

Time Synchronization and Logical Clocks



COS 418: *Distributed Systems*
Lecture 4

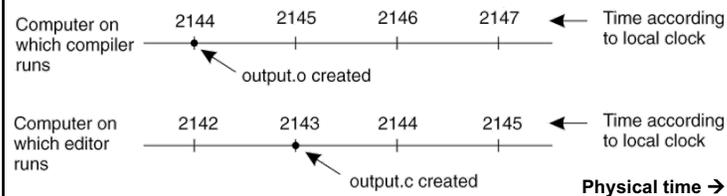
Kyle Jamieson

Today

1. The need for time synchronization
2. “Wall clock time” synchronization
3. Logical Time: Lamport Clocks

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A distributed edit-compile workflow



- 2143 < 2144 → make **doesn't call compiler**

Lack of time synchronization result –
a **possible object file mismatch**

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What makes time synchronization hard?

1. Quartz oscillator **sensitive** to temperature, age, vibration, radiation
– Accuracy ca. one part per million (**one second of clock drift over 12 days**)
2. The internet is:
 - **Asynchronous**: arbitrary message **delays**
 - **Best-effort**: messages **don't always arrive**

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 - Cristian’s algorithm, Berkeley algorithm, NTP
3. Logical Time: Lamport clocks

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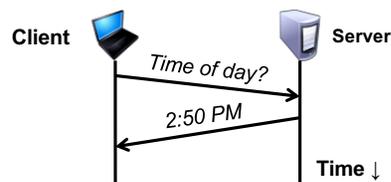
Just use Coordinated Universal Time?

- UTC is broadcast from radio stations on land and satellite (e.g., the Global Positioning System)
 - Computers with receivers can synchronize their clocks with these timing signals
- Signals from land-based stations are accurate to about 0.1–10 milliseconds
- Signals from GPS are accurate to about one microsecond
 - *Why can’t we put GPS receivers on all our computers?*

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Synchronization to a time server

- Suppose a server with an accurate clock (e.g., GPS-disciplined crystal oscillator)
 - Could simply issue an RPC to obtain the time:

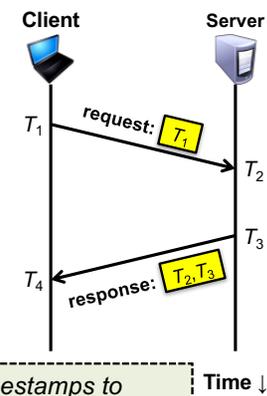


- But this doesn’t account for network latency
 - **Message delays** will have **outdated** server’s answer

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Cristian’s algorithm: Outline

1. Client sends a **request** packet, timestamped with its local clock T_1
2. Server timestamps its receipt of the request T_2 with its local clock
3. Server sends a **response** packet with its local clock T_3 and T_2
4. Client locally timestamps its receipt of the server’s response T_4



How the client can use these timestamps to synchronize its local clock to the server’s local clock?

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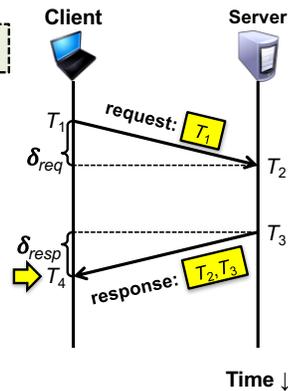
Cristian's algorithm: Offset sample calculation

Goal: Client sets clock $\leftarrow T_3 + \delta_{resp}$

- Client samples **round trip time** $\delta = \delta_{req} + \delta_{resp} = (T_4 - T_1) - (T_3 - T_2)$
- But client knows δ , not δ_{resp}

Assume: $\delta_{req} \approx \delta_{resp}$

Client sets clock $\leftarrow T_3 + \frac{1}{2}\delta$



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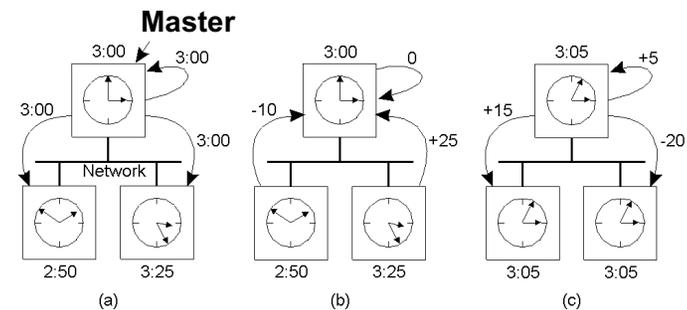
Berkeley algorithm

