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## 4.2 DIRECTED GRAPHS

---

- ▶ *introduction*
- ▶ *digraph API*
- ▶ *depth-first search*
- ▶ *breadth-first search*
- ▶ *topological sort*
- ▶ *strong components* ← see videos



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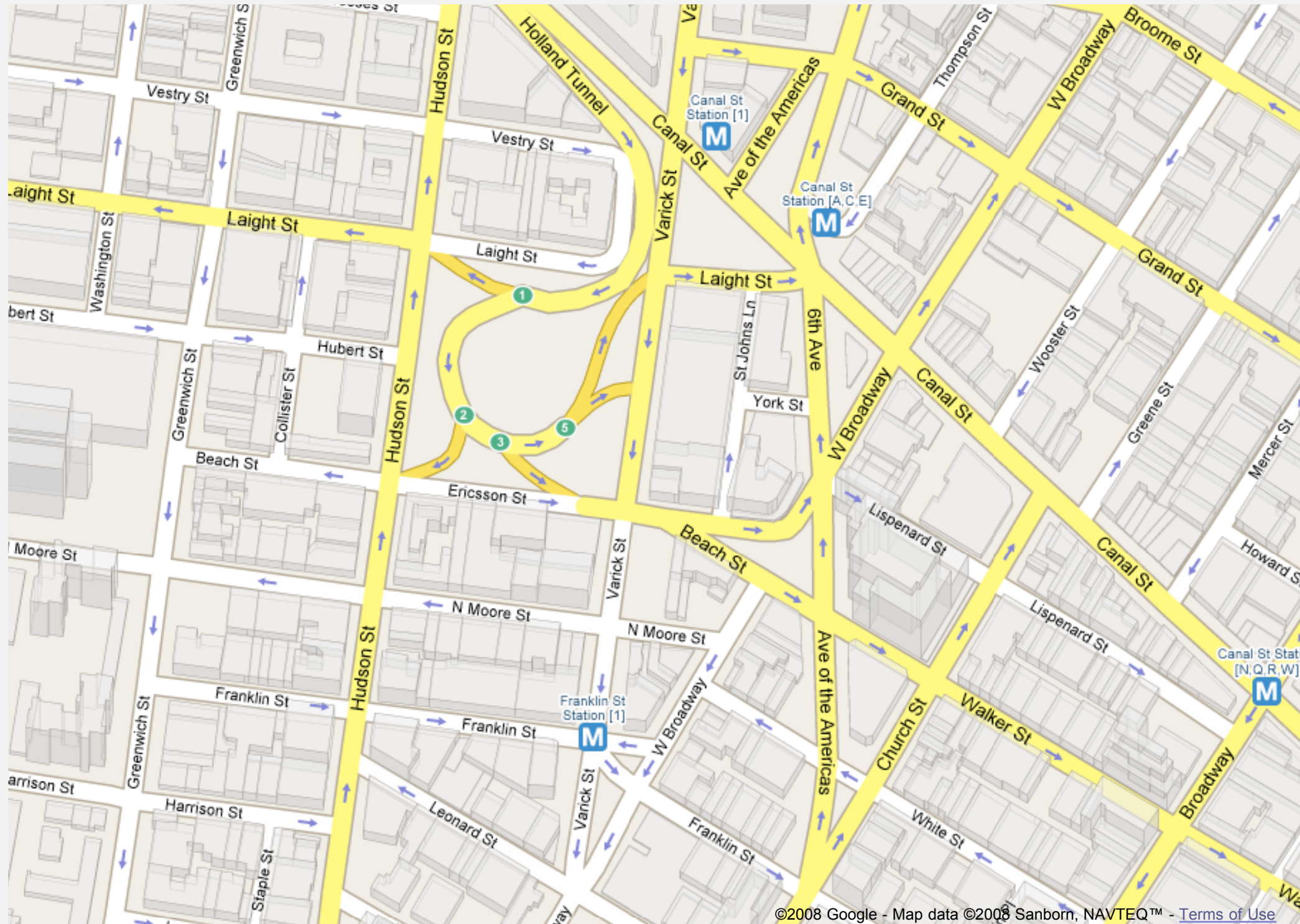
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# Road networks

Vertex = intersection; edge = one-way street.



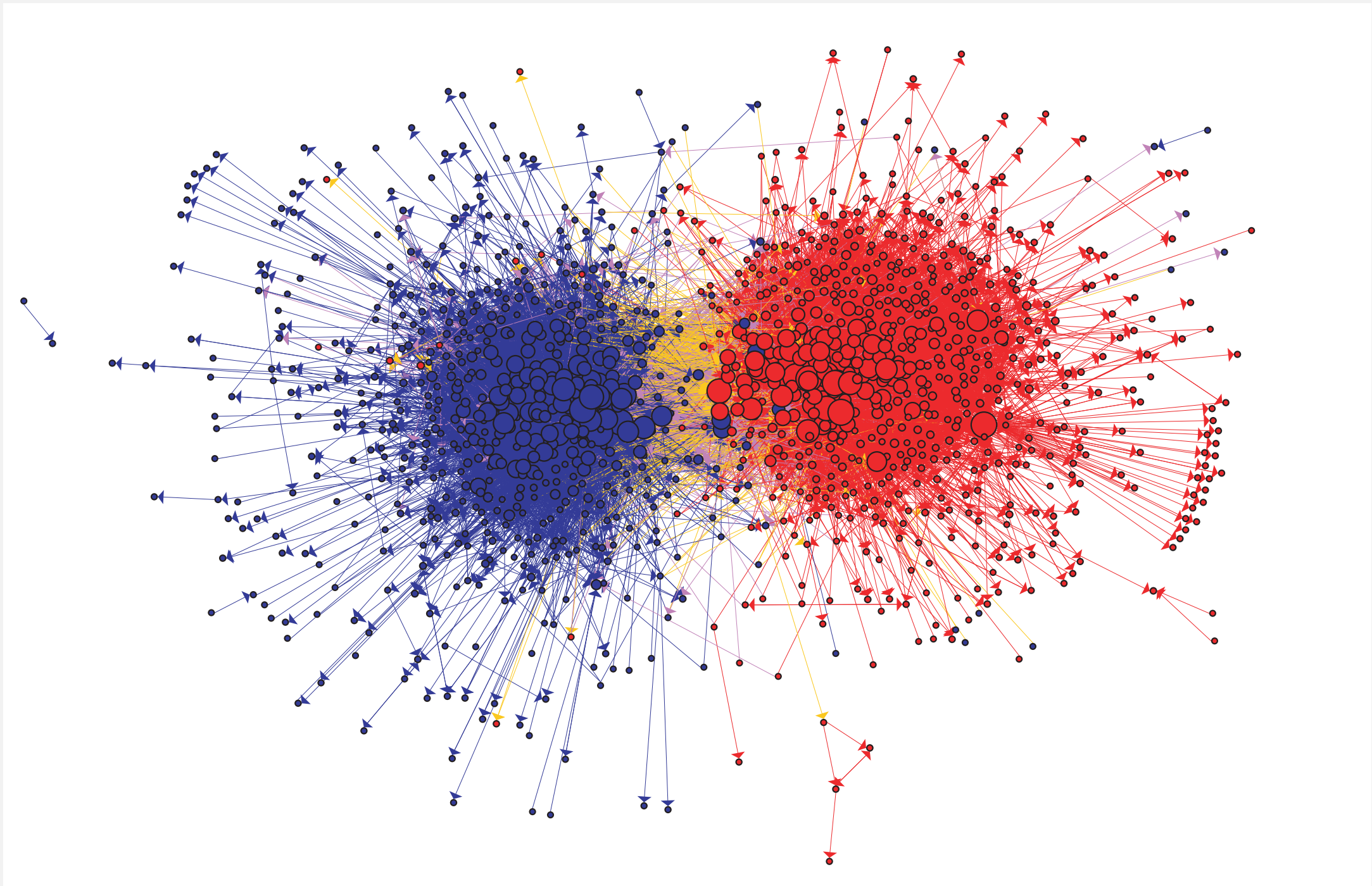
©2008 Google - Map data ©2008 Sanborn, NAVTEQ™ - [Terms of Use](#)



# Political blogosphere links

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Vertex = political blog; edge = link.

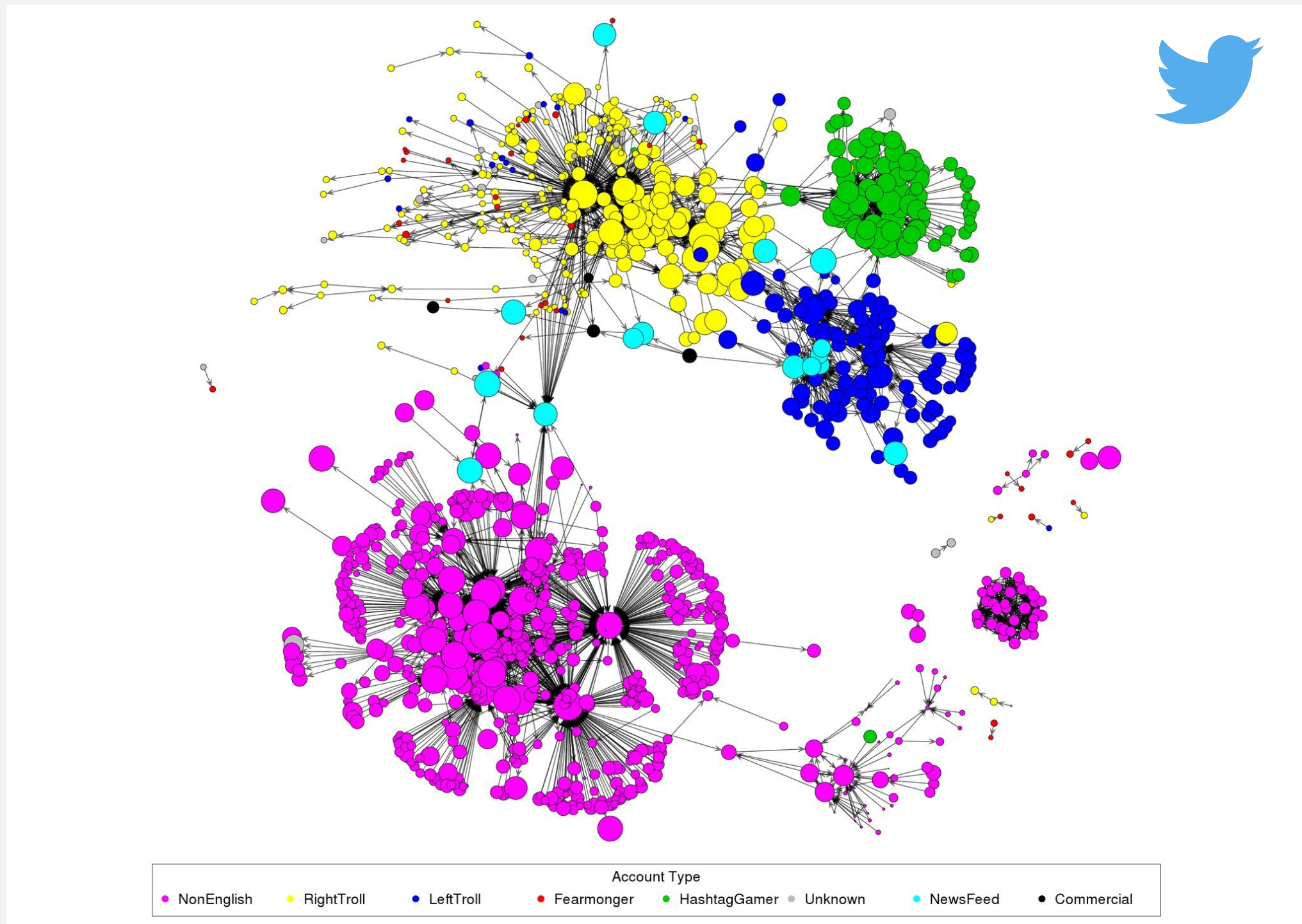


**The Political Blogosphere and the 2004 U.S. Election: Divided They Blog, Adamic and Glance, 2005**



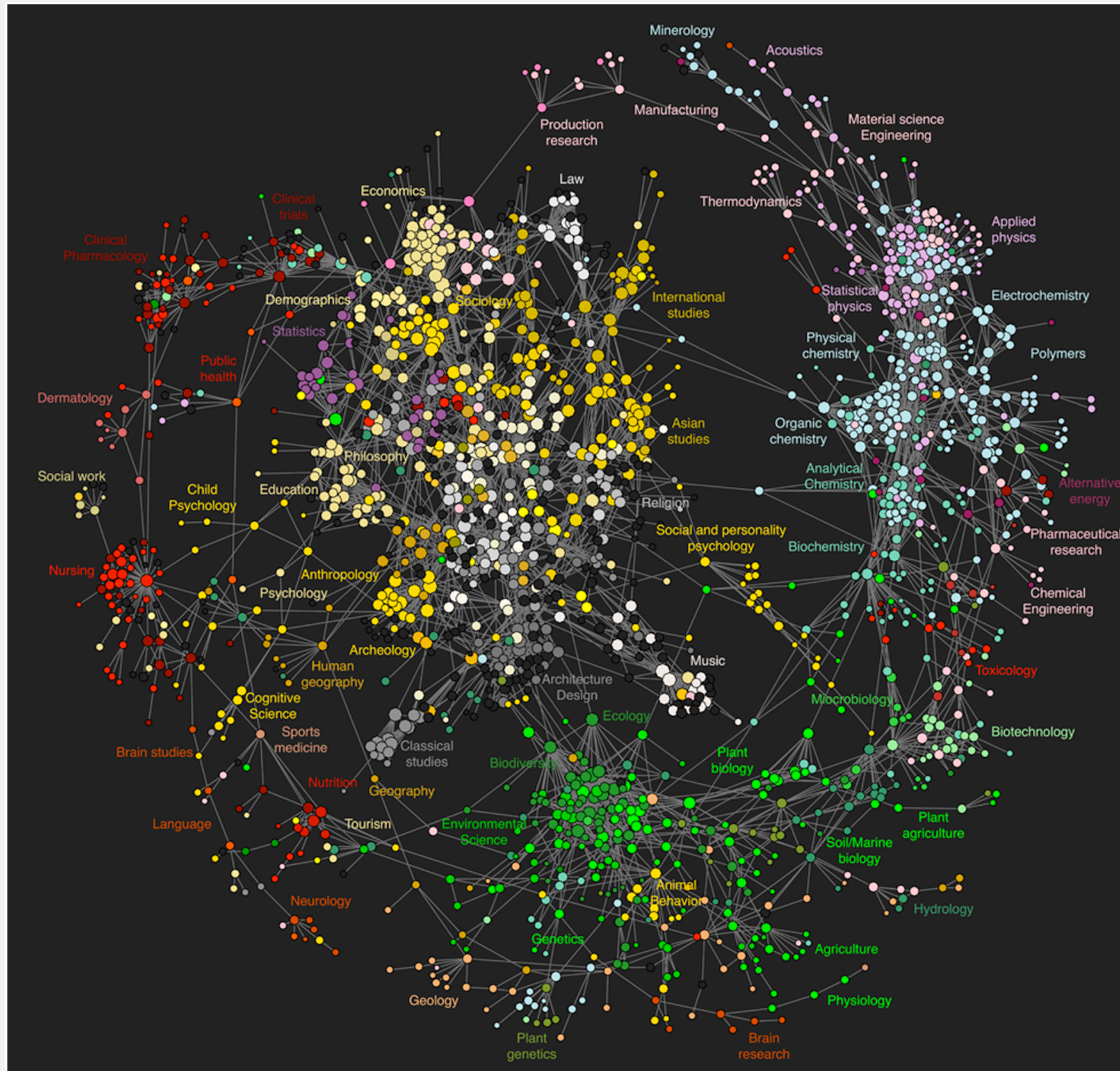
# Russian troll network

Vertex = Russian troll; edge = Twitter mention.



