

# Norms and Inner Products

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# Concrete vs. Abstract

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## More Concrete

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Matrices

Rank of a matrix

Full-rank matrices

Gaussian elimination

## More Abstract

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Linear mappings

Dimension of the image of a map

Injective (one-to-one) linear maps

When do systems have solutions

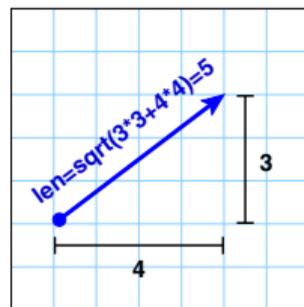
# Concrete vs. Abstract

<b>More Concrete</b>	<b>More Abstract</b>
Matrices Rank of a matrix Full-rank matrices Gaussian elimination	Linear mappings Dimension of the image of a map Injective (one-to-one) linear maps When do systems have solutions
Euclidean distance in $\mathbb{R}^n$ Dot products	General norms General inner products

## In Euclidean Space...

Length of a vector  $\mathbf{x}$ :  $\|\mathbf{x}\| = \sqrt{\sum_i x_i^2}$

Distance between vectors  $\mathbf{x}$  and  $\mathbf{y}$ :  $\|\mathbf{x} - \mathbf{y}\| = \sqrt{\sum_i (x_i - y_i)^2}$



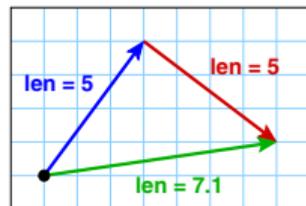
These let us talk about lengths and distances in  $\mathbb{R}^n$ .

Dot product between vectors  $\mathbf{x}$  and  $\mathbf{y}$ :  $\mathbf{x} \cdot \mathbf{y} = \sum_i x_i y_i$

This lets us talk about angles and perpendicularity (orthogonality).

# Properties of Euclidean Length

- Real-valued function on vectors
- “Positive definite”:
  - Non-negative:  $\|\mathbf{x}\| \geq 0$
  - Positive except for  $\mathbf{0}$  vector
- Absolutely homogeneous:  $\|\lambda\mathbf{x}\| = |\lambda| \|\mathbf{x}\|$
- Obeys triangle inequality:  $\|\mathbf{x} + \mathbf{y}\| \leq \|\mathbf{x}\| + \|\mathbf{y}\|$
- Induces a distance metric between vectors:  $d(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\|$



All of these can apply to more general notions of “length.”

# Properties of Dot Product

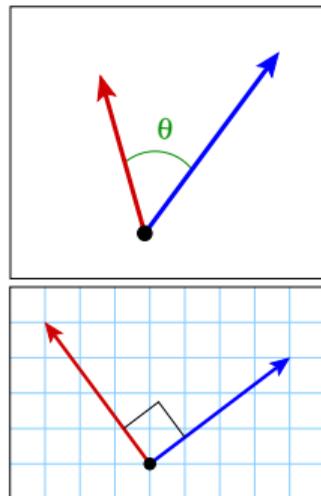
- Real-valued function on *pairs* of vectors
- Symmetric:  $\mathbf{x} \cdot \mathbf{y} = \mathbf{y} \cdot \mathbf{x}$
- Bilinear:  $(\lambda\mathbf{x} + \psi\mathbf{y}) \cdot \mathbf{z} = \lambda(\mathbf{x} \cdot \mathbf{z}) + \psi(\mathbf{y} \cdot \mathbf{z})$   
 $\mathbf{x} \cdot (\lambda\mathbf{y} + \psi\mathbf{z}) = \lambda(\mathbf{x} \cdot \mathbf{y}) + \psi(\mathbf{x} \cdot \mathbf{z})$
- Positive definite:  $\mathbf{x} \cdot \mathbf{x} > 0$  unless  $\mathbf{x} = \mathbf{0}$
- Induces a norm (in this case, standard Euclidean norm):  $\|\mathbf{x}\| = \sqrt{\mathbf{x} \cdot \mathbf{x}}$

All of these can apply to more general notions of “product.”

# More Properties of Dot Product

Before we generalize, two more properties:

- Relation to matrix product:  $\mathbf{x} \cdot \mathbf{y} = \mathbf{x}^T \mathbf{y} = \mathbf{y}^T \mathbf{x}$ ,  
and so  $\|\mathbf{x}\| = \sqrt{\mathbf{x}^T \mathbf{x}}$
- Relation to angles:  $\mathbf{x} \cdot \mathbf{y} = \|\mathbf{x}\| \|\mathbf{y}\| \cos \theta$ 
  - Important special case: for nonzero  $\mathbf{x}$ ,  $\mathbf{y}$ ,  
 $\mathbf{x} \cdot \mathbf{y} = 0$  iff  $\mathbf{x}$  and  $\mathbf{y}$  are perpendicular



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Suppose you apply a linear mapping to both vectors, then take a dot product in the new space.

- Will this be the same as the original dot product?

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- Will this always produce a “valid” dot product?

