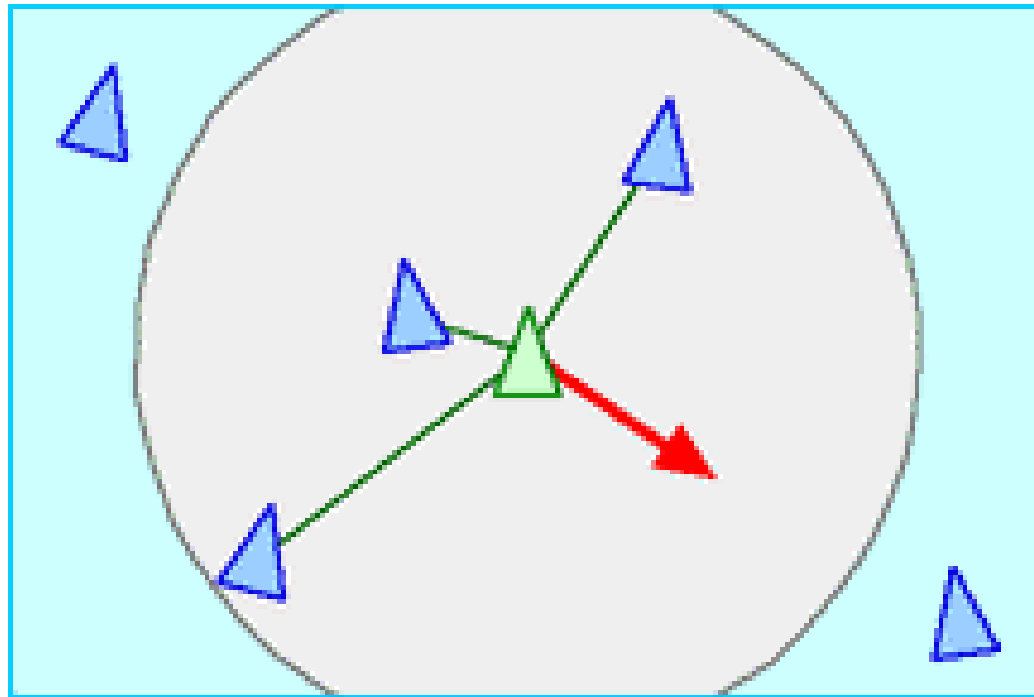
Flocking



- Complex flocking behaviors can be modeled with simple “intentional forces”
 - Separation
 - Alignment
 - Cohesion

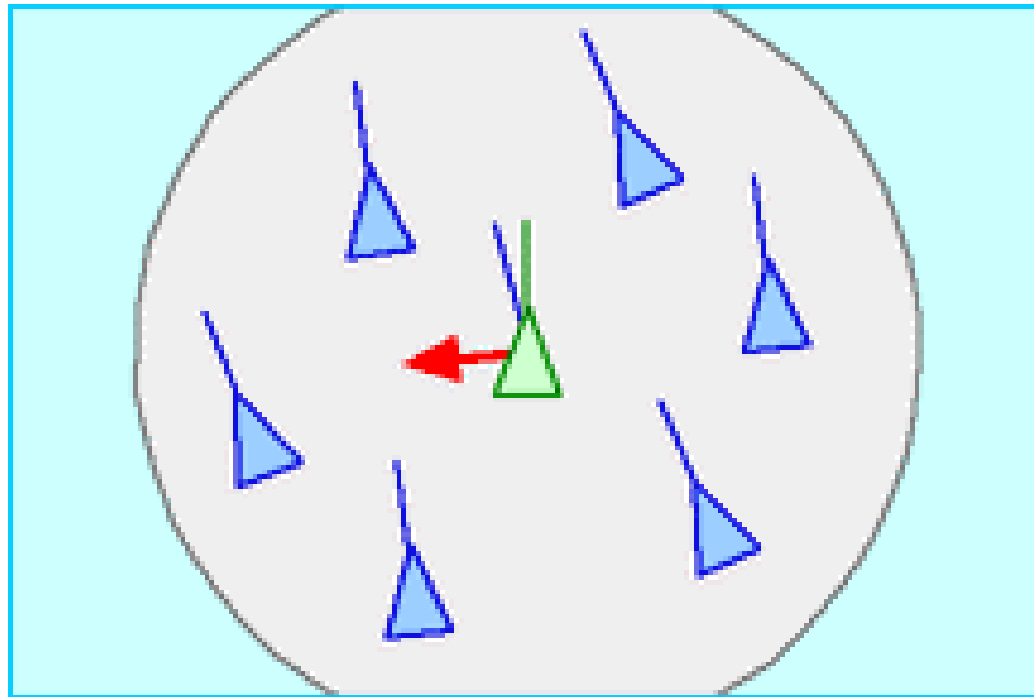
Flocking – 3 Behaviors (1)