Russian Troll-to-Russian Troll Twitter Mention Network, [fivethirtyeight.com](http://fivethirtyeight.com)

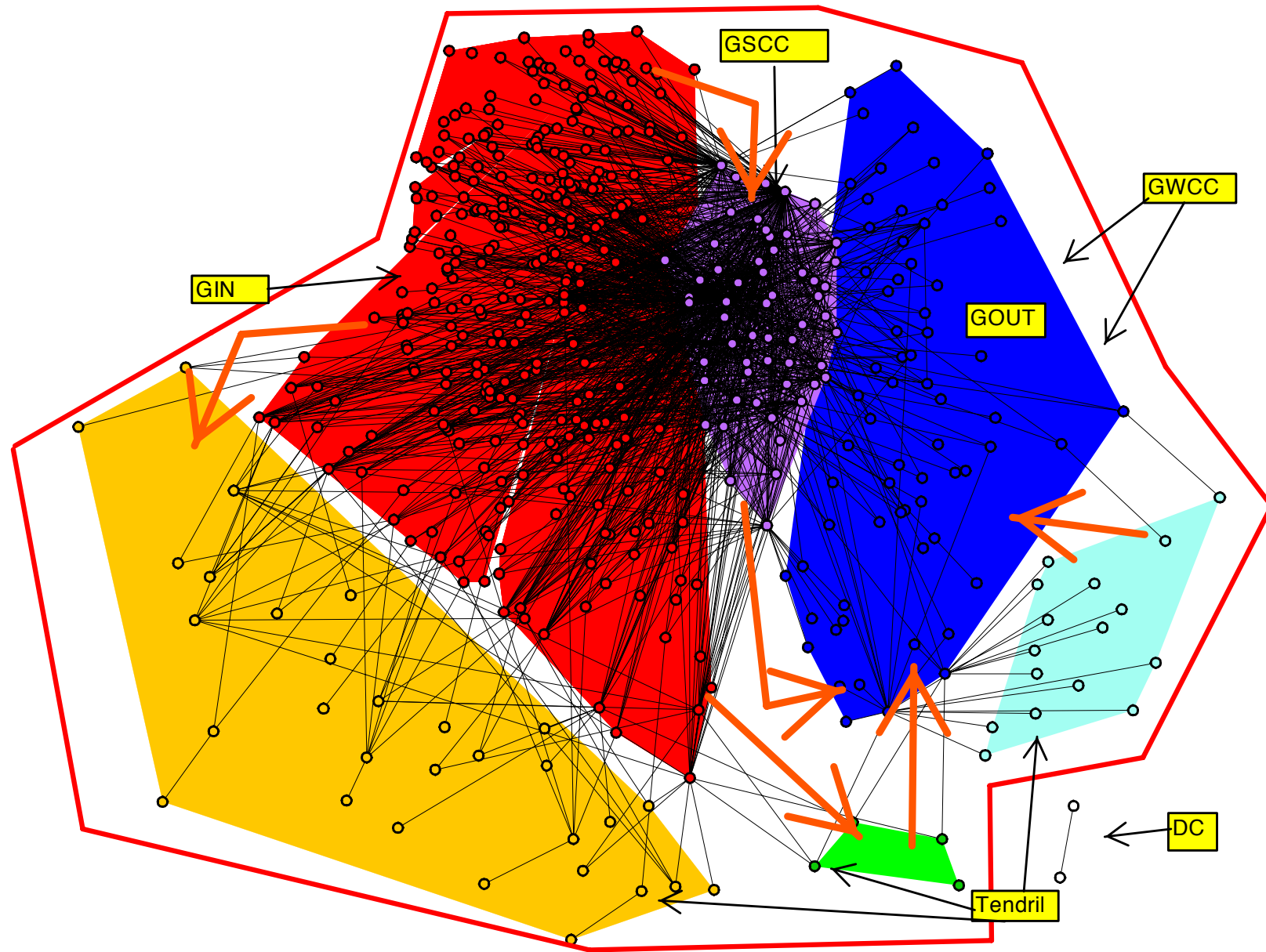
# Science clickstreams





# Overnight interbank loans

Vertex = bank; edge = overnight loan.

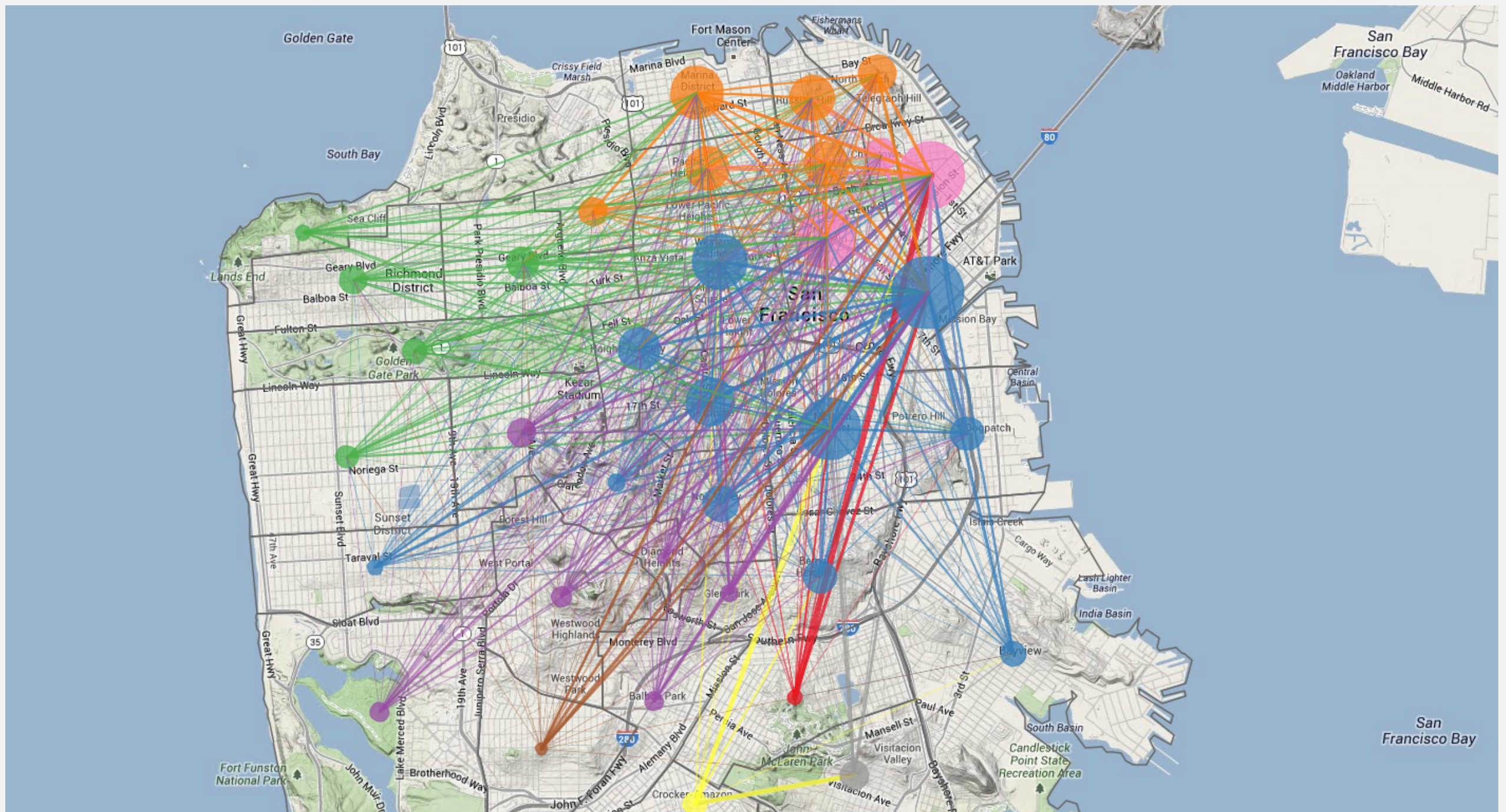


The Topology of the Federal Funds Market, Bech and Atalay, 2008



# Uber rides

Vertex = taxi pickup; edge = taxi ride.



<http://blog.uber.com/2012/01/09/uberdata-san-franciscocomics>

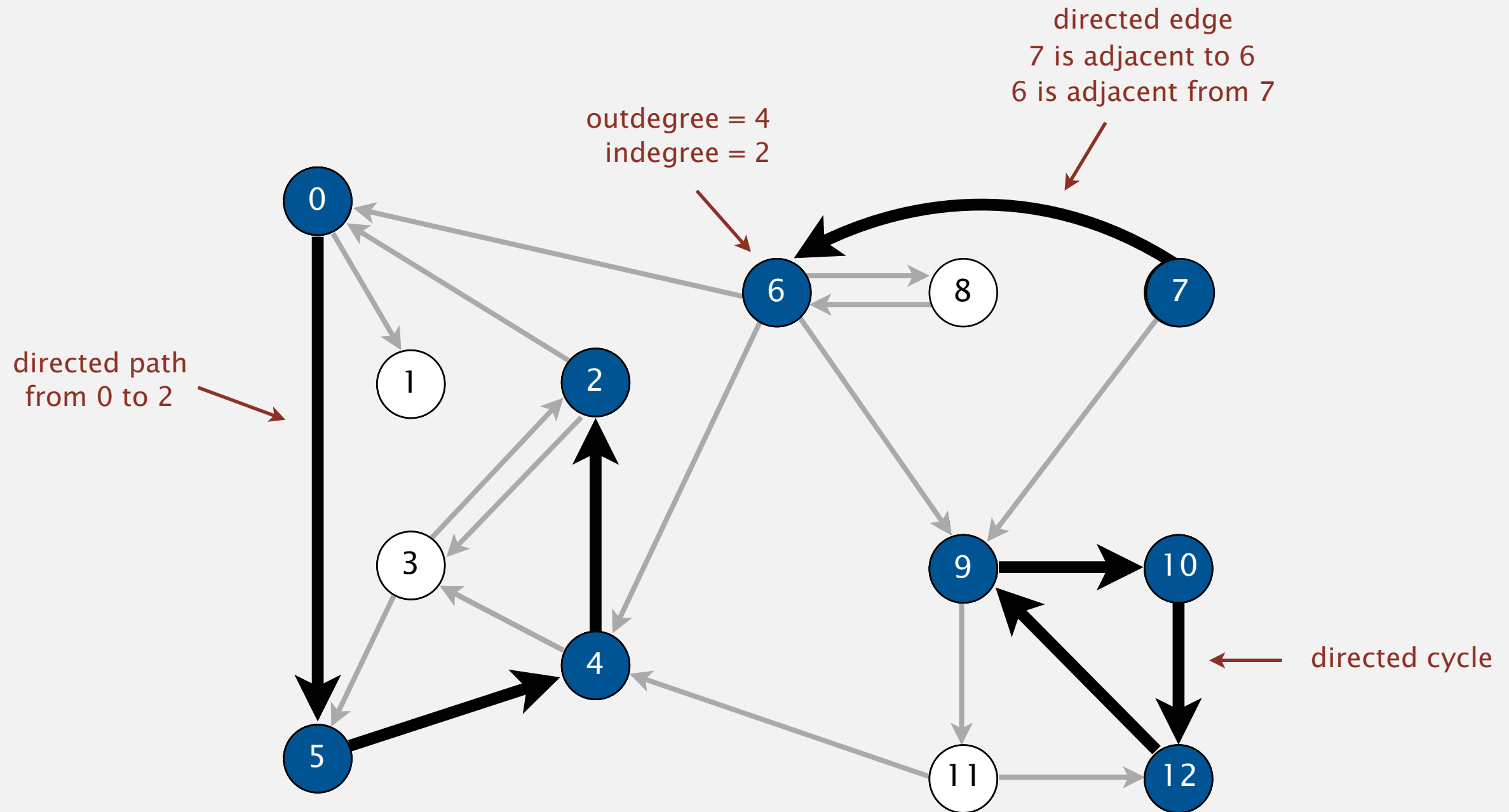
# Digraph applications

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<b>digraph</b>	<b>vertex</b>	<b>directed edge</b>
<b>transportation</b>	street intersection	one-way street
<b>web</b>	web page	hyperlink
<b>food web</b>	species	predator–prey relationship
<b>WordNet</b>	synset	hypernym
<b>scheduling</b>	task	precedence constraint
<b>financial</b>	bank	transaction
<b>cell phone</b>	person	placed call
<b>infectious disease</b>	person	infection
<b>game</b>	board position	legal move
<b>citation</b>	journal article	citation
<b>object graph</b>	object	pointer
<b>inheritance hierarchy</b>	class	inherits from
<b>control flow</b>	code block	jump

# Directed graph terminology

**Digraph.** Set of vertices connected pairwise by **directed** edges.





# Some digraph problems

---

problem	description
<b><math>s \rightarrow t</math> path</b>	<i>Is there a path from <math>s</math> to <math>t</math> ?</i>
<b>shortest <math>s \rightarrow t</math> path</b>	<i>What is the shortest path from <math>s</math> to <math>t</math> ?</i>
<b>directed cycle</b>	<i>Is there a directed cycle in the graph ?</i>
<b>topological sort</b>	<i>Can the digraph be drawn so that all edges point upwards?</i>
<b>strong connectivity</b>	<i>Is there a directed path between every pairs of vertices ?</i>
<b>transitive closure</b>	<i>For which vertices <math>v</math> and <math>w</math> is there a directed path from <math>v</math> to <math>w</math> ?</i>
<b>PageRank</b>	<i>What is the importance of a web page ?</i>



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# Digraph API

---

Almost identical to Graph API.

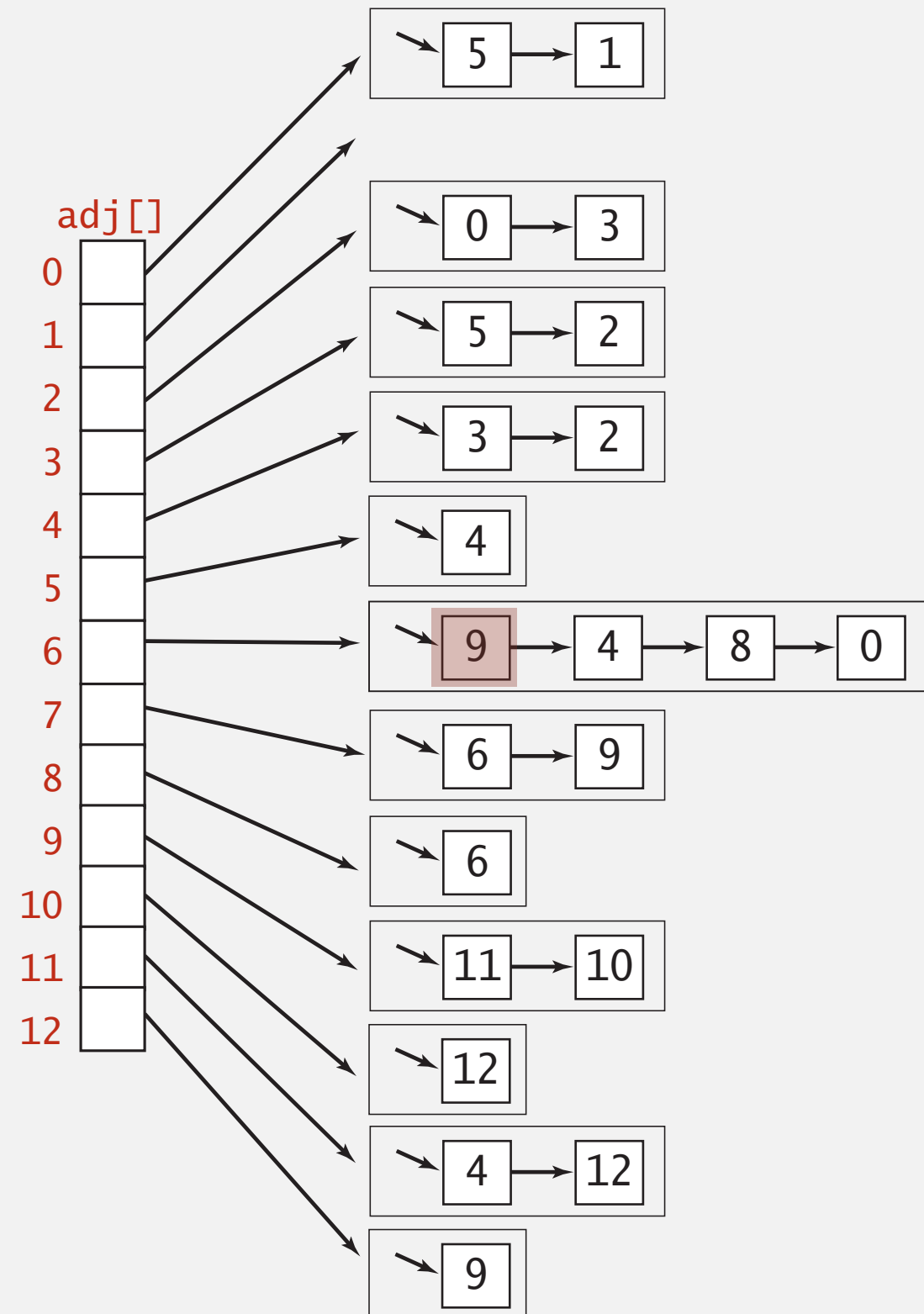
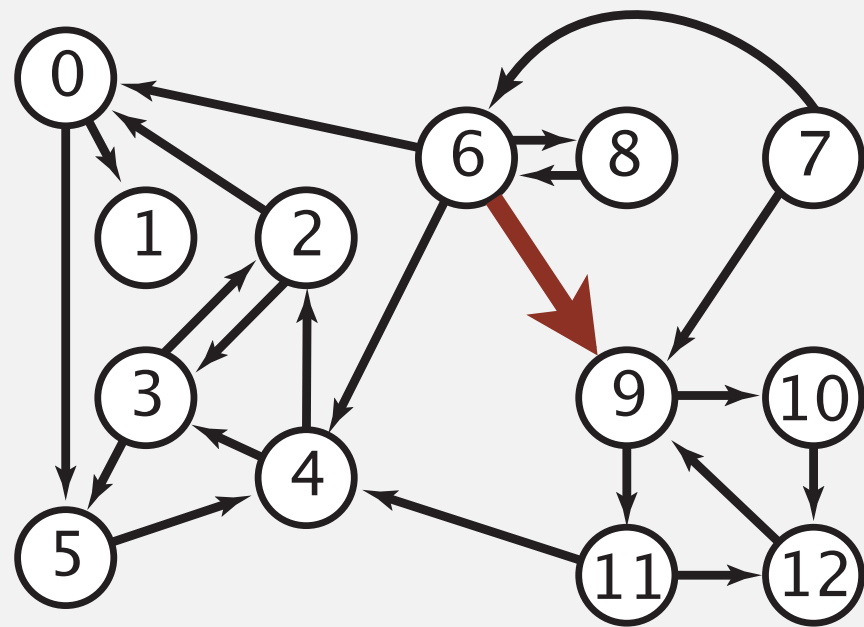
```
public class Digraph
```