- A single time server can **fail**, blocking timekeeping
- The **Berkeley algorithm** is a distributed algorithm for timekeeping
 - Assumes all machines have **equally-accurate local clocks**
 - Obtains **average** from participating computers and synchronizes clocks to that average

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Berkeley algorithm

- Master machine**: polls L other machines using Cristian's algorithm $\rightarrow \{\theta_i\} (i = 1 \dots L)$



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The Network Time Protocol (NTP)

- Enables clients to be accurately synchronized to UTC despite message delays
- Provides **reliable** service
 - Survives lengthy losses of connectivity
 - Communicates over redundant network paths
- Provides an **accurate** service
 - Unlike the Berkeley algorithm, leverages **heterogeneous** accuracy in clocks

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NTP: System structure

- Servers and time sources are arranged in layers (**strata**)
 - Stratum 0: High-precision time sources themselves
 - e.g., atomic clocks, shortwave radio time receivers
 - Stratum 1: NTP servers **directly connected** to Stratum 0
 - Stratum 2: NTP servers that synchronize with Stratum 1
 - Stratum 2 servers are **clients of** Stratum 1 servers
 - Stratum 3: NTP servers that synchronize with Stratum 2
 - Stratum 3 servers are **clients of** Stratum 2 servers
- Users’ computers synchronize with Stratum 3 servers

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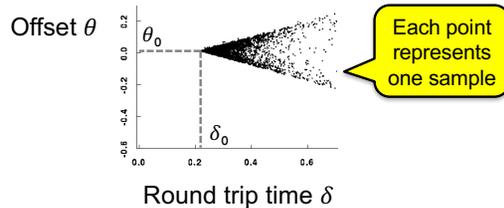
NTP operation: Server selection

- Messages between an NTP client and server are exchanged in pairs: request and response
 - Use Cristian’s algorithm
- For i^{th} message exchange with a particular server, calculate:
 1. **Clock offset** θ_i from client to server
 2. **Round trip time** δ_i between client and server
- Over last eight exchanges with server k , the client computes its **dispersion** $\sigma_k = \max_i \delta_i - \min_i \delta_i$
 - Client uses the server with **minimum dispersion**

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NTP operation : Clock offset calculation

- Client tracks **minimum round trip time** and **associated offset** over the last eight message exchanges (δ_0, θ_0)
 - θ_0 is the best estimate of offset: client adjusts its clock by θ_0 to **synchronize to server**



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NTP operation: How to change time

- Can't just change time: Don't want time to **run backwards**
 - Recall the make example
- Instead, change the **update rate** for the clock
 - Changes time in a more gradual fashion
 - Prevents inconsistent local timestamps

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Clock synchronization: Take-away points

- Clocks on different systems will always behave differently
 - Disagreement between machines can result in undesirable behavior
- NTP, Berkeley clock synchronization
 - Rely on timestamps to estimate network delays
 - **100s μ s–ms accuracy**
 - Clocks never exactly synchronized
- Often **inadequate** for distributed systems
 - Often need to reason about the **order of events**
 - Might need precision on the order of **ns**

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Motivation: Multi-site database replication

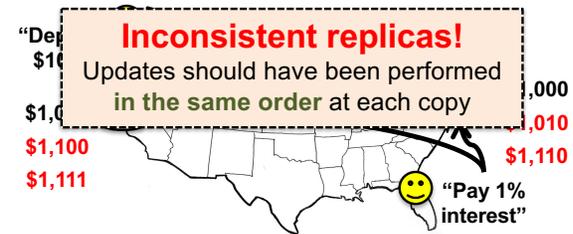
- A New York-based bank wants to make its transaction ledger database **resilient** to **whole-site failures**
- **Replicate** the database, keep one copy in sf, one in nyc