- Separation = collision avoidance:
avoid collisions with nearby flockmates



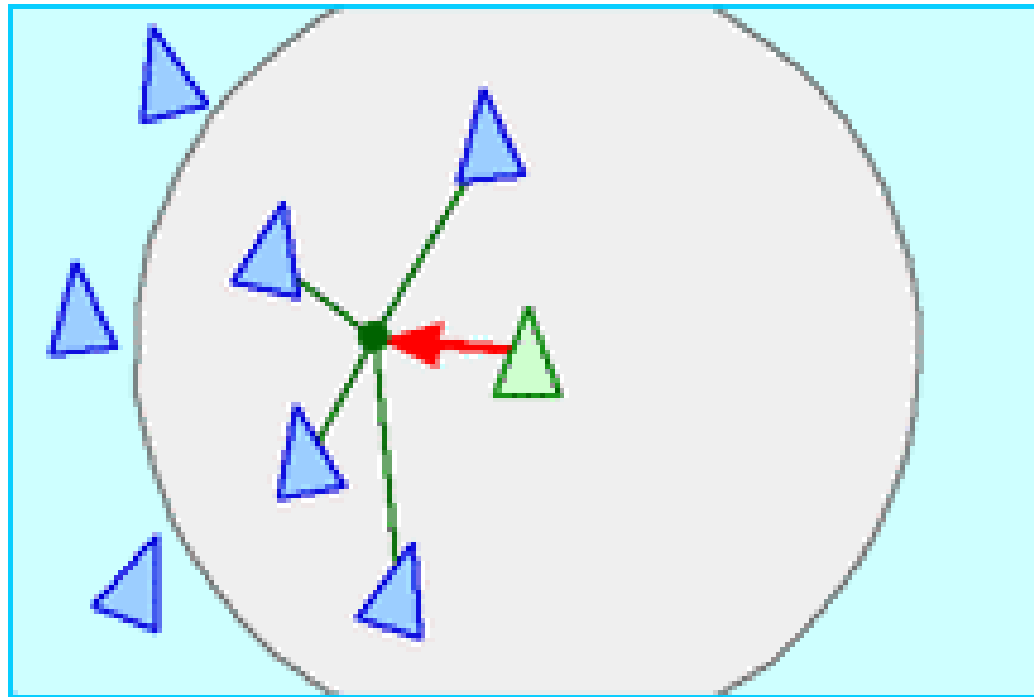
Flocking – 3 Behaviors (2)

- Alignment = velocity matching:
attempt to match velocity with nearby flockmates



Flocking – 3 Behaviors (3)

- Cohesion = flock centering:
attempt to stay close to nearby flockmates



Other Examples (single behavior)



- Example behaviors
 - Seek
 - Flee
 - Evasion
 - Pursuit
 - Wander
 - Arrival
 - Obstacle Avoidance
 - Containment
 - Wall Following
 - Path Following

Other Examples (single behavior)