<code>Digraph(int V)</code>	<i>create an empty digraph with <math>V</math> vertices</i>
<code>void addEdge(int v, int w)</code>	<i>add a directed edge <math>v \rightarrow w</math></i>
<code>Iterable&lt;Integer&gt; adj(int v)</code>	<i>vertices adjacent from <math>v</math></i>
<code>int V()</code>	<i>number of vertices</i>
<code>int E()</code>	<i>number of edges</i>
<code>Digraph reverse()</code>	<i>reverse of this digraph</i>



# Digraph representation: adjacency lists

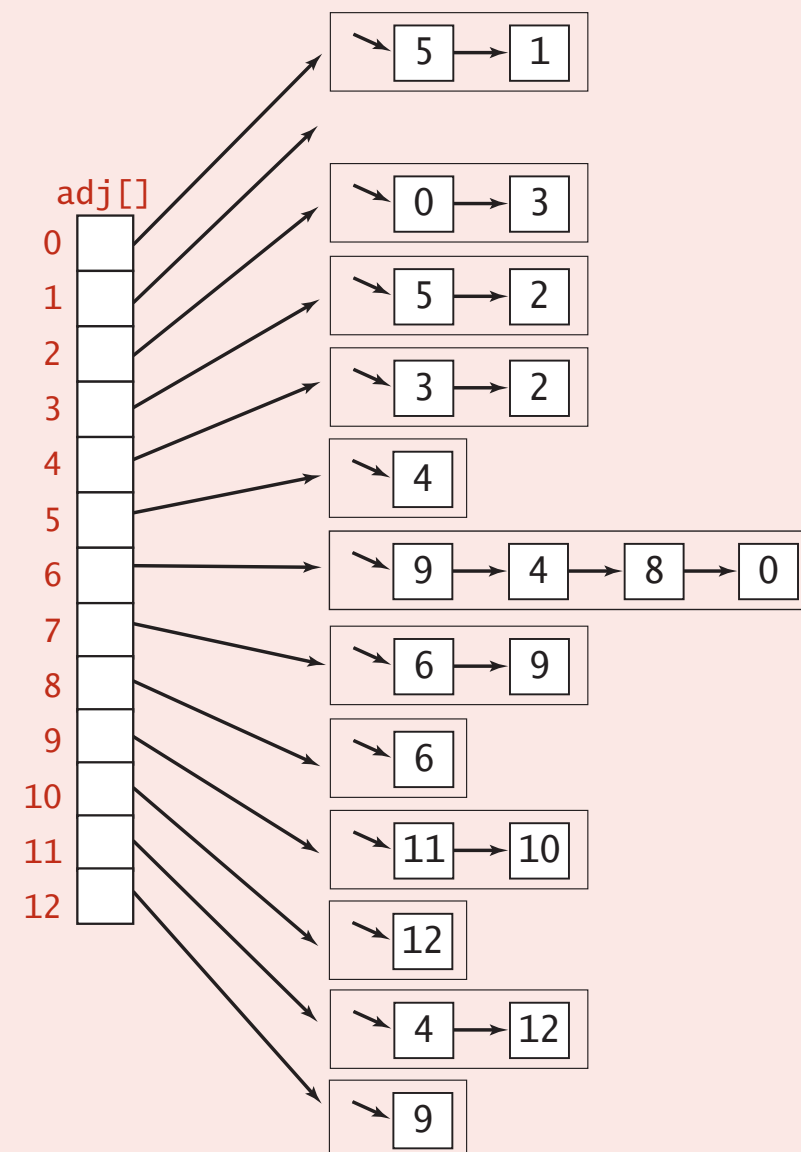
Maintain vertex-indexed array of lists.





Which is the order of growth of the running time for removing an edge  $v \rightarrow w$  from a digraph using the **adjacency-lists** representation, where  $V$  is the number of vertices and  $E$  is the number of edges?

- A. 1
- B.  $outdegree(v)$
- C.  $indegree(w)$
- D.  $outdegree(v) + indegree(w)$





Which is the order of growth of the running time of the following code fragment if the digraph uses the **adjacency-lists** representation, where  $V$  is the number of vertices and  $E$  is the number of edges?

- A.  $V$
- B.  $E + V$
- C.  $V^2$
- D.  $VE$

```
for (int v = 0; v < G.V(); v++)  
    for (int w : G.adj(v))  
        StdOut.println(v + "->" + w);
```

prints each edge exactly once



# Digraph representations

**In practice.** Use adjacency-lists representation.

- Algorithms based on iterating over vertices adjacent from  $v$ .
- Real-world graphs tend to be **sparse** (not **dense**).

↑  
proportional  
to  $V$  edges

↑  
proportional  
to  $V^2$  edges

representation	space	insert edge from $v$ to $w$	edge from $v$ to $w$ ?	iterate over vertices adjacent from $v$ ?
list of edges	$E$	1	$E$	$E$
adjacency matrix	$V^2$	1 †	1	$V$
adjacency lists	$E + V$	1	$outdegree(v)$	$outdegree(v)$

† disallows parallel edges

# Adjacency-lists graph representation (review): Java implementation

```
public class Graph  
{
```

```
    private final int V;  
    private Bag<Integer>[] adj;
```

← adjacency lists

```
    public Graph(int V)
```

```
    {  
        this.V = V;  
        adj = (Bag<Integer>[]) new Bag[V];  
        for (int v = 0; v < V; v++)  
            adj[v] = new Bag<Integer>();  
    }
```

← create empty graph  
with V vertices

```
    public void addEdge(int v, int w)
```

```
    {  
        adj[v].add(w);  
        adj[w].add(v);  
    }
```

← add edge v-w

```
    public Iterable<Integer> adj(int v)
```

```
    { return adj[v]; }
```

← iterator for vertices  
adjacent to v

```
}
```

# Adjacency-lists digraph representation: Java implementation

```
public class Digraph
```

```
{
```

```
    private final int V;  
    private Bag<Integer>[] adj;
```

← adjacency lists

```
    public Digraph(int V)
```

```
    {
```

```
        this.V = V;
```

```
        adj = (Bag<Integer>[]) new Bag[V];
```

```
        for (int v = 0; v < V; v++)
```

```
            adj[v] = new Bag<Integer>();
```

```
    }
```

← create empty digraph  
with V vertices

```
    public void addEdge(int v, int w)
```

```
    {
```

```
        adj[v].add(w);
```

```
    }
```

← add edge v→w

```
    public Iterable<Integer> adj(int v)
```

```
    { return adj[v]; }
```

← iterator for vertices  
adjacent from v

```
}
```





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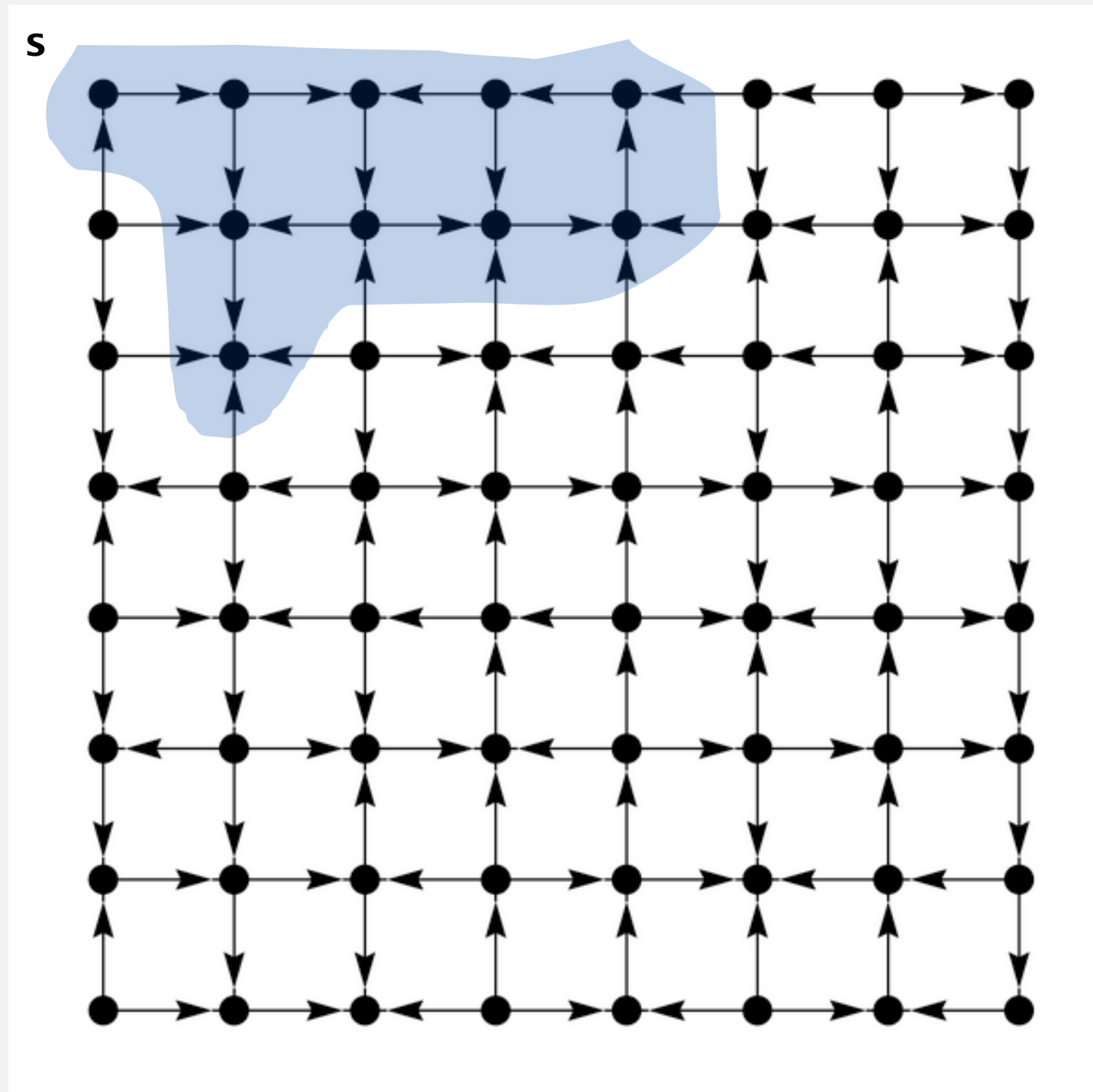
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- ▶ *introduction*
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- ▶ *breadth-first search*
- ▶ *topological sort*

# Reachability

---

**Problem.** Find all vertices reachable from  $s$  along a directed path.



# Depth-first search in digraphs

---

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- DFS is a **digraph** algorithm.

**DFS** (to visit a vertex  $v$ )

---

Mark vertex  $v$ .

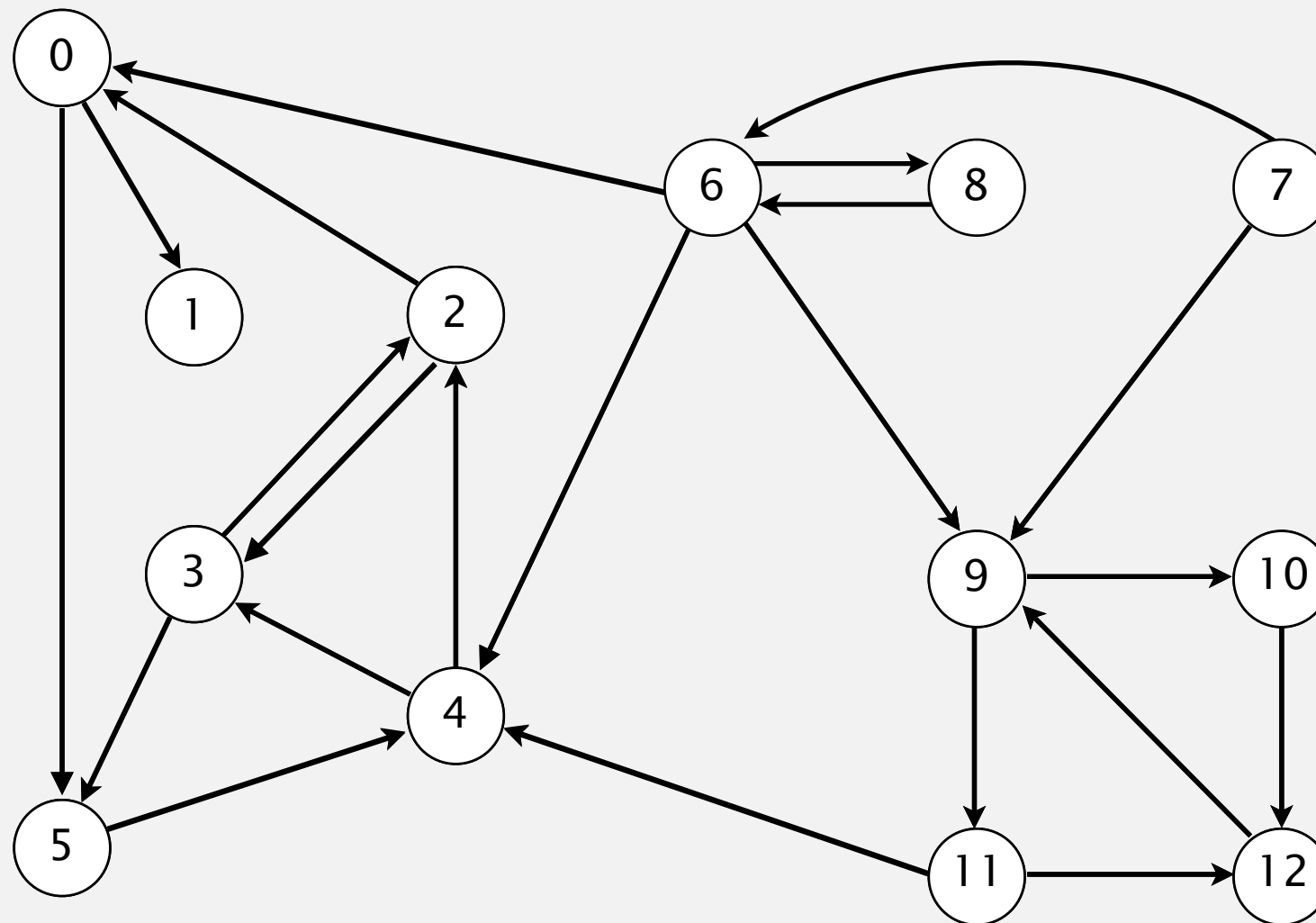
Recursively visit all unmarked  
vertices  $w$  adjacent from  $v$ .

