COS 423 Lecture 7 Rank-Pairing Heaps

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Inefficiency in pairing heaps:

- Links during *inserts*, *melds*, *decrease-keys* can combine two trees of very different sizes, increasing the potential by $\Theta(\lg n)$.
- To avoid such bad links, we use *ranks*:
 - Each node has a non-negative integer rank
 - Missing nodes have rank –1
 - Rank of root = 1 + rank of left child
 - *rank of tree* = rank of root

Store ranks with nodes. Link only roots of equal rank. Rank of winning root increases by one:



A heap is a set of half trees, not just one half tree (can't link half trees of different ranks)
Representation of a heap: a circular singly-linked list of roots of half trees, with the root of minimum key (the *min-root*) first
Circular linking → catenation takes O(1) time
Node ranks depend on how operations are done

find-min: return item in min-root

make-heap: return a new, empty list

insert: create new one-node half tree of rank 0, insert in list, update min-root



meld: catenate lists, update min-root



delete-min: Delete min-root. Cut edges along right path down from new root to give new half-trees. Link roots of equal rank until no two roots have equal rank. Form list of remaining half trees.

To do links, use array of buckets, one per rank. Add each tree to its bucket, link with tree in bucket if there is one, add tree formed by link to next bucket.

delete-min: numbers are keys



delete-min: numbers are ranks







- Each link takes O(1) time, forming final tree takes O(max rank) time \rightarrow delete-min takes O(max rank + #links) time Amortize links: let Φ = # half trees One unit of time per link , $\Delta \Phi$ = -1
 - \rightarrow link takes 0 amortized time

make heap, find-min, meld do not change Φ,
insert increases Φ by 1 → each takes O(1)
amortized time
delete-min takes O(#new half trees + max rank)
amortized time

How many new half trees? What is max rank? All rank differences are 1, all leaves have rank 0
 → all half trees are perfect: a half tree of rank r contains exactly 2^r nodes

- \rightarrow #new half trees, max rank $\leq \lg n$
- \rightarrow *delete-min* takes O(lgn) amortized time

Data structure: *lazy binomial queue*.

A perfect half tree of rank 4



What about *decrease-key*?

Add parent pointers to data structure *decrease key*(*x*, *k*, *H*): Remove *x* and its

left subtree (becomes a new half tree). Replace x by its right child. Change key of x to k. Add x to the list of half tree roots. Update the min-root.

But: rank differences are no longer all 1, half trees are no longer perfect, max rank can grow beyond O(lgn)

decrease-key(x, k, H): numbers are ranks





Solution: maintain an invariant on rank differences. Allowed node types are 1,1 (perfect); 1,2; and 0,*j* for any *j* > 1.

At end of *decrease-key* of *x*, set r(x) = r(left(x)) + 1; start from old parent *y* of *x* and walk up path toward root, decreasing ranks to restore the invariant:

while
$$p(y) \neq$$
 null and $r(y)$ too big do
{let y be i,j with $i \leq j$;
if $j - i > 1$ then $r(y) \leftarrow r(y) - i$
else $r(y) \leftarrow r(y) - i + 1$;
 $y \leftarrow p(y)$ };
if $p(y) =$ null then $r(y) = r(left(y)) + 1$

In successive steps, r(y) decreases by a nonincreasing amount







delete(x, H): decrease-key(x, $-\infty$, H); delete-min(H)

delete-min: Delete min-root. Cut edges along
right path down from new root to give new
half-trees. Set rank of each new root = 1 +
rank of left child. Link roots of equal rank until
no two roots have equal rank. Form list of
remaining half trees.

Delete-min: numbers are keys



Delete-min: numbers are ranks







Each link takes O(1) time, forming final tree takes O(max rank) time → delete-min takes O(max rank + #links) time

Data structure: (type-2) rank-pairing heap

Invariant on rank differences \rightarrow max rank is O(lgn)

Amortize rank decrease steps as well as links
 → amortized time of *decrease-key* is O(1),
 other amortized time bounds the same

Half tree height bound

Fibonacci numbers

Golden ratio $\varphi = (1 + \sqrt{5})/2$ $\varphi^2 = \varphi + 1$ $\varphi^k \leq F_{k+2}$

For any non-root x, $s(x) + 1 \ge F_{r(x) + 3}$ For any root x, $s(x) \ge F_{r(x)+2}$ **Proof** for non-roots by induction on h(x): $s(null) + 1 = 0 + 1 = F_2$ $s(\text{leaf}) + 1 = 1 + 1 \ge F_3$ $h(x) > 0: s(x) + 1 = s(left(x)) + 1 + s(right(x)) + 1 \ge 1$ $F_{r(x)+2} + F_{r(x)+1} = F_{r(x)+3}$ if x is 1,1 or 1,2; immediate if x is 0,j

$$n \ge F_{r(x)+2} \ge \varphi^{r(x)} \rightarrow$$
$$r(x) \le \lg_{\varphi} n < 1.44043 \lg_{n} n$$

How to amortize rank decrease steps and links? Such a step must decrease Φ

 $\Phi(x) = i + j + c$ if x is i,j (c any constant) \rightarrow when r(x) decreases by δ , $\Phi(x)$ decreases by 2δ , $\Phi(p(x))$ increases by δ , net change is $-\delta$ A link converts a root to a 1,1 $\rightarrow \Phi(root) > \Phi(x)$ if x is 1,1 Choosing c = -2, $\Phi(root) = 1$ gives $\Phi(x) = 0$ if x 1,1

Almost works!

Problem: 0,2 nodes also have $\Phi = 0$, but such nodes need $\Phi = 1$ when they become roots. Need extra potential.

Only one 1,1 node can decrease in rank during a decrease-key: choose c = −1, give 1,1 nodes potential 0 instead of 1.

$$\Phi(x) = r(x) - r(left(x)) \text{ if root}$$

= 0 if 1,1
= 2r(x) - r(left(x)) - r(right(x)) - 1 otherwise

make-heap ($\Delta \Phi = 0$), find-min ($\Delta \Phi = 0$), insert ($\Delta \Phi = 1$), meld ($\Delta \Phi = 0$) take O(1) amortized time delete-min: Each new root needs one unit of Φ , which it has unless it is a 1,1 node. Only $\lg_{\alpha} n$ 1,1 nodes on a path (at most one per rank) \rightarrow creation of new half trees increases Φ by at most $\lg_{\omega} n$ Each link takes 0 amortized time \rightarrow delete-min takes O(lgn) amortized time

decrease-key: Creating new subtree takes O(1) amortized time ($\Delta \Phi \le 2$). Each rank decrease step reduces Φ unless it is of a 1,1 node. Only one 1,1 node can decrease in rank: can only decrease by 1, previous decrease must be by at least 2

 \rightarrow *decrease-key* takes O(1) amortized time

Variants

Can strengthen or weaken rank invariant: Stronger: nodes are 1,1 or 0,*j* for *j* > 0 *type-1 rank-pairing heap* Weaker: nodes are 1,1; 1,2; 1,3; or 0,*j* for *j* > 2 *type-3 rank-pairing heap* **Type 1**: smaller height bound but more complicated amortized analysis, worse constant factors, seems to require a special linking order in *delete-min*

- Type 2: the sweet spot
- Type 3: simpler amortized analysis (Φ(non-root) = sum of rank differences of children – 2) but bigger height bound

Why care about fast decrease-key?

Dijkstra's shortest path algorithm: coming up!