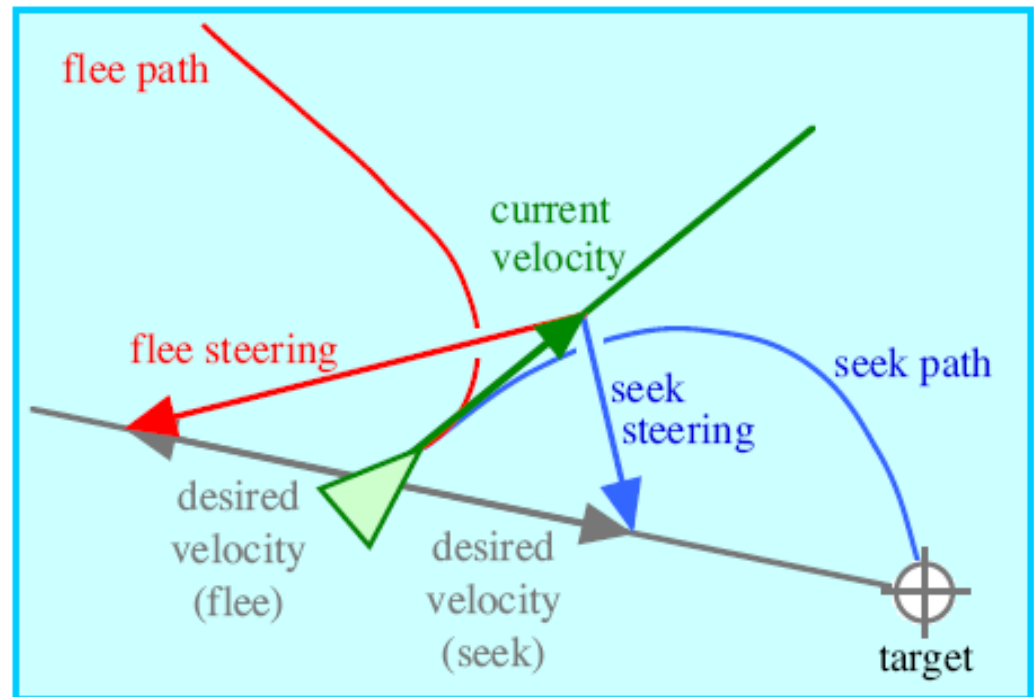


- Example behaviors

- Seek

- Flee

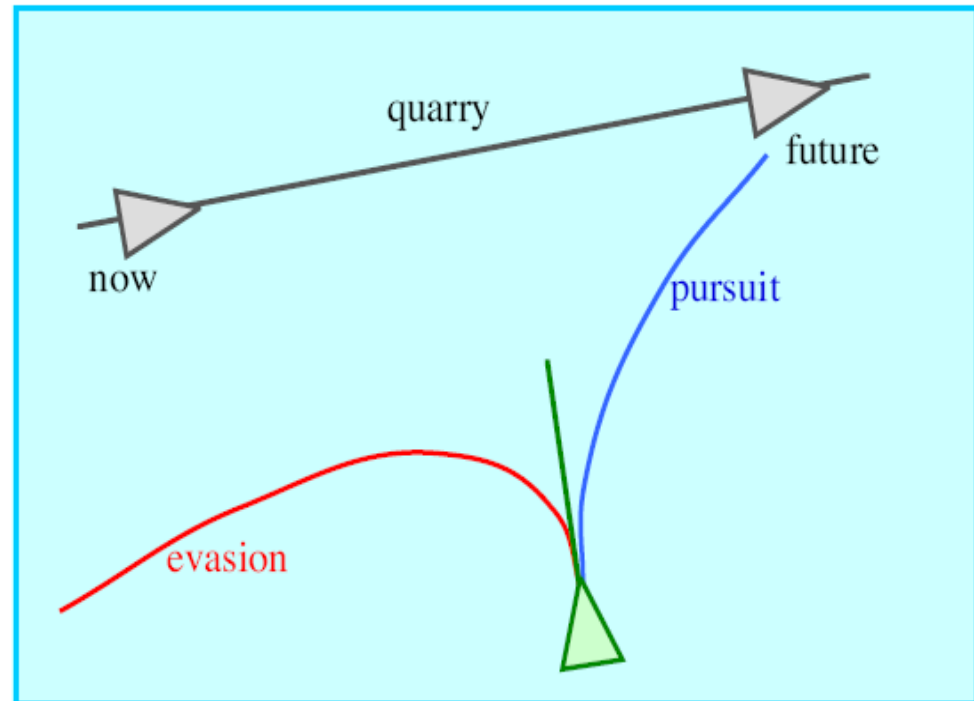