---

# Depth-first search demo

To visit a vertex  $v$ :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices adjacent from  $v$ .



a directed graph

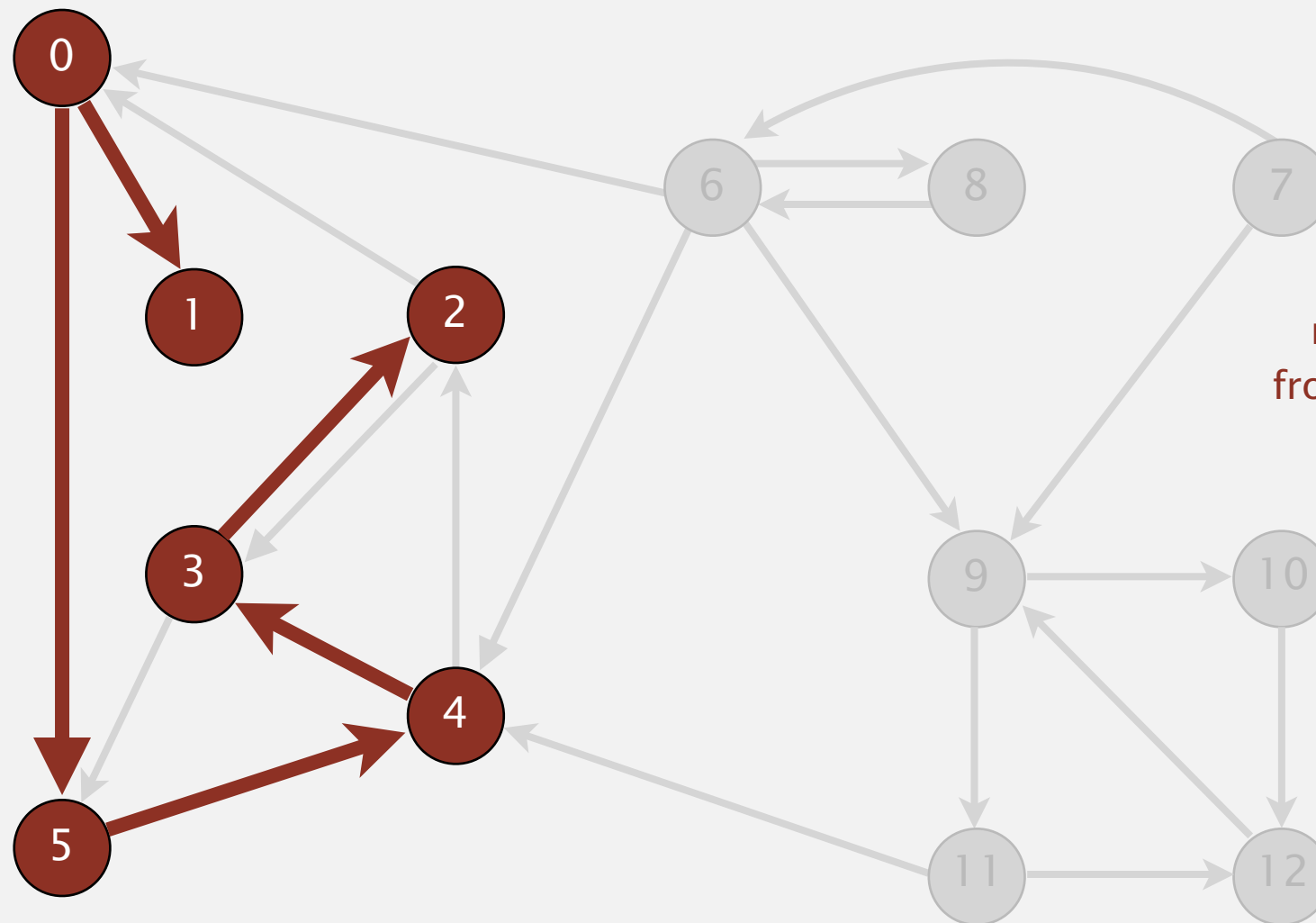
4→2  
2→3  
3→2  
6→0  
0→1  
2→0  
11→12  
12→9  
9→10  
9→11  
8→9  
10→12  
11→4  
4→3  
3→5  
6→8  
8→6  
5→4  
0→5  
6→4  
6→9  
7→6



# Depth-first search demo

To visit a vertex  $v$  :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices adjacent from  $v$ .



v	marked[]	edgeTo[]
0	T	—
1	T	0
2	T	3
3	T	4
4	T	5
5	T	0
6	F	—
7	F	—
8	F	—
9	F	—
10	F	—
11	F	—
12	F	—

reachable from 0

# Depth-first search (in undirected graphs)

---

Recall code for **undirected** graphs.

```
public class DepthFirstSearch  
{
```

```
    private boolean[] marked;
```

← true if connected to s

```
    public DepthFirstSearch(Graph G, int s)  
    {  
        marked = new boolean[G.V()];  
        dfs(G, s);  
    }
```

← constructor marks  
vertices connected to s

```
    private void dfs(Graph G, int v)  
    {  
        marked[v] = true;  
        for (int w : G.adj(v))  
            if (!marked[w])  
                dfs(G, w);  
    }
```

← recursive DFS does the work

```
    public boolean visited(int v)  
    { return marked[v]; }
```

← client can ask whether any  
vertex v is connected to s

```
}
```

# Depth-first search (in directed graphs)

---

Code for **directed** graphs identical to undirected one.

```
public class DirectedDFS  
{
```

```
    private boolean[] marked;
```

← true if connected to s

```
    public DirectedDFS(Digraph G, int s)  
    {  
        marked = new boolean[G.V()];  
        dfs(G, s);  
    }
```

← constructor marks  
vertices connected to s

```
    private void dfs(Digraph G, int v)  
    {  
        marked[v] = true;  
        for (int w : G.adj(v))  
            if (!marked[w])  
                dfs(G, w);  
    }
```

← recursive DFS does the work

```
    public boolean visited(int v)  
    { return marked[v]; }
```

← client can ask whether  
vertex v is reachable from s

```
}
```

# Reachability application: program control-flow analysis

Every program is a digraph.

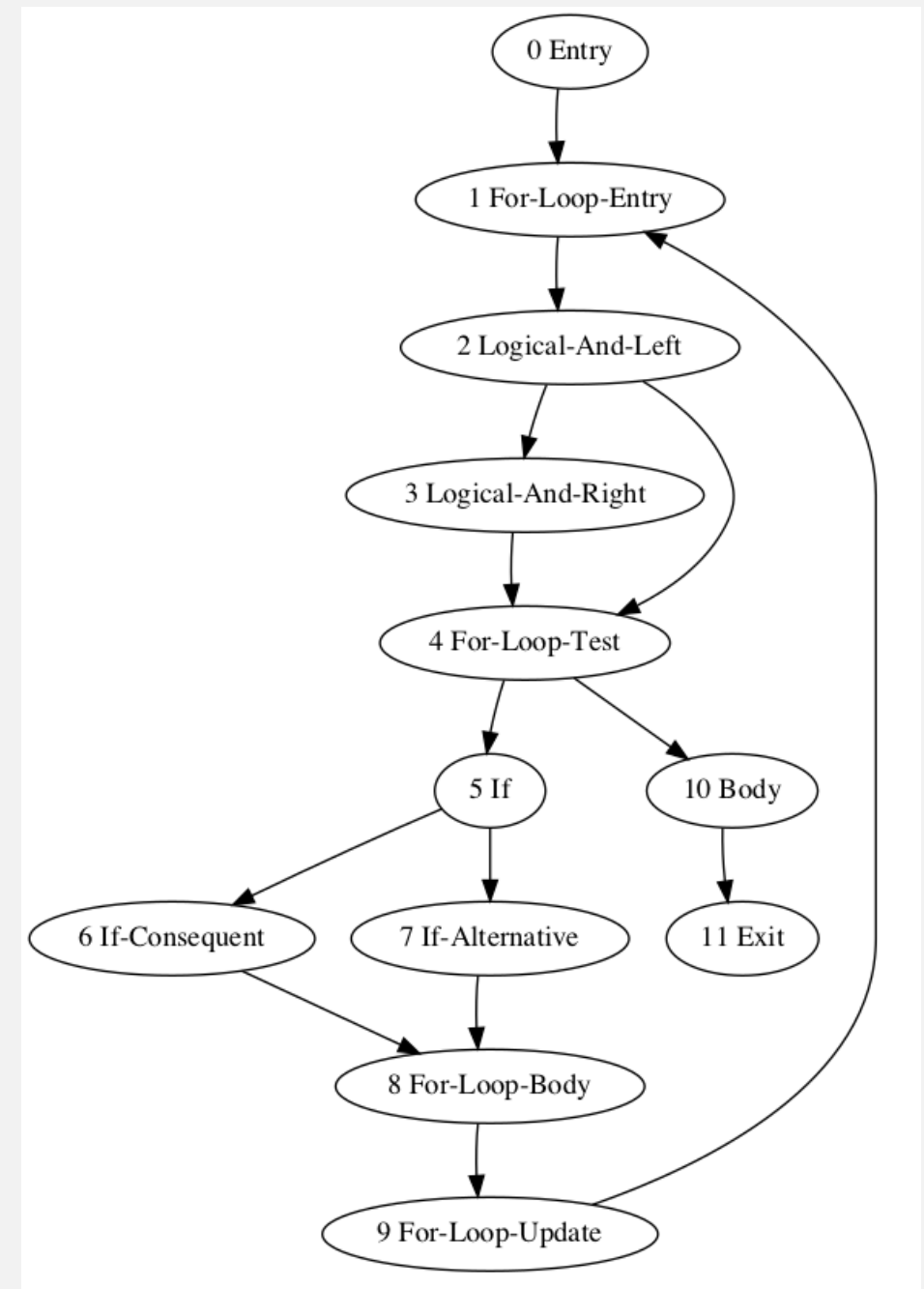
- Vertex = basic block of instructions (straight-line program).
- Edge = jump.

Dead-code elimination.

Find (and remove) unreachable code.

Infinite-loop detection.

Determine whether exit is unreachable.





# Reachability application: mark-sweep garbage collector

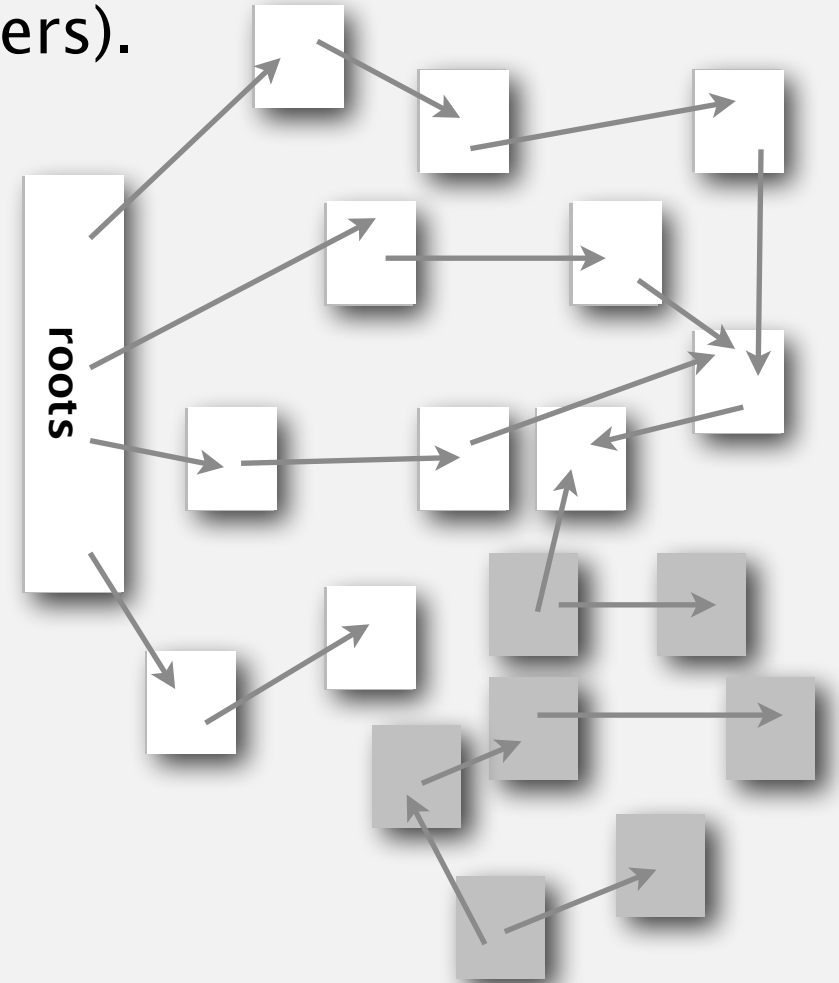
---

Every data structure is a digraph.

- Vertex = object.
- Edge = reference.

**Roots.** Objects known to be directly accessible by program (e.g., stack).

**Reachable objects.** Objects indirectly accessible by program (starting at a root and following a chain of pointers).



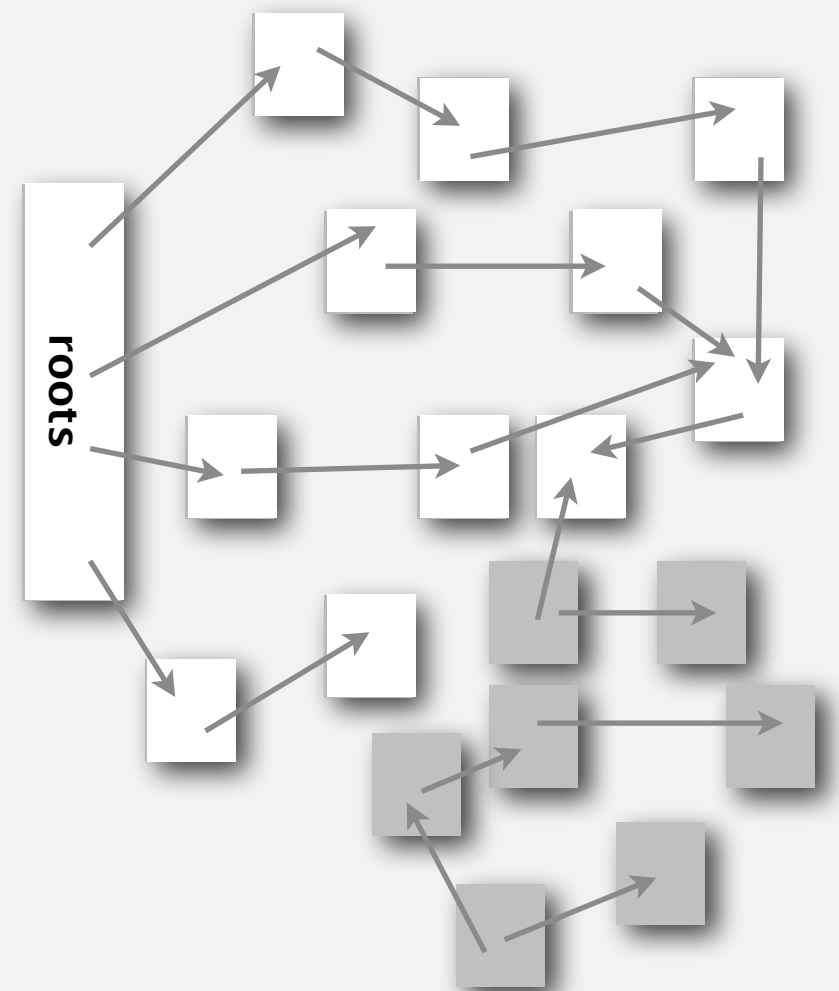
# Reachability application: mark-sweep garbage collector

---

**Mark-sweep algorithm.** [McCarthy, 1960]

- Mark: mark all reachable objects.
- Sweep: if object is unmarked, it is garbage (so add to free list).

**Memory cost.** Uses 1 extra mark bit per object (plus DFS stack).



# Depth-first search in digraphs summary

---

DFS enables direct solution of simple digraph problems.