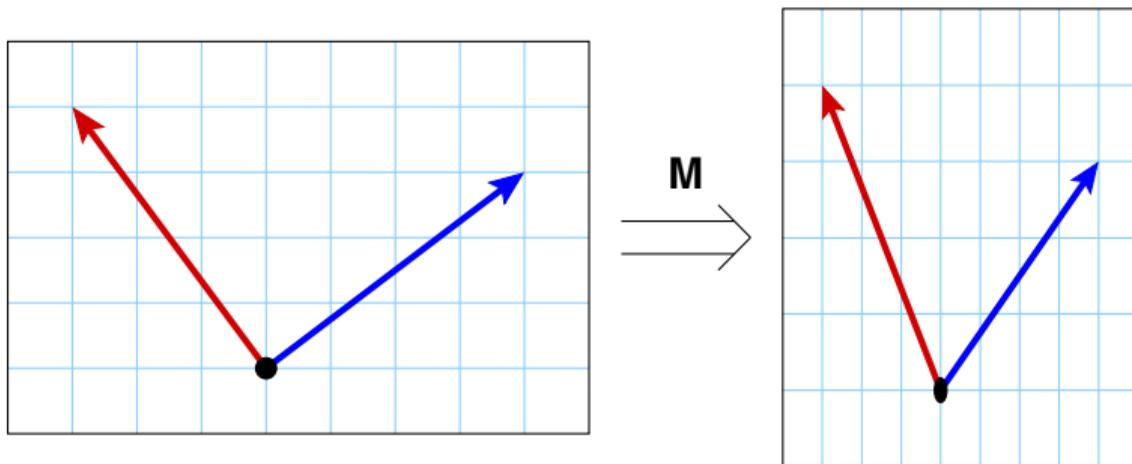
# Generalizing Dot Product: Inner Product

Suppose you apply a linear mapping to both vectors, then take a dot product in the new space.

- Will this be the same as the original dot product? **No.**
- Will this always produce a “valid” dot product? **No.**
  - For positive definiteness, need the linear mapping *not* to collapse dimensions

# Generalizing Dot Product: Inner Product

Suppose you apply an **injective** linear mapping to both vectors, then take a dot product in the new space.

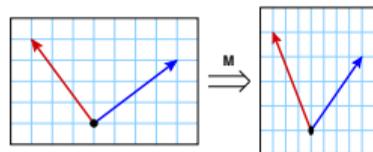


# Generalizing Dot Product: Inner Product

Suppose you apply a **injective** linear mapping to both vectors, then take a dot product in the new space.

Let the transformation be representable by matrix  $M$ .

New inner product  $\langle \mathbf{x}, \mathbf{y} \rangle = (M\mathbf{x})^\top (M\mathbf{y}) = \mathbf{x}^\top M^\top M \mathbf{y} = \mathbf{x}^\top \mathbf{A} \mathbf{y}$ , where the matrix  $\mathbf{A}$  is square, symmetric, and *positive definite*.



## Aside: Quadratic Forms

You'll often see notation such as  $\mathbf{x}^T \mathbf{A} \mathbf{x}$ , with square and symmetric  $\mathbf{A}$ . This is a *quadratic form*: a second-order polynomial in the elements of  $\mathbf{x}$ :

Let  $\mathbf{x} = (x_1, x_2, x_3, \dots)$ . Then,

$$\mathbf{x}^T \mathbf{A} \mathbf{x} = ax_1^2 + bx_1x_2 + cx_2^2 + dx_1x_3 + ex_2x_3 + fx_3^2 + \dots$$

Also: a *bilinear form*  $\mathbf{x}^T \mathbf{A} \mathbf{y}$  is a function from two vectors to a scalar that is linear in both  $\mathbf{x}$  and  $\mathbf{y}$ .

# Generalizing Dot Product: Inner Product

The generalized inner product, applied to the same vector twice, gives

$$\langle \mathbf{x}, \mathbf{x} \rangle_A = \mathbf{x}^\top \mathbf{A} \mathbf{x}$$

for some square, symmetric  $\mathbf{A}$ .

- If  $\mathbf{A}$  is diagonal, then we just have scaled versions of  $x_1^2$ ,  $x_2^2$ , etc.
  - Application: the “weight” or “importance” of each dimension is different.
- If  $\mathbf{A}$  is not diagonal, also have “mixed” quadratic terms:  $x_1x_2$ ,  $x_2x_3$ , etc.
  - Application: accounting for “correlation” between dimensions.

**Example:**  $\mathbf{A} = \begin{bmatrix} 1 & -1/2 \\ -1/2 & 1 \end{bmatrix}$ , so  $\mathbf{x}^\top \mathbf{A} \mathbf{x} = x_1^2 + x_2^2 - x_1x_2$ .

The norm induced by this inner product *downweights* correlation in  $x_1$  and  $x_2$ .

# Generalizing Dot Product: Inner Product

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for some square, symmetric  $\mathbf{A}$ .

- But we know that this has to be  $> 0$  (unless  $\mathbf{x}$  is the  $\mathbf{0}$  vector), because it came from a dot product in some (transformed) space.
- So we say that  $\mathbf{A}$  is “symmetric positive definite” or SPD.
- Key duality between SPD matrices, generalized inner products, and norms on linearly-transformed vector spaces.
  - $\mathbf{A}$  is SPD iff it can be written as  $\mathbf{A} = \mathbf{M}^\top \mathbf{M}$

## Generalizing Norm: $L^p$ Spaces

Not all norms come from inner products. We can have vector spaces with *valid norms* but *no well-defined inner products*.

Most important example:  $\ell_p$  norm

$$\|\mathbf{x}\|_p = \left( \sum_i |x_i|^p \right)^{1/p}$$

for  $p \geq 1$ . (For  $p < 1$ , does not satisfy triangle inequality, so not a valid norm.)

# Generalizing Norm: $L^p$ Spaces

$$\|\mathbf{x}\|_p = \left( \sum_i |x_i|^p \right)^{1/p}$$

- $p = 2$ : Good ol' Euclidean norm.
- $p = 1$ : Manhattan or taxicab norm.  
 $\|\mathbf{x}\|_1 = \sum_i |x_i| =$  sum of **North-South** and **East-West** distances, when restricted to city-block grid. Often used in *robust estimation*.
- $p = \infty$ : Infinity norm or *max* norm.

$$\|\mathbf{x}\|_\infty = \max_i |x_i|$$