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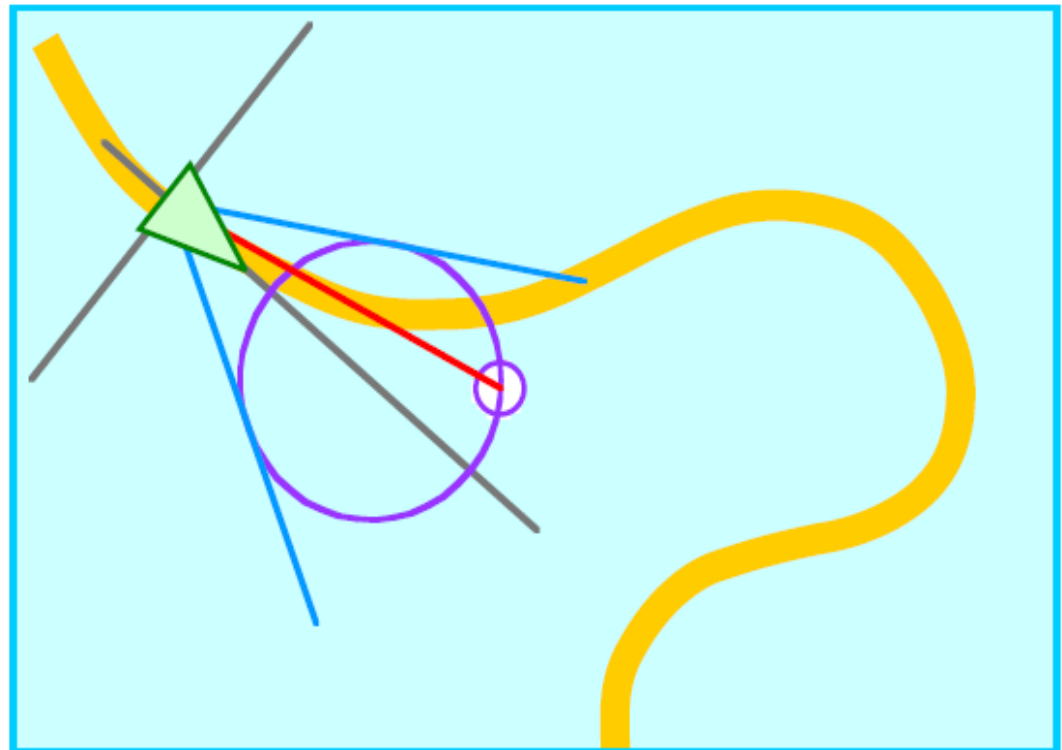