- ✓ • Reachability.
- Path finding.
- Topological sort.
- Directed cycle detection.

Basis for solving difficult digraph problems.

- 2-satisfiability.
- Directed Euler path.
- Strongly connected components.

SIAM J. COMPUT.  
Vol. 1, No. 2, June 1972

## DEPTH-FIRST SEARCH AND LINEAR GRAPH ALGORITHMS\*

ROBERT TARJAN†

**Abstract.** The value of depth-first search or “backtracking” as a technique for solving problems is illustrated by two examples. An improved version of an algorithm for finding the strongly connected components of a directed graph and an algorithm for finding the biconnected components of an undirect graph are presented. The space and time requirements of both algorithms are bounded by  $k_1V + k_2E + k_3$  for some constants  $k_1, k_2$ , and  $k_3$ , where  $V$  is the number of vertices and  $E$  is the number of edges of the graph being examined.



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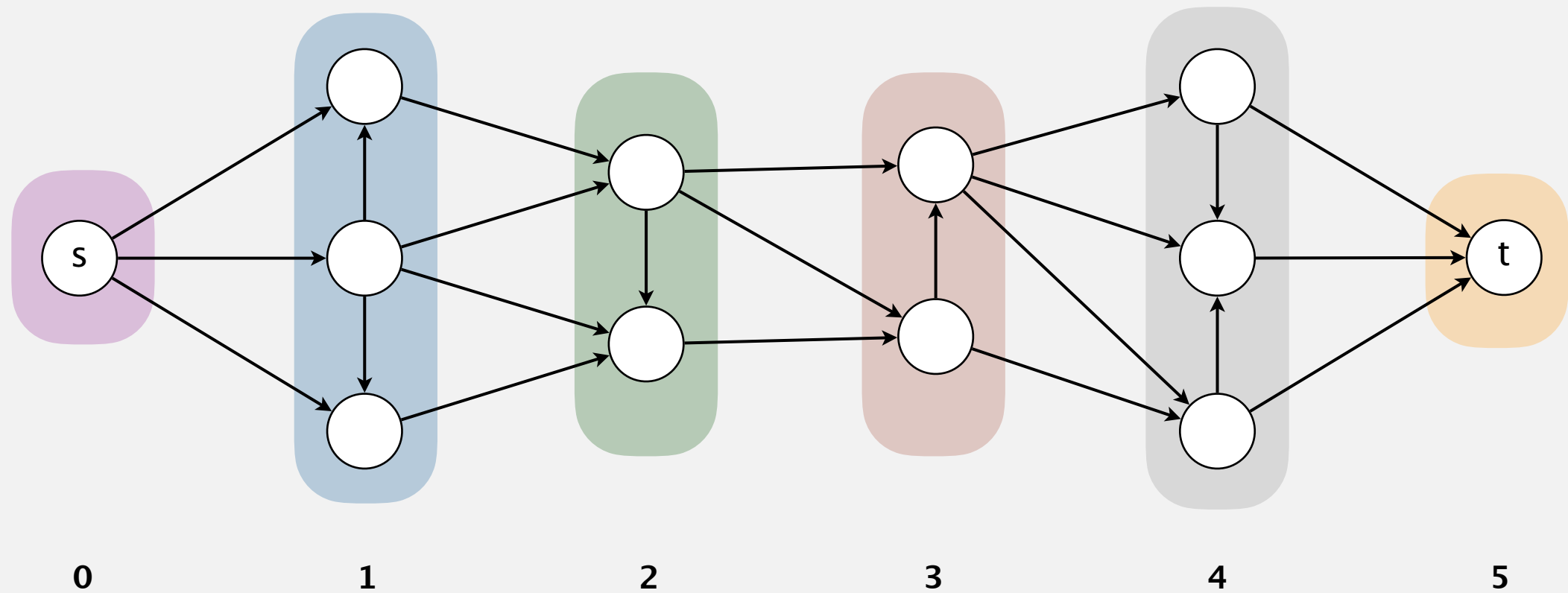
---

- ▶ *introduction*
- ▶ *digraph API*
- ▶ *depth-first search*
- ▶ *breadth-first search*
- ▶ *topological sort*



# Shortest directed paths

**Problem.** Find directed path from  $s$  to each vertex that uses fewest edges.



# Breadth-first search in digraphs

---

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- BFS is a **digraph** algorithm.

**BFS** (from source vertex  $s$ )

---

Put  $s$  onto a FIFO queue, and mark  $s$  as visited.

Repeat until the queue is empty:

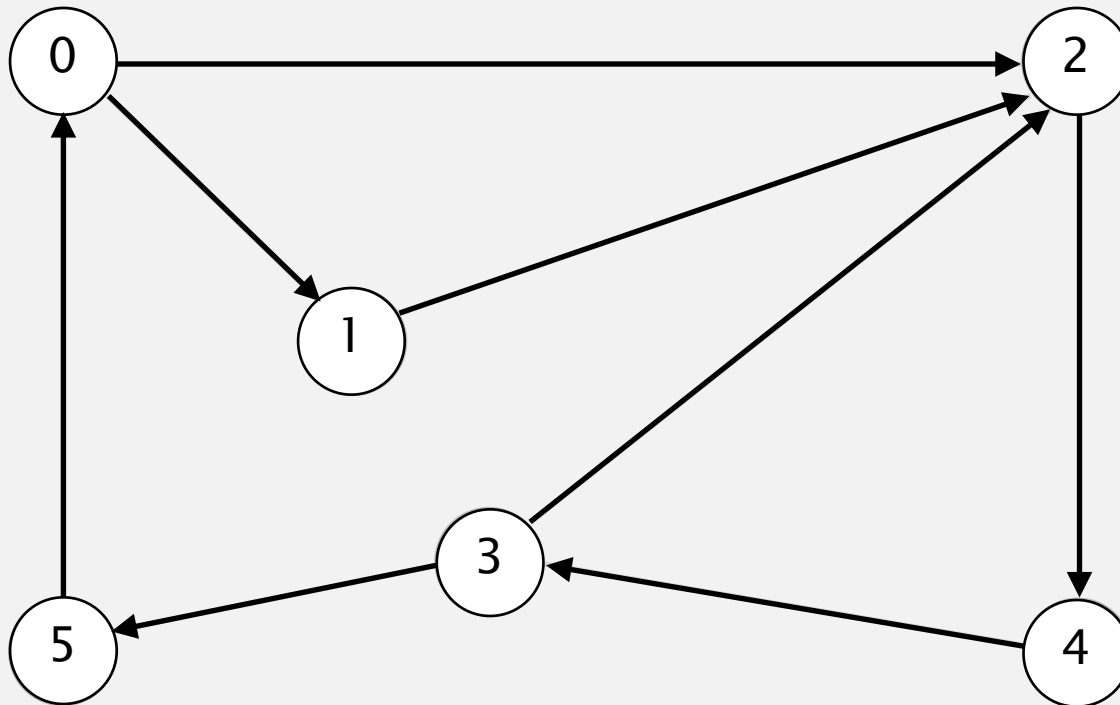
- remove the least recently added vertex  $v$
  - for each unmarked vertex adjacent from  $v$ :  
add to queue and mark as visited.
- 

**Proposition.** BFS computes directed path with fewest edges from  $s$  to each vertex in time proportional to  $E + V$ .

# Directed breadth-first search demo

Repeat until queue is empty:

- Remove vertex  $v$  from queue.
- Add to queue all unmarked vertices adjacent from  $v$  and mark them.



**tinyDG2.txt**

V	E
6	
8	
5	0
2	4
3	2
1	2
0	1
4	3
3	5
0	2

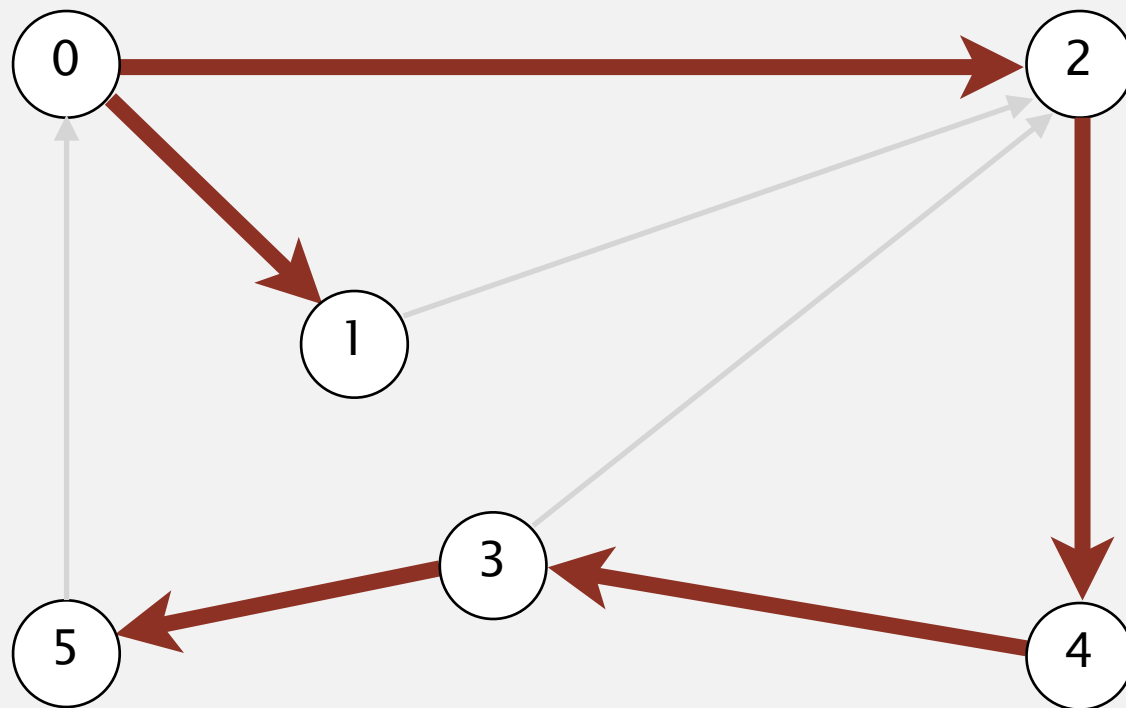
**graph G**

# Directed breadth-first search demo

---

Repeat until queue is empty:

- Remove vertex  $v$  from queue.
- Add to queue all unmarked vertices adjacent from  $v$  and mark them.



$v$	edgeTo[]	marked[]
0	–	T
1	0	T
2	0	T
3	4	T
4	2	T
5	3	T

**all done**



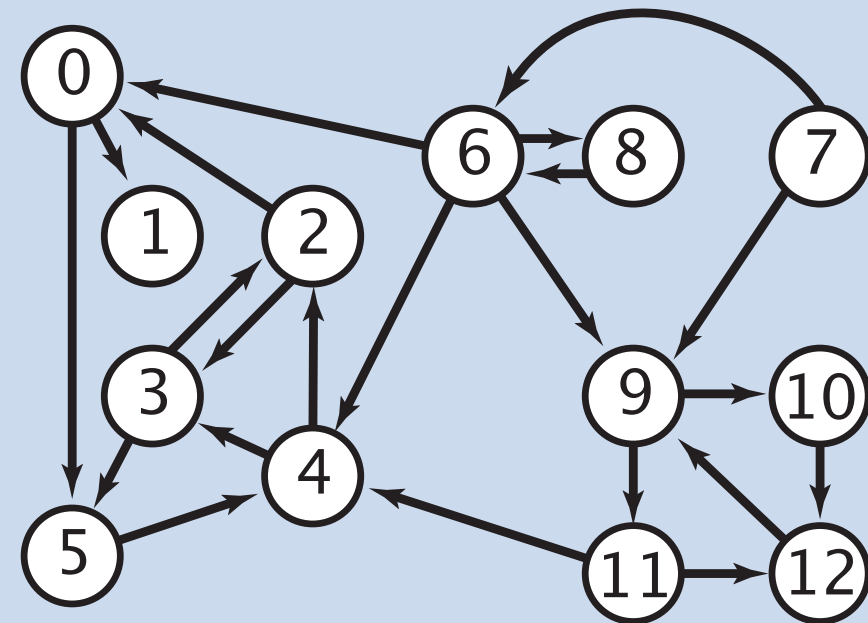
# MULTIPLE-SOURCE SHORTEST PATHS



Given a digraph and a **set** of source vertices, find shortest path from **any** vertex in the set to every other vertex.

**Ex.**  $S = \{ 1, 7, 10 \}$ .

- Shortest path to 4 is  $7 \rightarrow 6 \rightarrow 4$ .
- Shortest path to 5 is  $7 \rightarrow 6 \rightarrow 0 \rightarrow 5$ .
- Shortest path to 12 is  $10 \rightarrow 12$ .



needed for Assignment 6

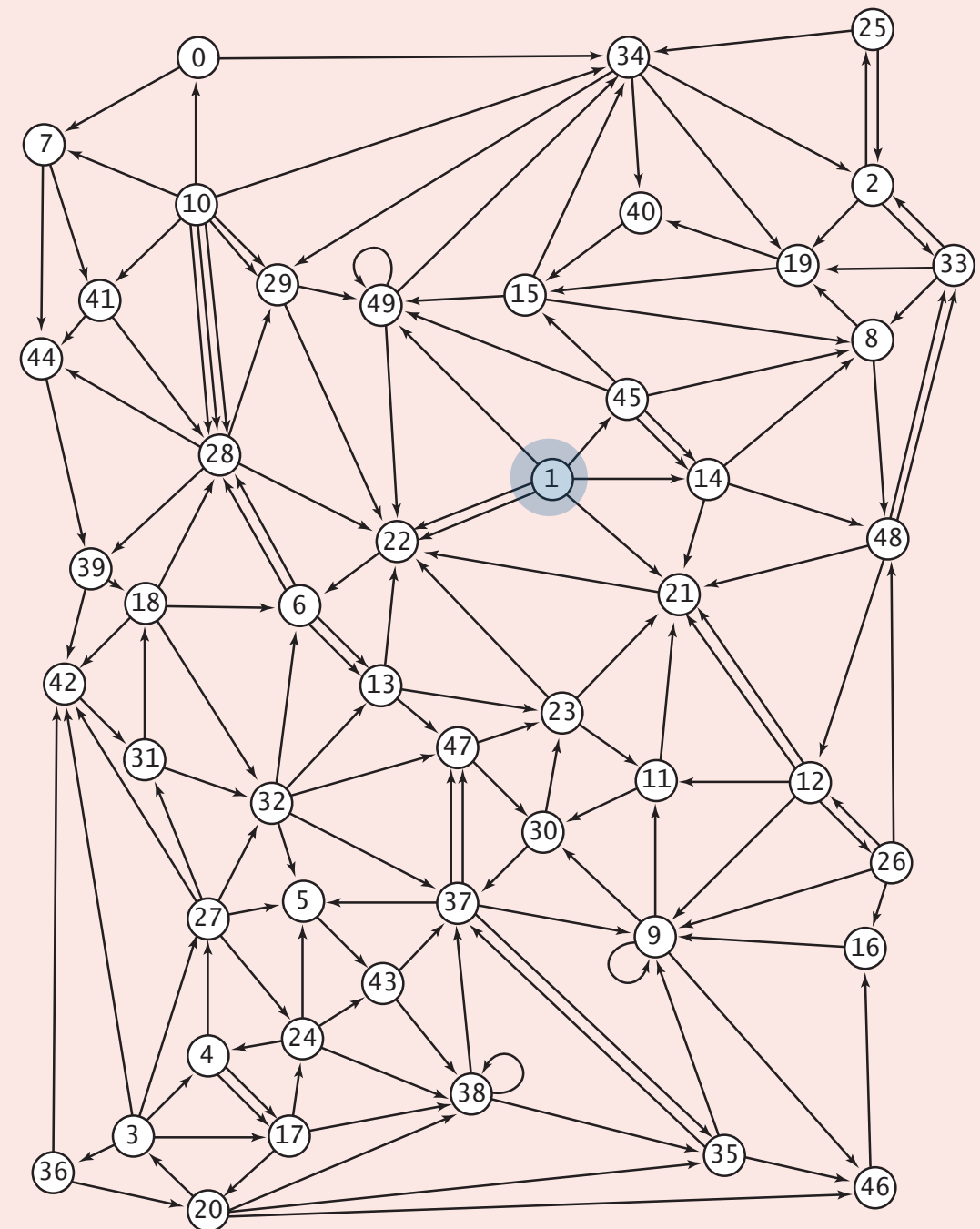


**Q.** How to implement **multi-source** shortest paths algorithm?



Suppose that you want to design a web crawler. Which graph search algorithm should you use?