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The consequences of concurrent updates

- **Replicate** the database, keep one copy in sf, one in nyc
 - Client sends **query** to the **nearest** copy
 - Client sends **update** to **both** copies



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Idea: Logical clocks

- Landmark 1978 paper by Leslie Lamport
- **Insight:** only the **events themselves** matter

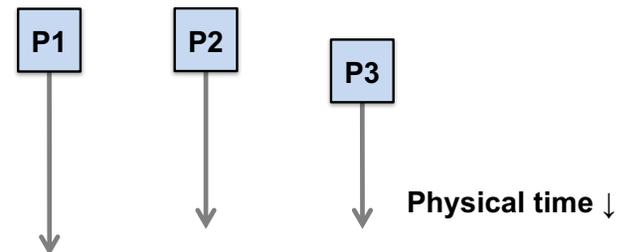


Idea: Disregard the precise clock time
Instead, capture **just** a "happens before" relationship between a pair of events

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Defining "happens-before" (→)

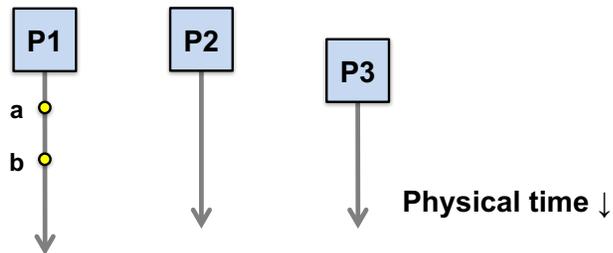
- Consider three processes: P1, P2, and P3
- **Notation:** Event a **happens before** event b ($a \rightarrow b$)



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Defining “happens-before” (\rightarrow)

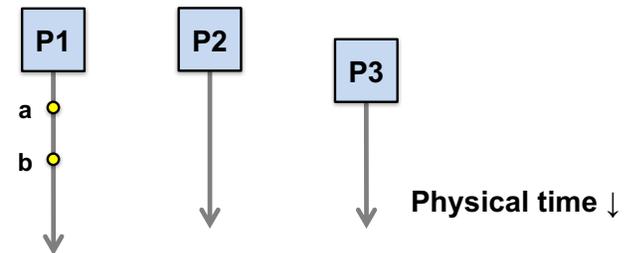
- Can observe event order at a single process



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Defining “happens-before” (\rightarrow)

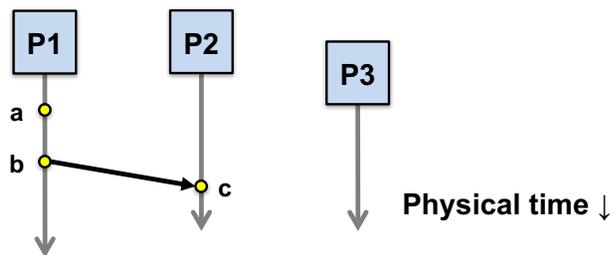
1. If **same process** and a occurs before b, then $a \rightarrow b$



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Defining “happens-before” (\rightarrow)

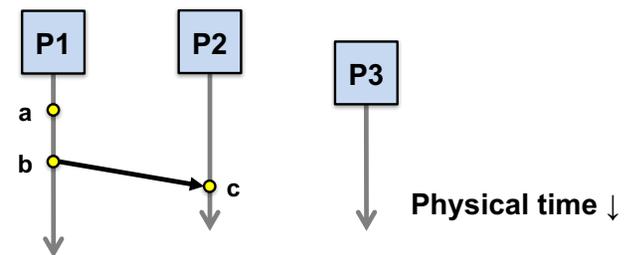
1. If **same process** and a occurs before b, then $a \rightarrow b$
2. Can observe ordering when processes communicate



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Defining “happens-before” (\rightarrow)

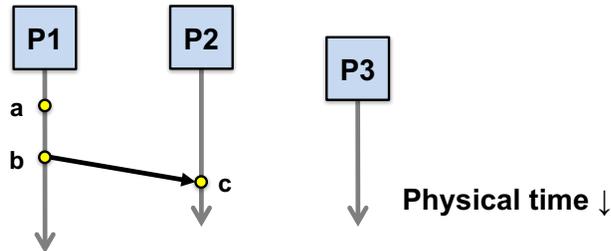
1. If **same process** and a occurs before b, then $a \rightarrow b$
2. If **c** is a message receipt of **b**, then $b \rightarrow c$