Other Examples (single behavior)



- Example behaviors

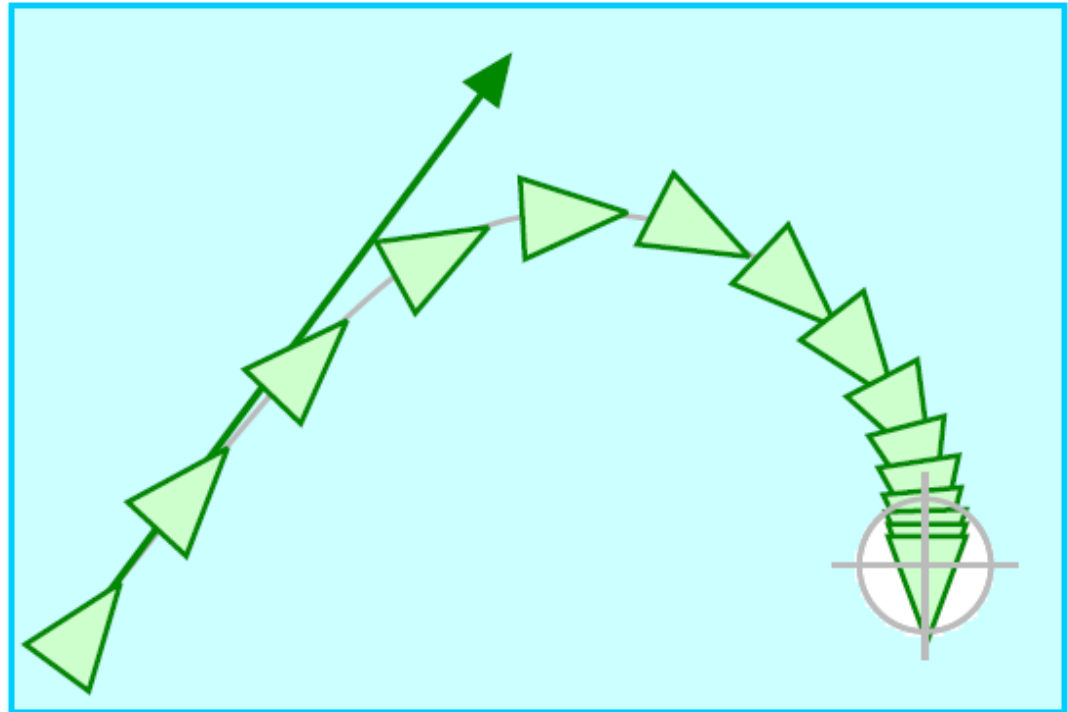
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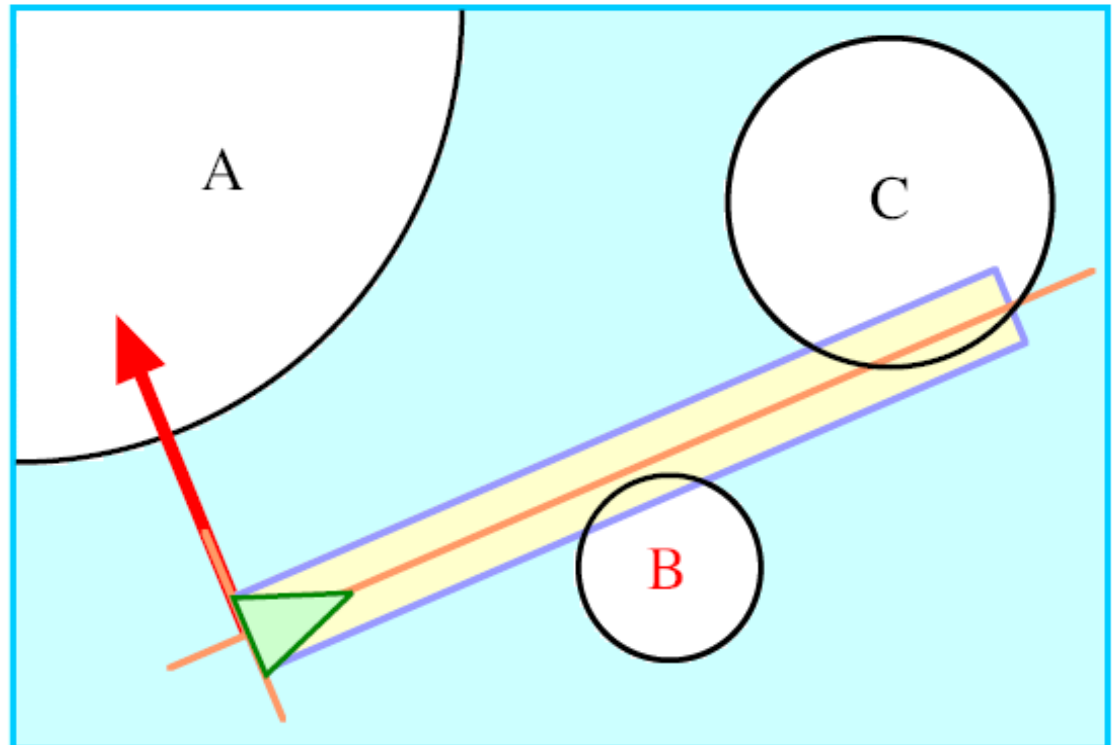


Other Examples (single behavior)



- Example behaviors

- Seek
- Flee
- Evasion
- Pursuit
- Wander
- Arrival
- **Obstacle Avoidance**
- Containment
- Wall Following
- Path Following