- A. depth-first search
- B. breadth-first search
- C. either A or B
- D. neither A nor B



# Web crawler output

---

## BFS crawl

```
http://www.princeton.edu
http://www.w3.org
http://ogp.me
http://giving.princeton.edu
http://www.princetonartmuseum.org
http://www.goprincetontigers.com
http://library.princeton.edu
http://helpdesk.princeton.edu
http://tigernet.princeton.edu
http://alumni.princeton.edu
http://gradschool.princeton.edu
http://vimeo.com
http://princetonusg.com
http://artmuseum.princeton.edu
http://jobs.princeton.edu
http://odoc.princeton.edu
http://blogs.princeton.edu
http://www.facebook.com
http://twitter.com
http://www.youtube.com
http://deimos.apple.com
http://qeprize.org
http://en.wikipedia.org
...
```

## DFS crawl

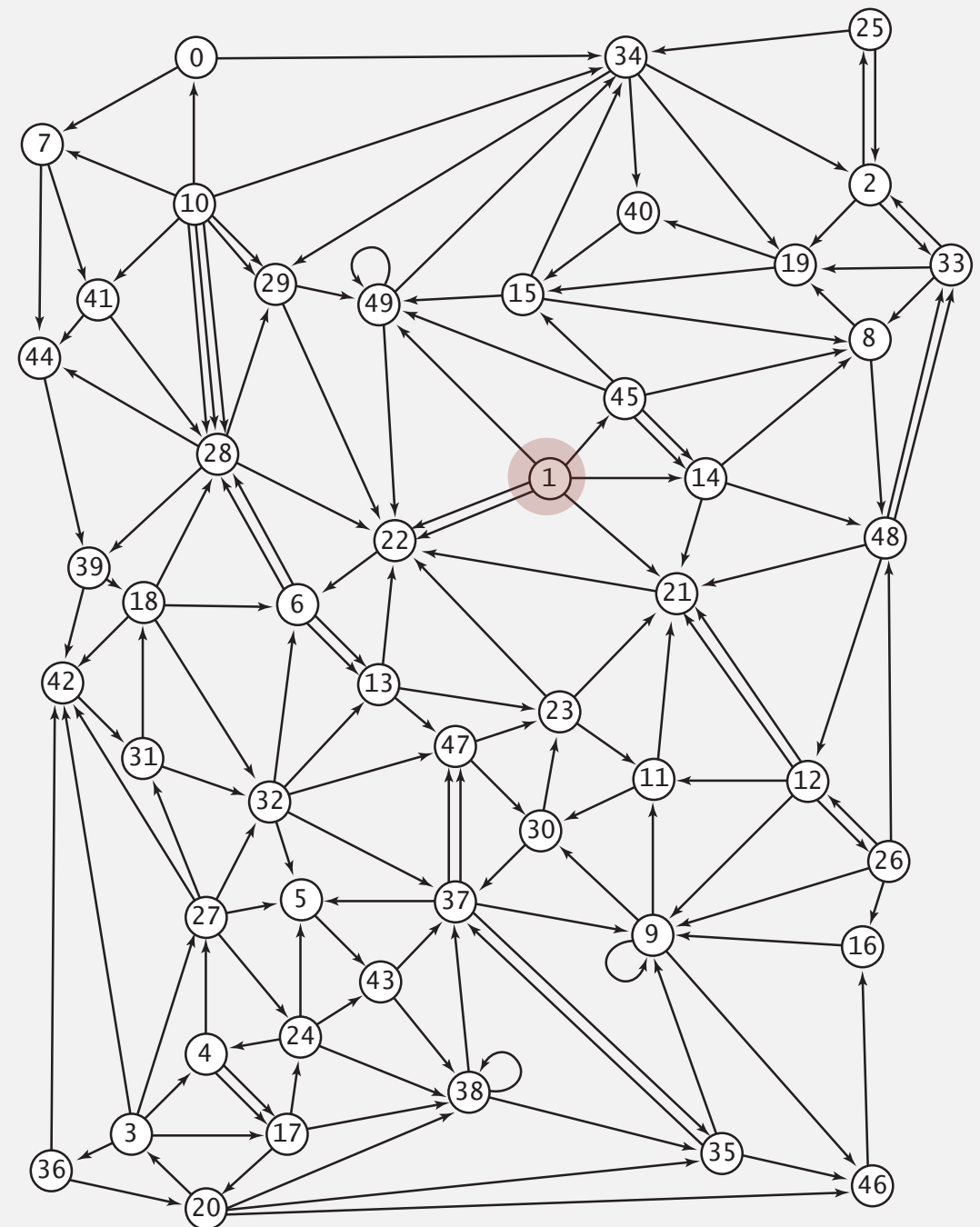
```
http://www.princeton.edu
http://deimos.apple.com
http://www.youtube.com
http://www.google.com
http://news.google.com
http://csi.gstatic.com
http://googlenewsblog.blogspot.com
http://labs.google.com
http://groups.google.com
http://img1.blogblog.com
http://feeds.feedburner.com
http://buttons.google syndication.com
http://fusion.google.com
http://insidesearch.blogspot.com
http://agoogleaday.com
http://static.googleusercontent.com
http://searchresearch1.blogspot.com
http://feedburner.google.com
http://www.dot.ca.gov
http://www.TahoeRoads.com
http://www.LakeTahoeTransit.com
http://www.laketahoe.com
http://ethel.tahoeguide.com
...
```

# Breadth-first search in digraphs application: web crawler

**Goal.** Crawl web, starting from some root web page, say `www.princeton.edu`.

**Solution.** [BFS with implicit digraph]

- Choose root web page as source  $s$ .
- Maintain a Queue of websites to explore.
- Maintain a SET of marked websites.
- Dequeue the next website and enqueue any unmarked websites to which it links.



# Bare-bones web crawler: Java implementation

```
Queue<String> queue = new Queue<String>();  
SET<String> marked = new SET<String>();
```

← queue of websites to crawl  
← set of marked websites

```
String root = "http://www.princeton.edu";  
queue.enqueue(root);  
marked.add(root);
```

← start crawling from root website

```
while (!queue.isEmpty())  
{
```

```
    String v = queue.dequeue();  
    StdOut.println(v);  
    In in = new In(v);  
    String input = in.readAll();
```

← read in raw html from next website in queue

```
    String regexp = "http://(\\w+\\.)+(\\w+)";  
    Pattern pattern = Pattern.compile(regexp);  
    Matcher matcher = pattern.matcher(input);
```

← use regular expression to find all URLs in website of form http://xxx.yyy.zzz [crude pattern misses relative URLs]

```
    while (matcher.find())  
    {
```

```
        String w = matcher.group();
```

```
        if (!marked.contains(w))  
        {  
            marked.add(w);  
            q.enqueue(w);  
        }
```

← if unmarked, mark and enqueue

```
    }  
}
```





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## 4.2 DIRECTED GRAPHS

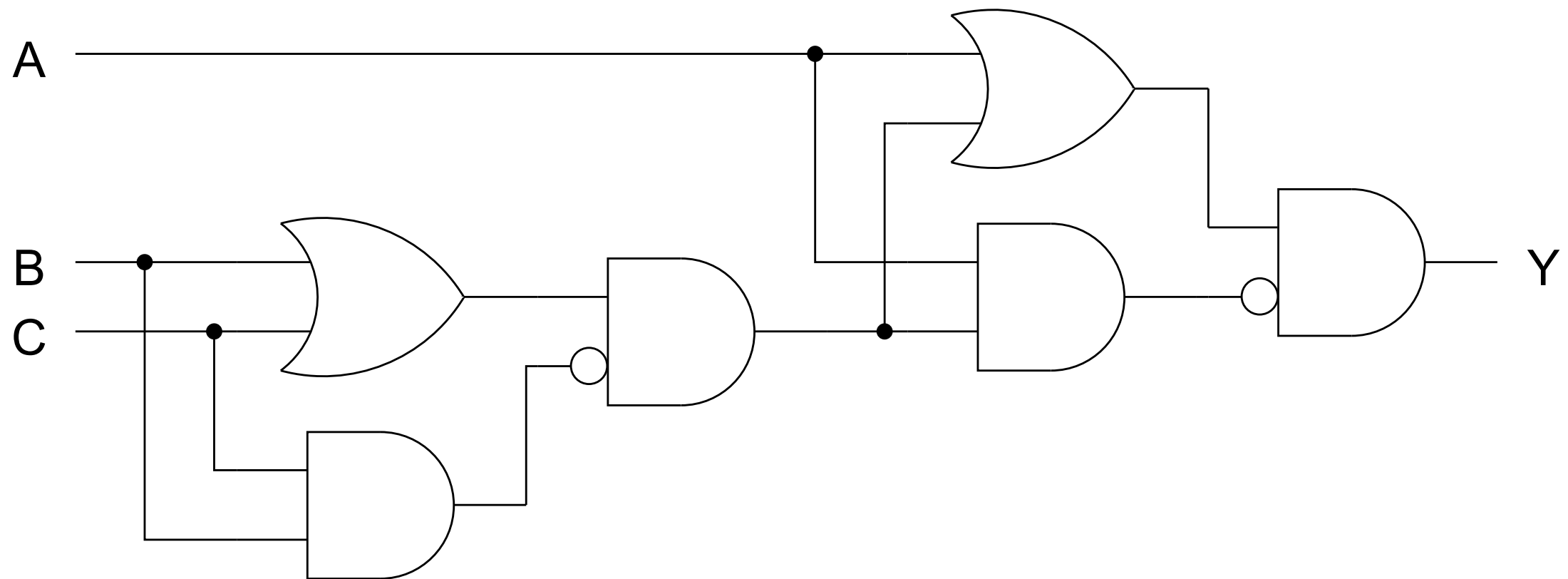
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- ▶ *introduction*
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# Combinational circuit

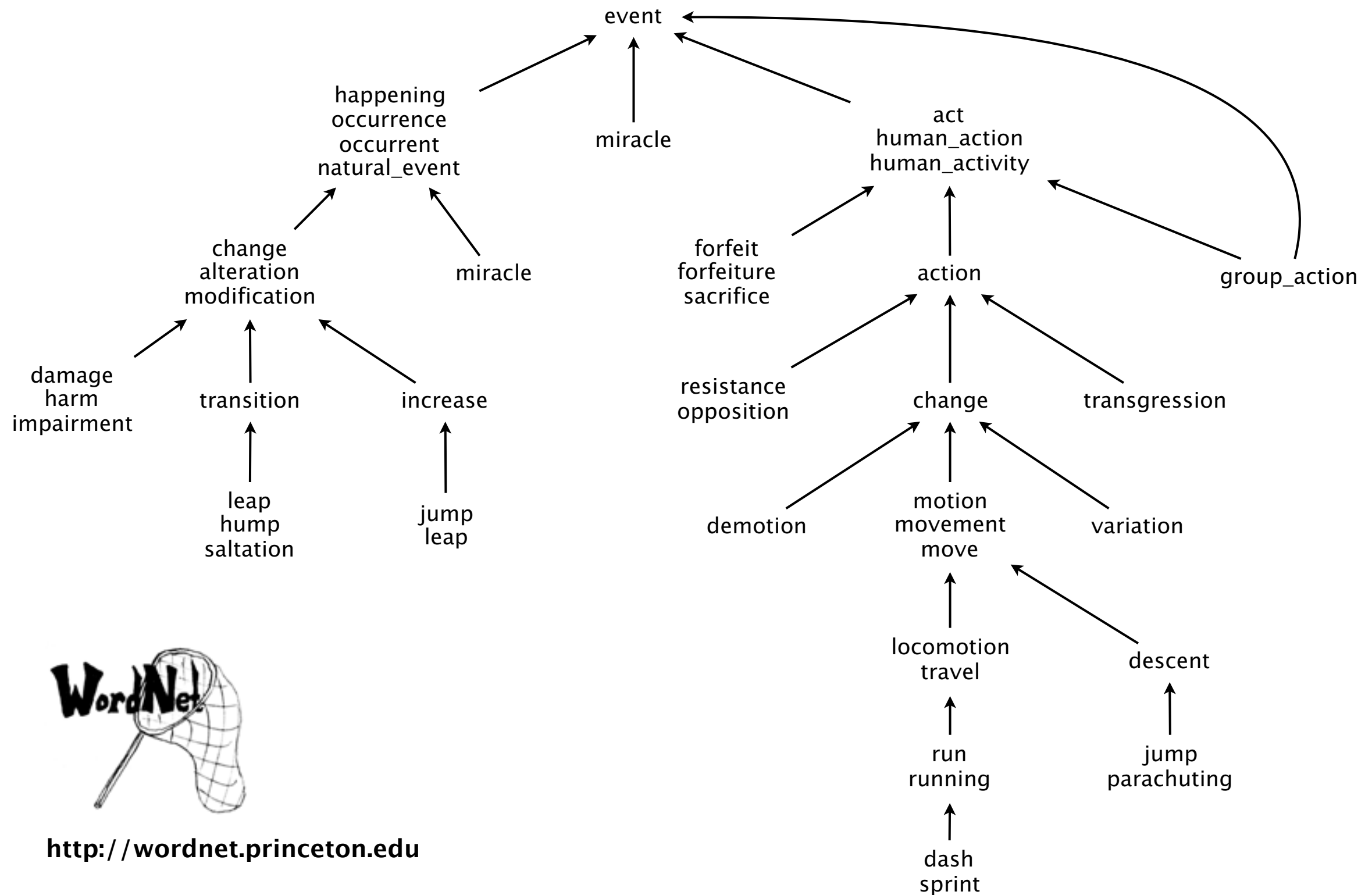
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Vertex = logical gate; edge = wire.



# WordNet digraph

Vertex = synset; edge = hypernym relationship.



<http://wordnet.princeton.edu>

# Git digraph

---

Vertex = revision of repository; edge = revision relationship.

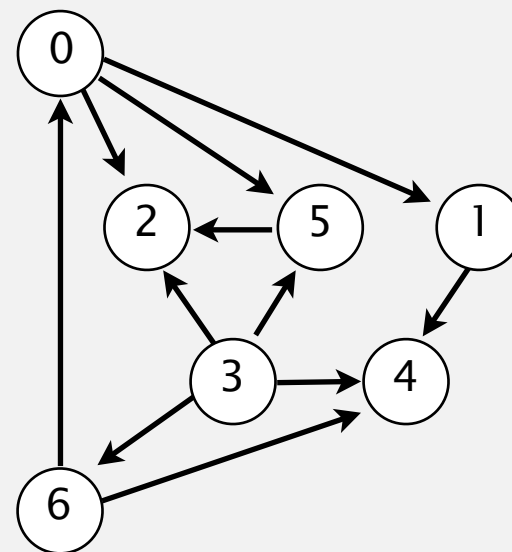
# Precedence scheduling

**Goal.** Given a set of tasks to be completed with precedence constraints, in which order should we schedule the tasks?

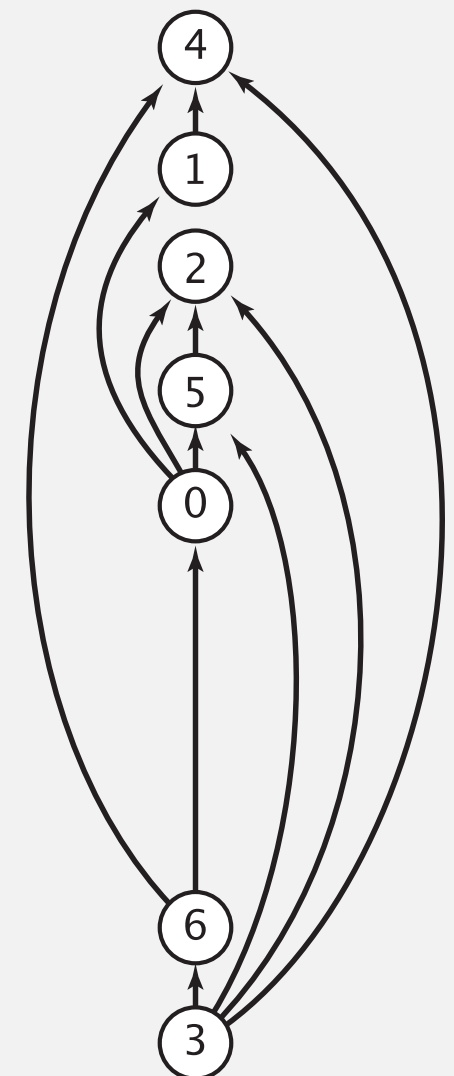
**Digraph model.** vertex = task; edge = precedence constraint.