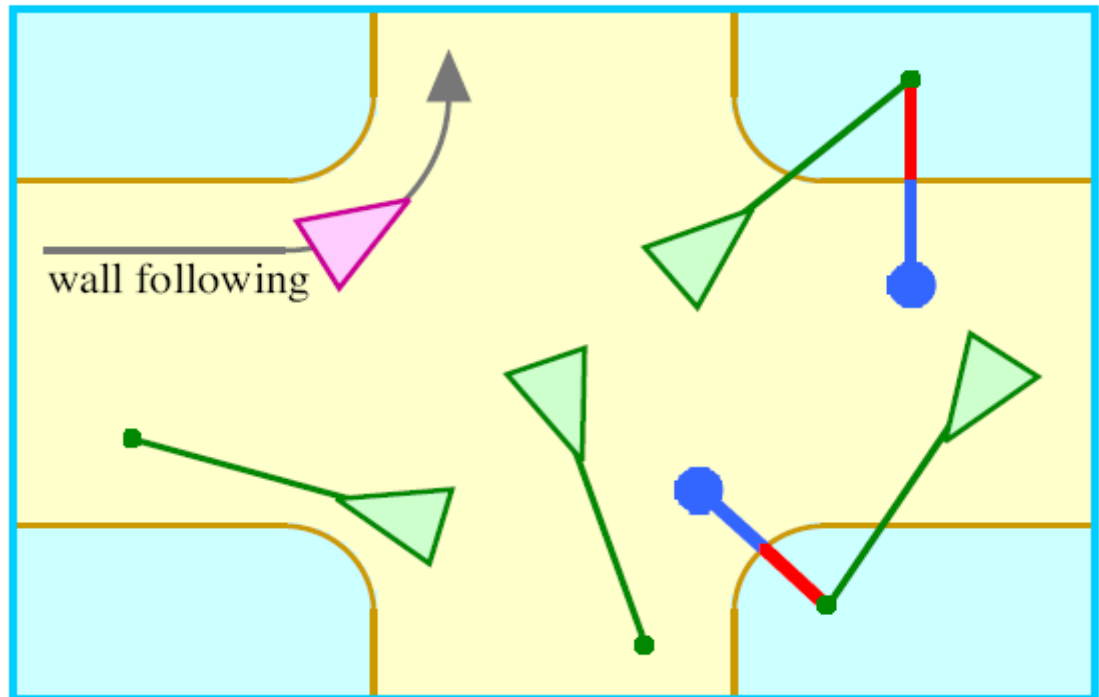


Other Examples (single behavior)



- Example behaviors

- Seek
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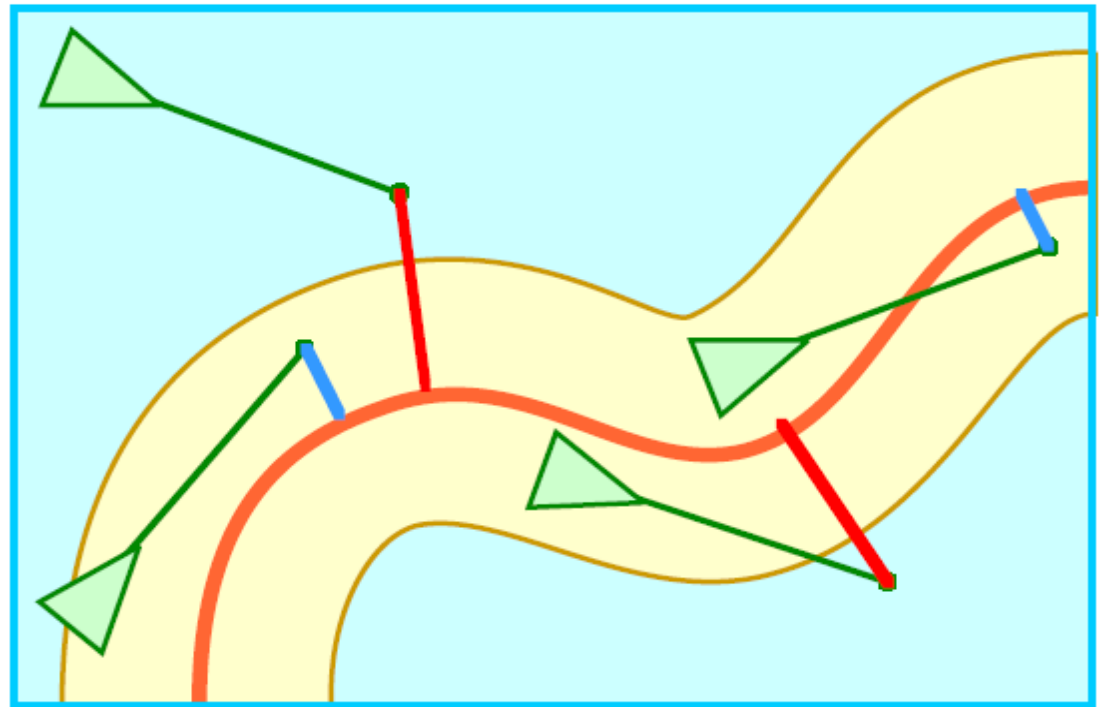


Other Examples (single behavior)



- Example behaviors

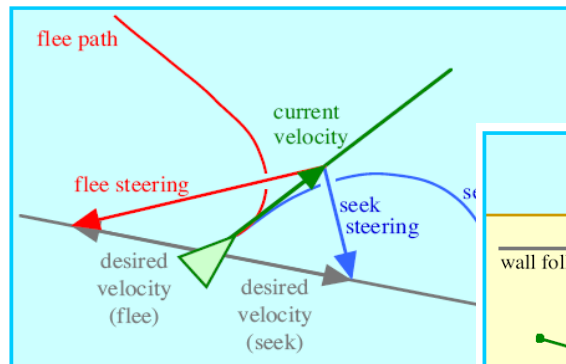
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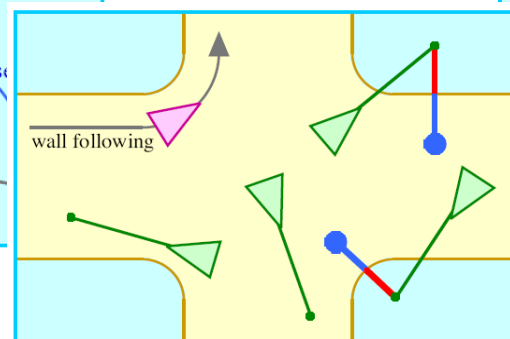
Other Examples (combined behaviors)



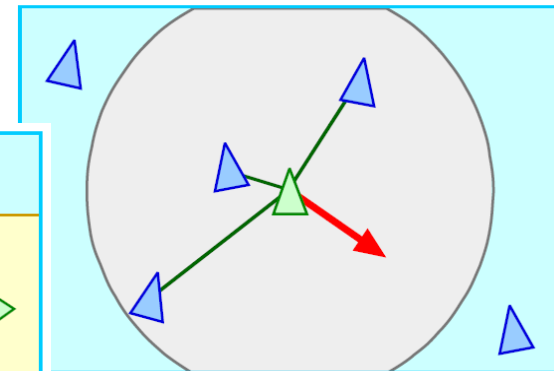
- Combined behaviors
 - Queuing = seek, containment, & separation
 - Flocking = alignment, cohesion, & separation



Seek



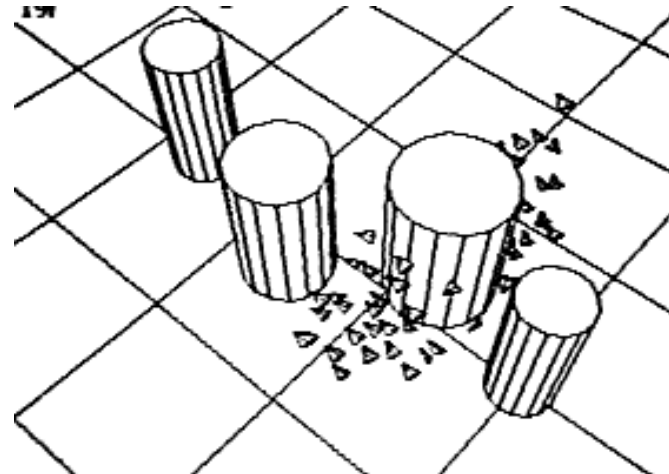
Containment



Separation

Obstacle Avoidance (1)

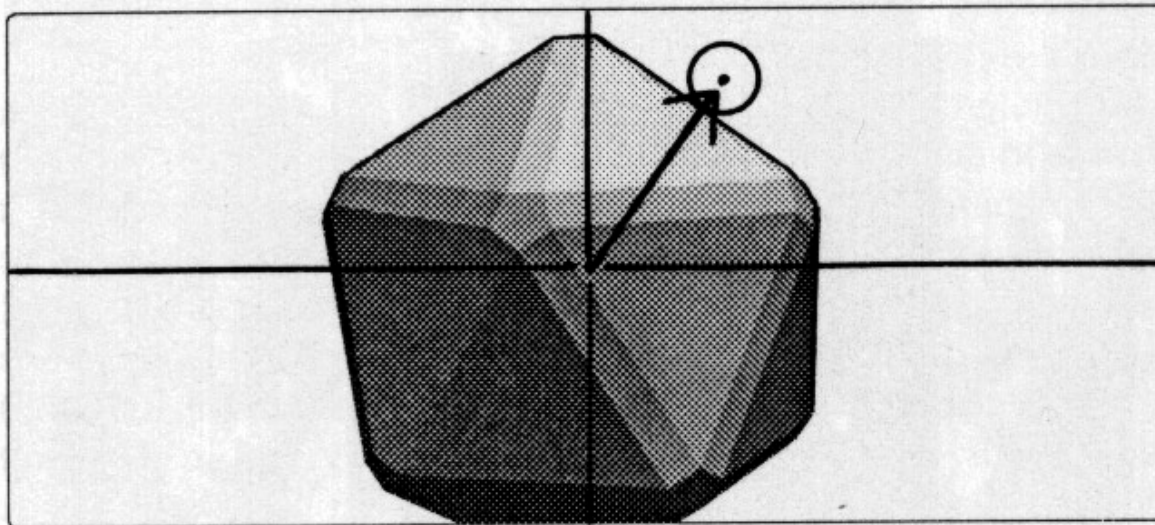
- Force field approach
 - Obstacles have a field of repulsion
 - Boids increasingly repulsed as they approach obstacle
- Drawbacks:
 - Approaching a force in exactly the opposite direction
 - Flying alongside a wall