0. Algorithms
1. Complexity Theory
2. Artificial Intelligence
3. Intro to CS
4. Cryptography
5. Scientific Computing
6. Advanced Programming

tasks



precedence constraint graph



feasible schedule



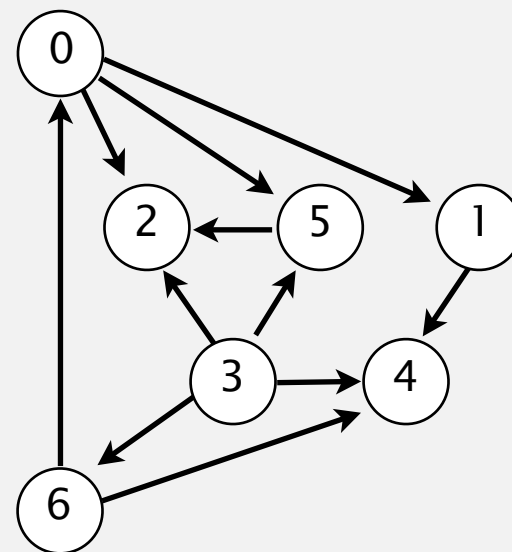
# Topological sort

DAG. Directed **acyclic** graph.

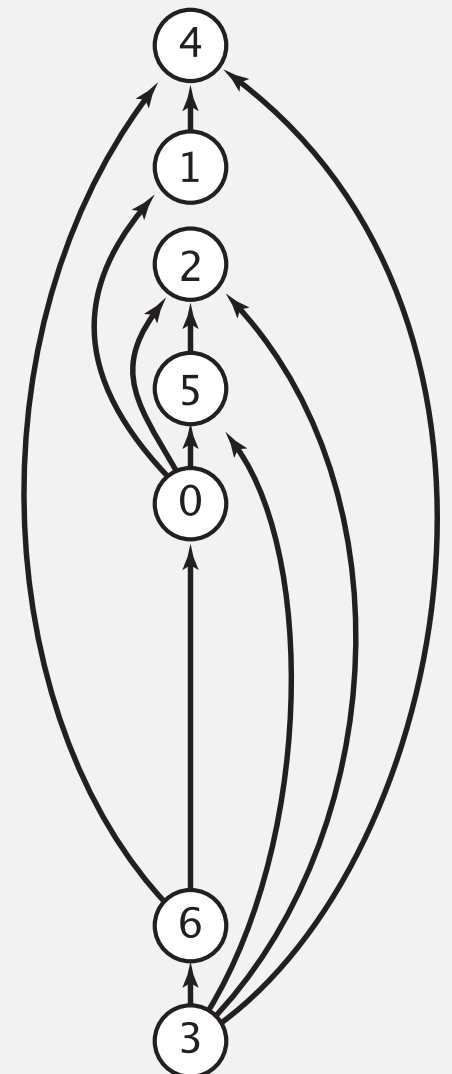
Topological sort. Redraw DAG so all edges point upwards.

$0 \rightarrow 5$	$0 \rightarrow 2$
$0 \rightarrow 1$	$3 \rightarrow 6$
$3 \rightarrow 5$	$3 \rightarrow 4$
$5 \rightarrow 2$	$6 \rightarrow 4$
$6 \rightarrow 0$	$3 \rightarrow 2$
$1 \rightarrow 4$	

directed edges



DAG

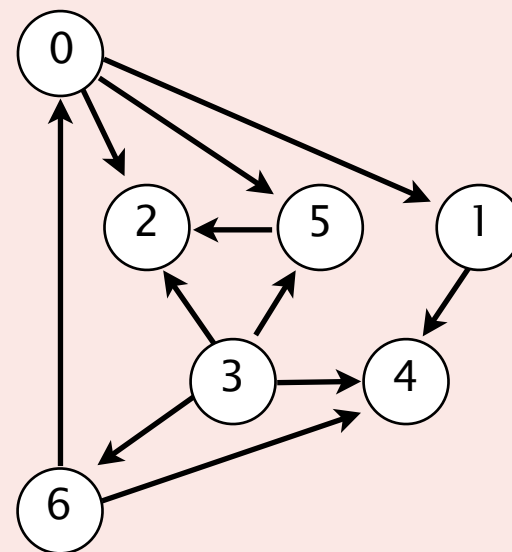


topological order

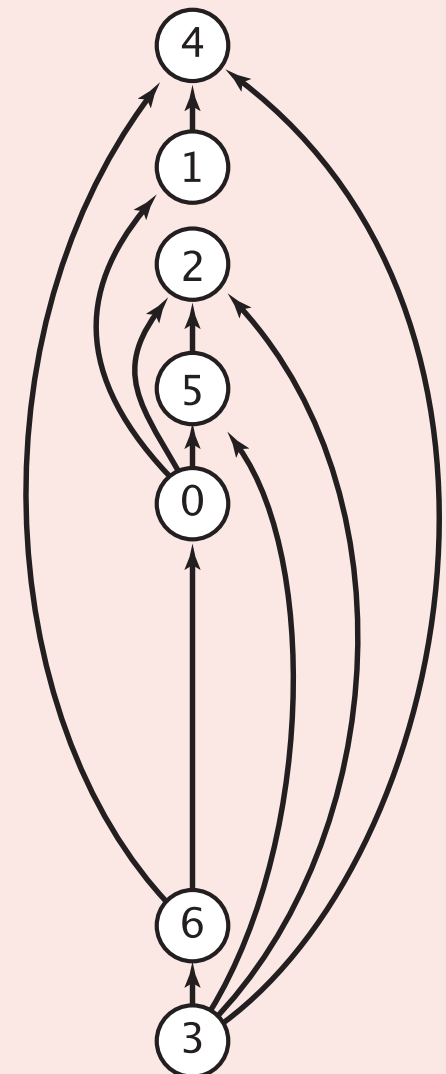


Suppose that you want to find a topological order of a DAG.  
Which graph search algorithm should you use?

- A. depth-first search
- B. breadth-first search
- C. either A or B
- D. neither A nor B



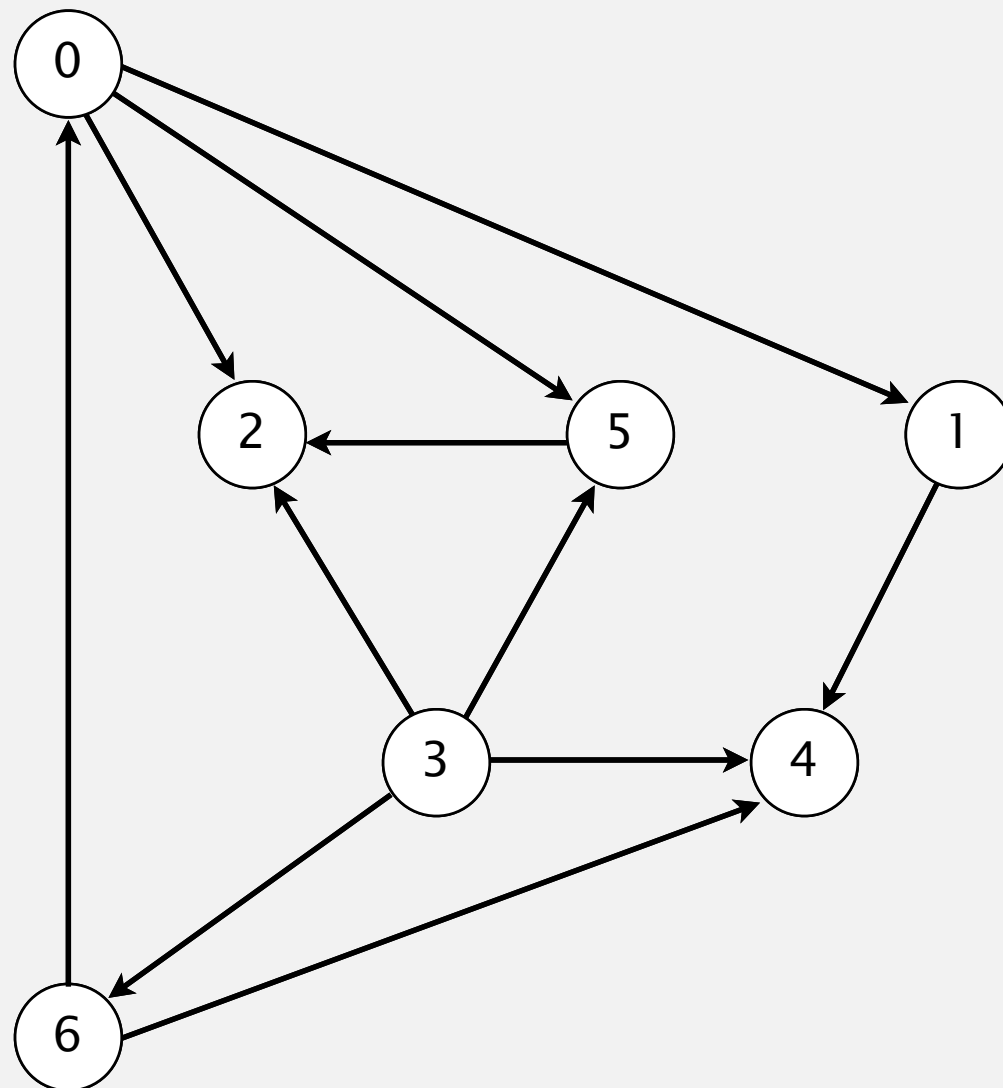
DAG



topological order

# Topological sort demo

- Run depth-first search.
- Return vertices in reverse postorder.



tinyDAG7.txt

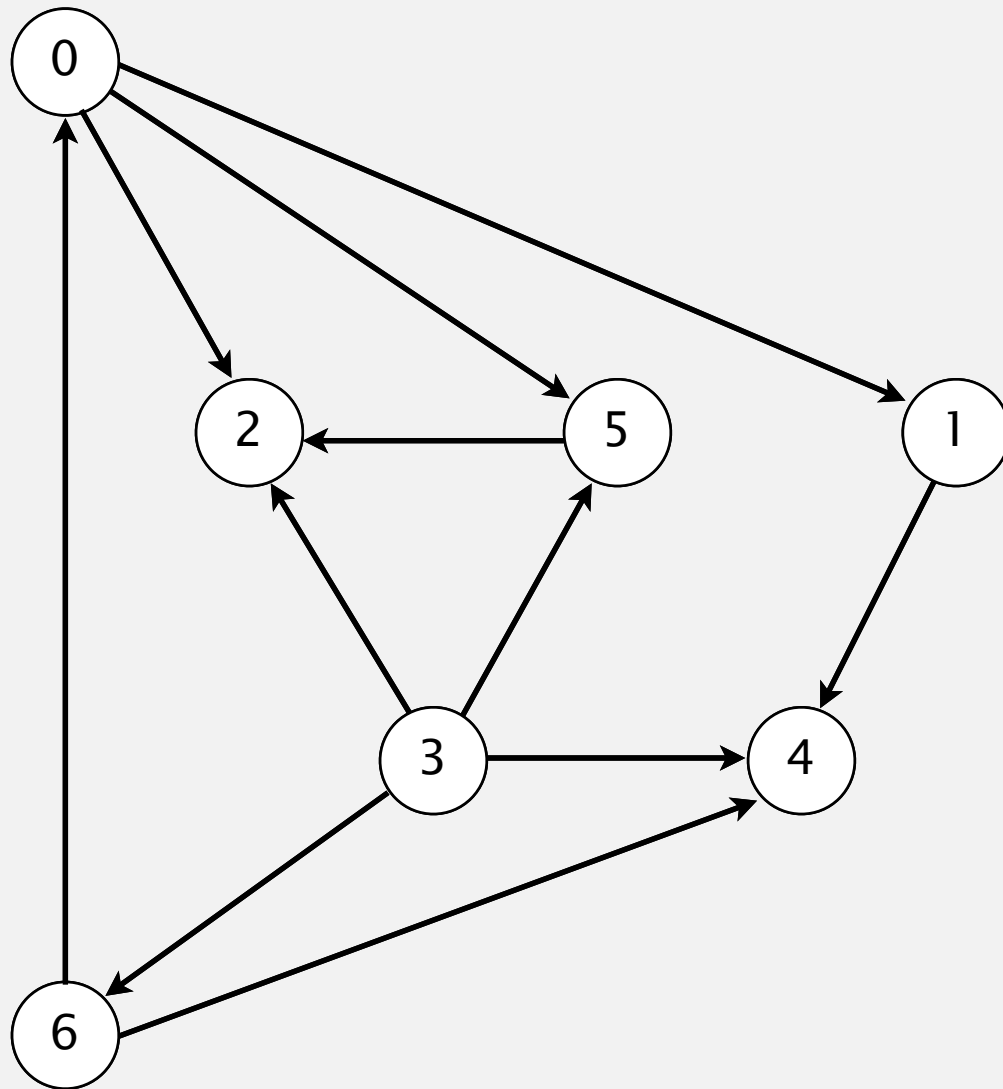
```
7
11
0 5
0 2
0 1
3 6
3 5
3 4
5 2
6 4
6 0
3 2
```

a directed acyclic graph

# Topological sort demo

---

- Run depth-first search.
- Return vertices in reverse postorder.



**postorder**

4 1 2 5 0 6 3

**topological order**

3 6 0 5 2 1 4

**done**

# Depth-first search order

---

```
public class DepthFirstOrder
{
    private boolean[] marked;
    private Stack<Integer> reversePostorder;

    public DepthFirstOrder(Digraph G)
    {
        reversePostorder = new Stack<Integer>();
        marked = new boolean[G.V()];
        for (int v = 0; v < G.V(); v++)
            if (!marked[v]) dfs(G, v);
    }

    private void dfs(Digraph G, int v)
    {
        marked[v] = true;
        for (int w : G.adj(v))
            if (!marked[w]) dfs(G, w);
        reversePostorder.push(v);
    }

    public Iterable<Integer> reversePostorder()
    { return reversePostorder; }
}
```

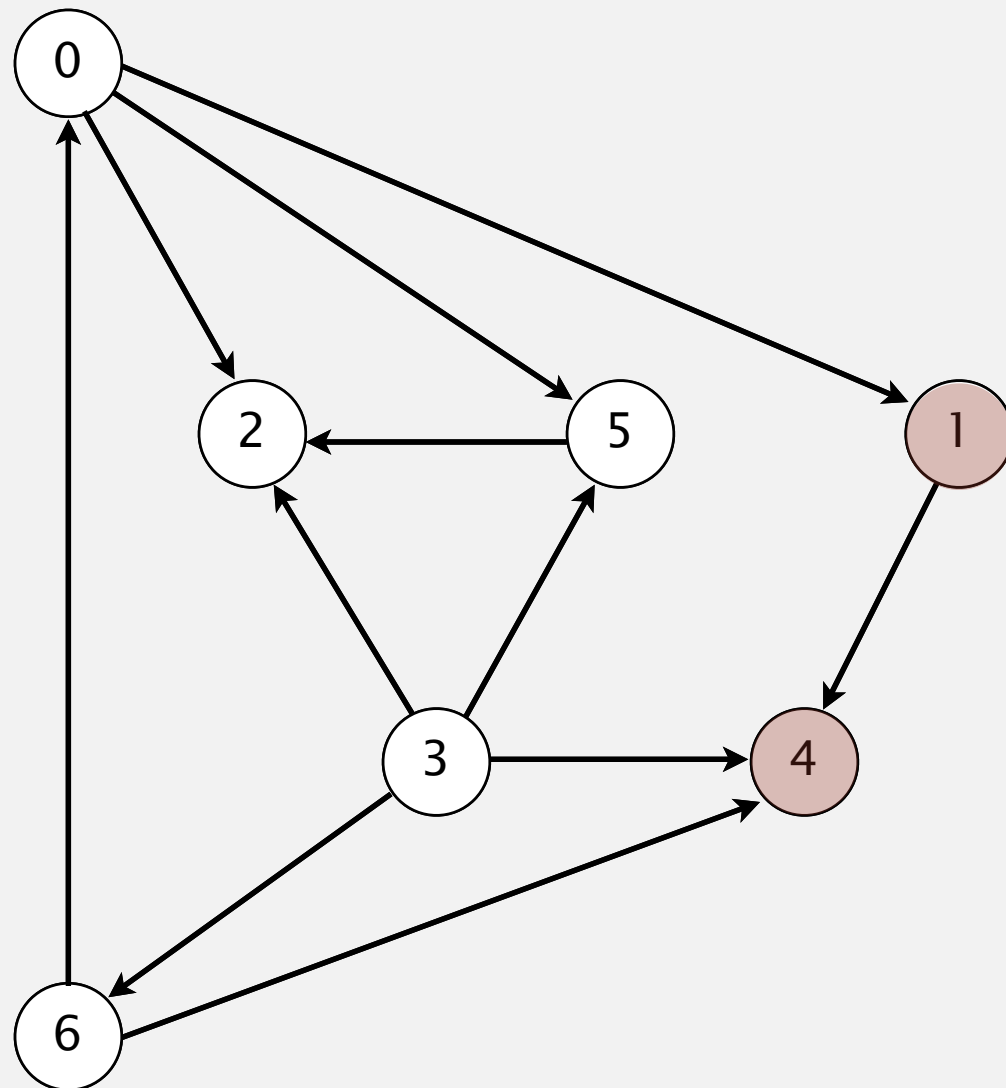
← returns all vertices in  
“reverse DFS postorder”

# Topological sort in a DAG: intuition

---

## Why does topological sort algorithm work?

- First vertex in postorder has outdegree 0.
- Second-to-last vertex in postorder can only point to last vertex.
- ...