Obstacle Avoidance (2)



- Steer-to-avoid approach
 - Boid only considers obstacles directly in front of it
 - Finds silhouette edge of obstacle closest to point of eventual impact
 - A vector is computed that will aim the boid at a point one body length beyond the silhouette edge

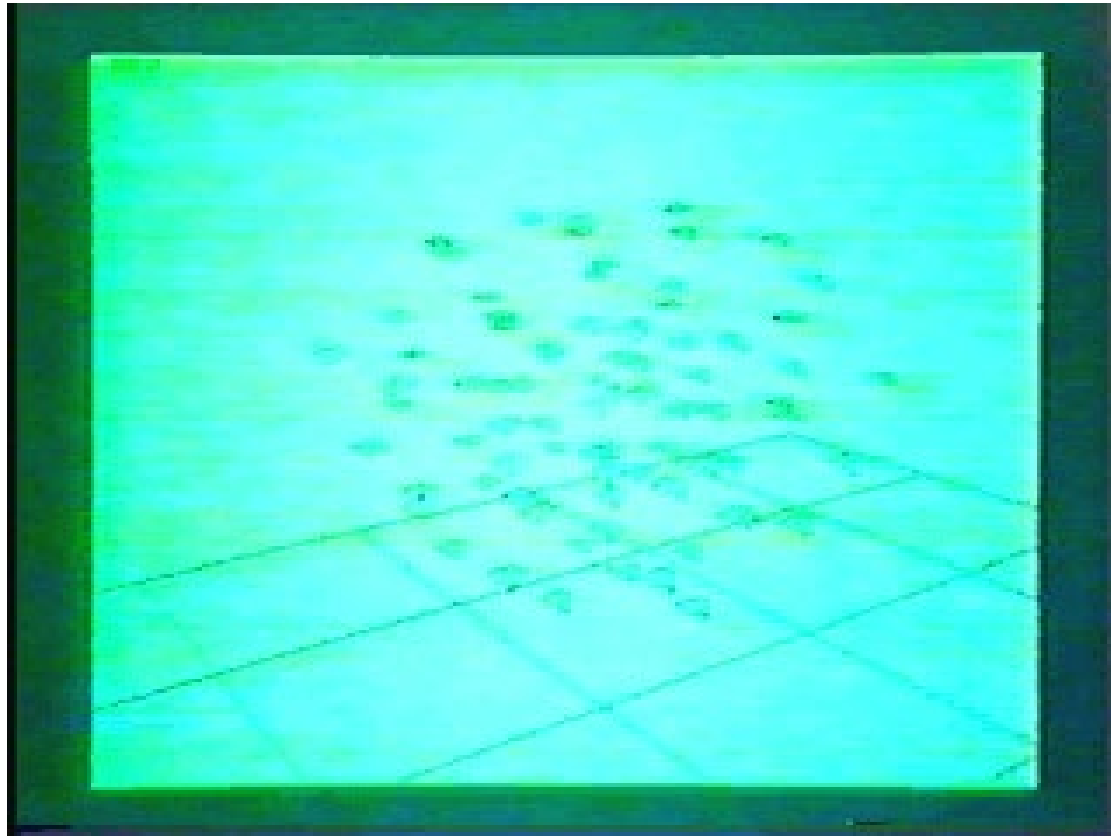


Arbitrating Independent Behaviors



- Navigation module of boid brain to collect relevant acceleration requests and then determine single behaviorally desired acceleration
 - Weighted average according to priority
- Emergency acceleration allocated to satisfy pressing needs first
 - Example: Centering ignored in order to maneuver around obstacles

Boids Example



Reynolds

Boids Example



<http://www.kfish.org/~conrad/java/Boids/example2.html>