**postorder**

4 1 2 5 0 6 3

**topological order**

3 6 0 5 2 1 4

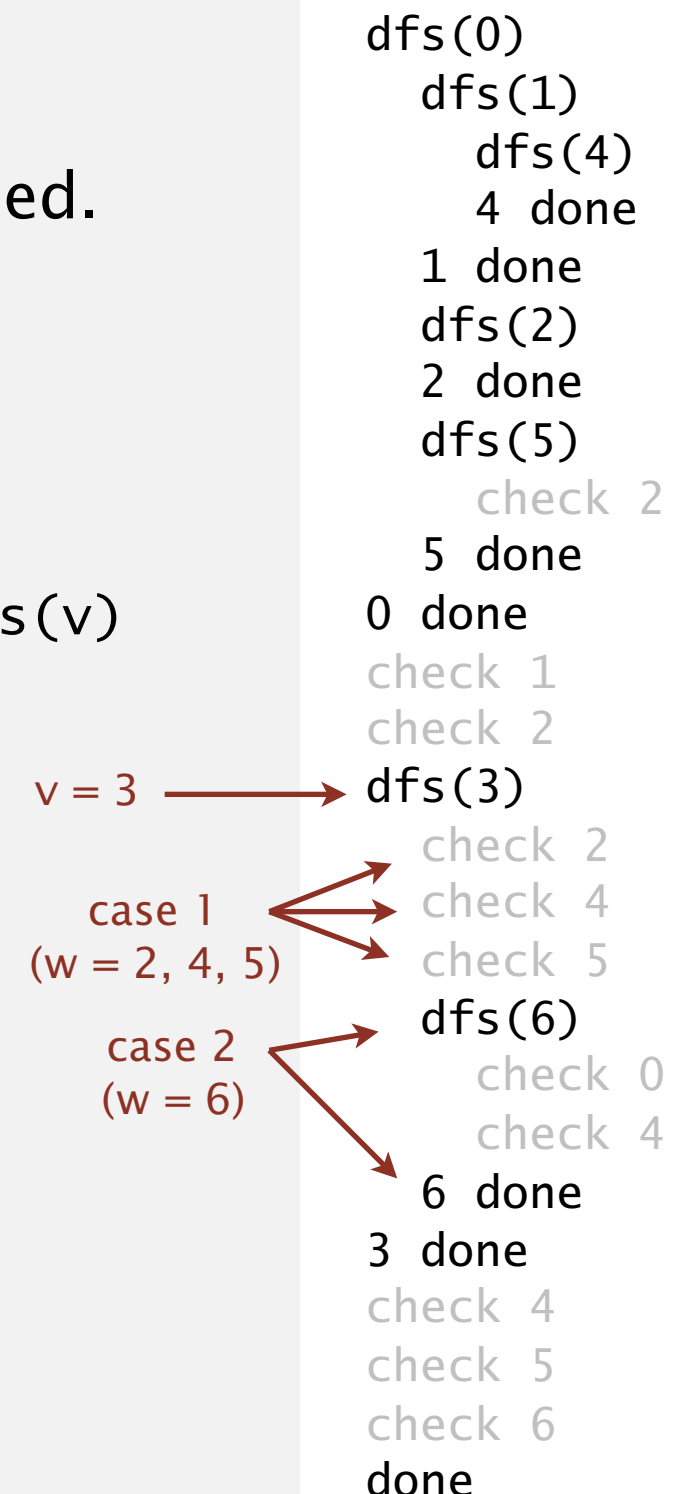


# Topological sort in a DAG: correctness proof

**Proposition.** Reverse DFS postorder of a DAG is a topological order.

**Pf.** Consider any edge  $v \rightarrow w$ . When  $\text{dfs}(v)$  is called:

- Case 1:  $\text{dfs}(w)$  has already been called and returned.
  - thus,  $w$  appears before  $v$  in postorder
- Case 2:  $\text{dfs}(w)$  has not yet been called.
  - $\text{dfs}(w)$  will get called directly or indirectly by  $\text{dfs}(v)$
  - so,  $\text{dfs}(w)$  will return before  $\text{dfs}(v)$
  - thus,  $w$  appears before  $v$  in postorder
- Case 3:  $\text{dfs}(w)$  has already been called, but has not yet returned.
  - function-call stack contains path from  $w$  to  $v$
  - edge  $v \rightarrow w$  would complete a directed cycle
  - contradiction (it's a DAG)



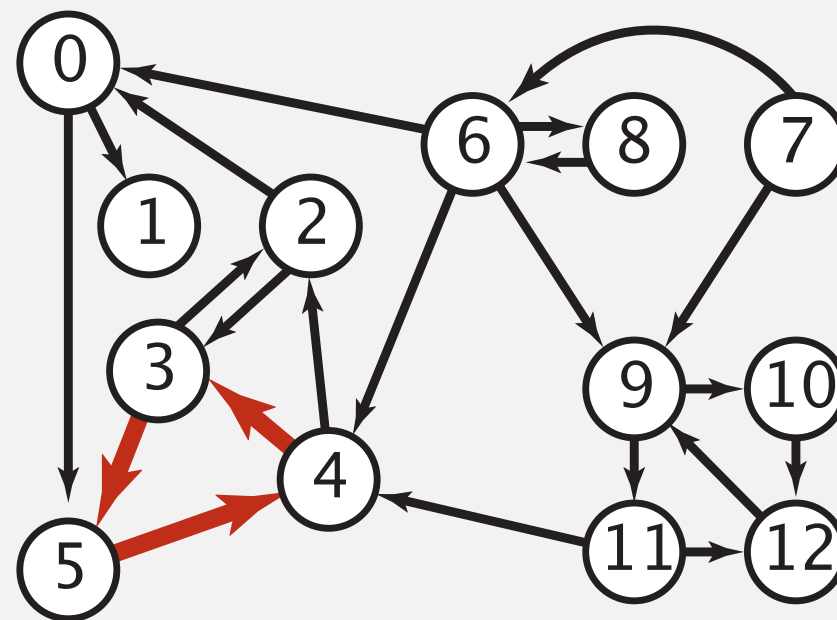
# Directed cycle detection

---

**Proposition.** A digraph has a topological order iff no directed cycle.

**Pf.**

- If directed cycle, topological order impossible.
- If no directed cycle, DFS-based algorithm finds a topological order.



a digraph with a directed cycle

**Goal.** Given a digraph, find a directed cycle.

**Solution.** DFS. What else? See textbook.

# Directed cycle detection application: precedence scheduling

---

**Scheduling.** Given a set of tasks to be completed with precedence constraints, in what order should we schedule the tasks?

PAGE 3

DEPARTMENT	COURSE	DESCRIPTION	PREREQS
COMPUTER SCIENCE	CPSC 432	INTERMEDIATE COMPILER DESIGN, WITH A FOCUS ON DEPENDENCY RESOLUTION.	CPSC 432

<http://xkcd.com/754>

**Remark.** A directed cycle implies scheduling problem is infeasible.

# Directed cycle detection application: cyclic inheritance

---

The Java compiler does cycle detection.

```
public class A extends B
{
    ...
}
```

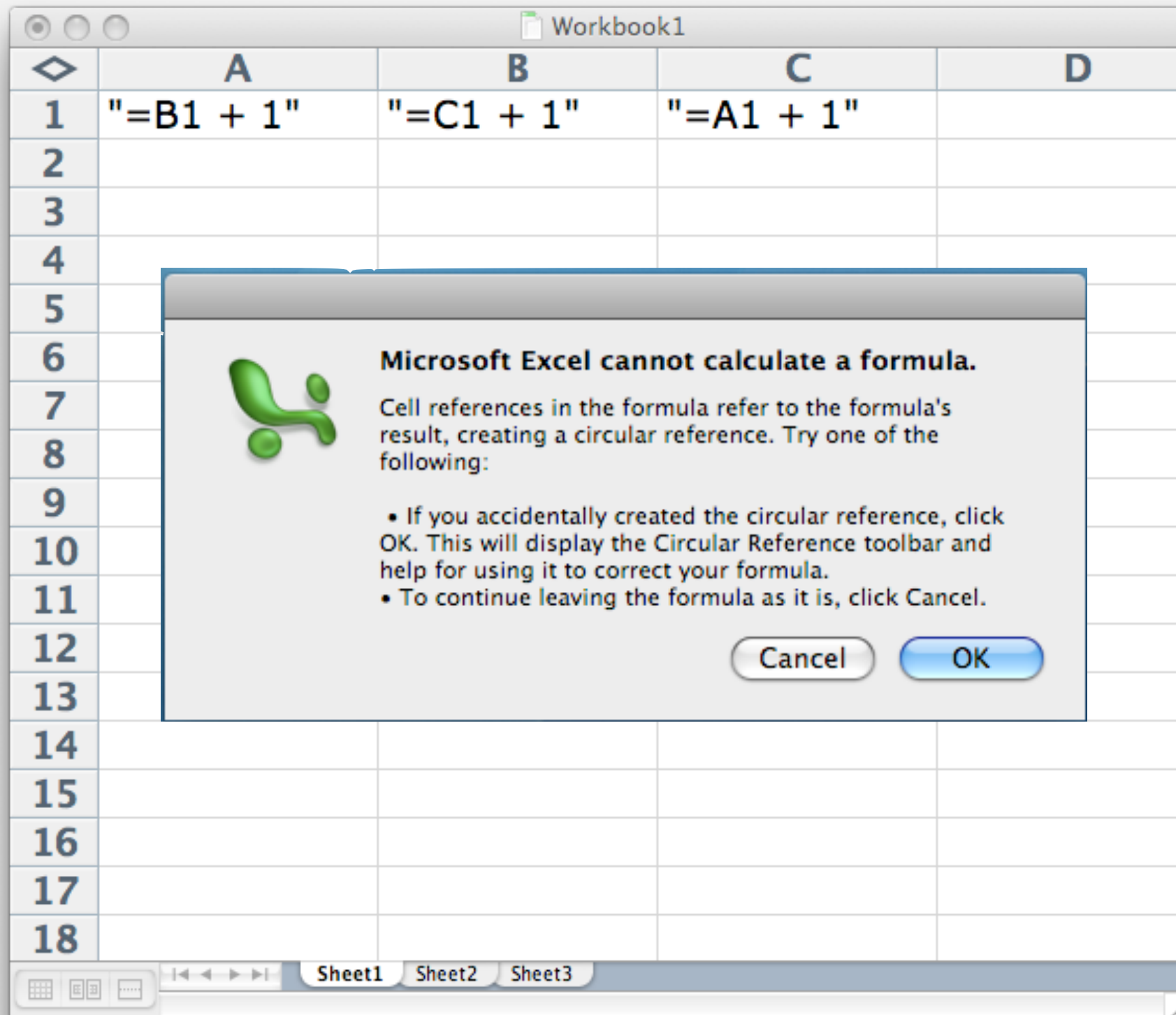
```
public class B extends C
{
    ...
}
```

```
public class C extends A
{
    ...
}
```

```
% javac A.java
A.java:1: cyclic inheritance
involving A
public class A extends B { }
                ^
1 error
```

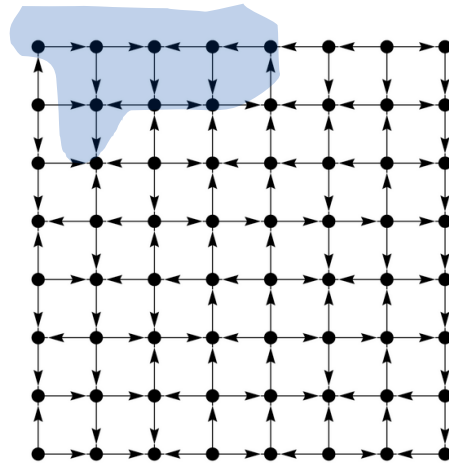
# Directed cycle detection application: spreadsheet recalculation

Microsoft Excel does cycle detection.



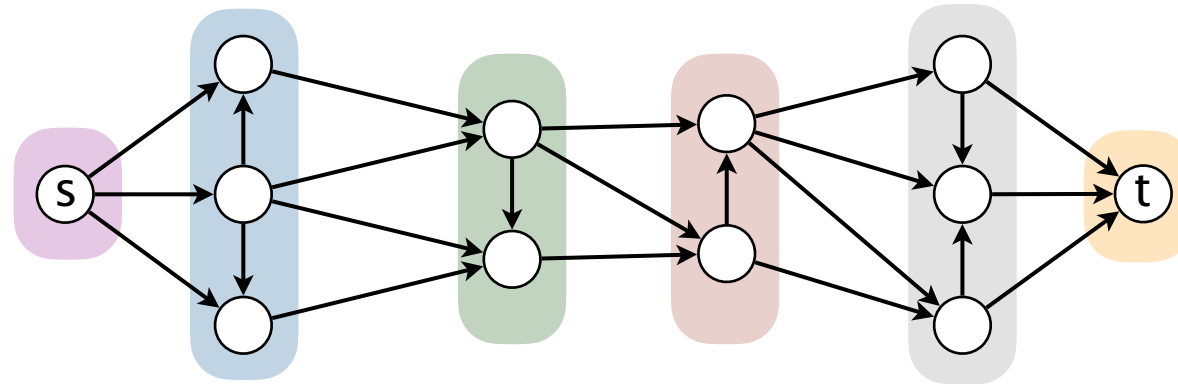
# Digraph-processing summary: algorithms of the day

**single-source  
reachability  
in a digraph**



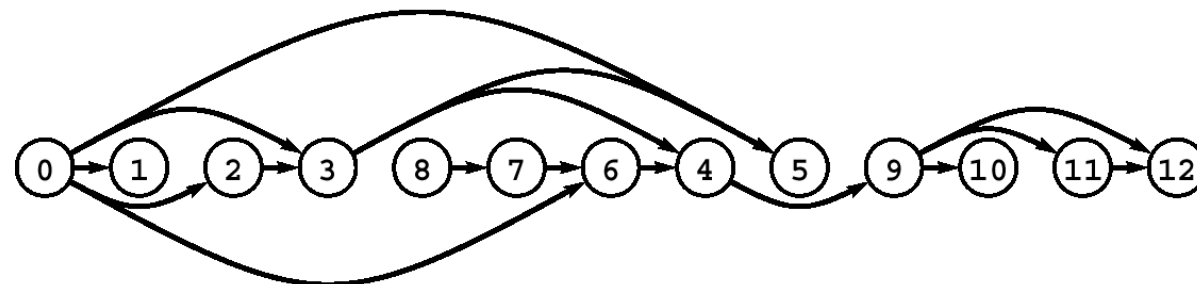
DFS/BFS

**shortest path  
in a digraph**



BFS

**topological sort  
in a DAG**



DFS