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Defining “happens-before” (\rightarrow)

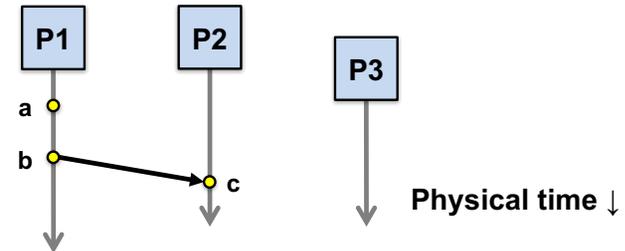
1. If **same process** and **a** occurs before **b**, then $a \rightarrow b$
2. If **c** is a message receipt of **b**, then $b \rightarrow c$
3. Can observe ordering transitively



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Defining “happens-before” (\rightarrow)

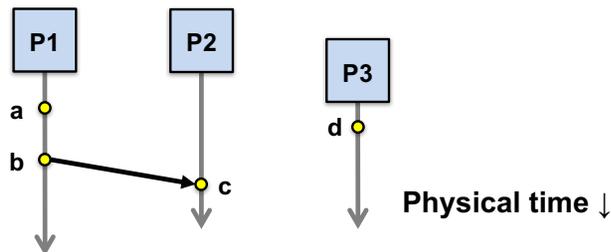
1. If **same process** and **a** occurs before **b**, then $a \rightarrow b$
2. If **c** is a message receipt of **b**, then $b \rightarrow c$
3. If $a \rightarrow b$ and $b \rightarrow c$, then $a \rightarrow c$



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Concurrent events

- Not all events are related by \rightarrow
- **a, d** not related by \rightarrow so **concurrent**, written as $a \parallel d$



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Lamport clocks: Objective

- We seek a **clock time** $C(a)$ for every event **a**

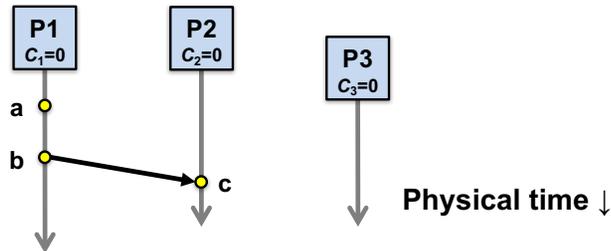
Plan: Tag events with clock times; use clock times to make distributed system correct

- Clock condition: If $a \rightarrow b$, then $C(a) < C(b)$

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The Lamport Clock algorithm

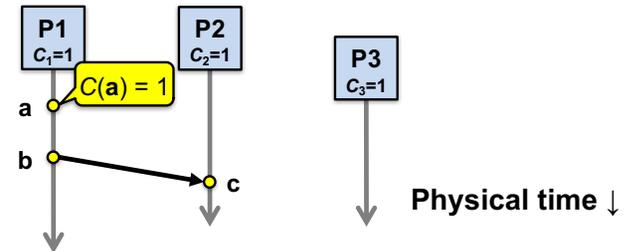
- Each process P_i maintains a local clock C_i
- Before executing an event, $C_i \leftarrow C_i + 1$



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The Lamport Clock algorithm

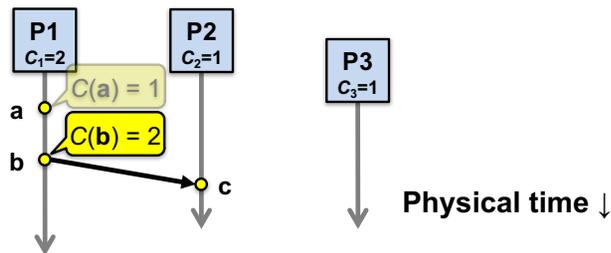
- Before executing an event a , $C_i \leftarrow C_i + 1$:
 - Set event time $C(a) \leftarrow C_i$



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The Lamport Clock algorithm

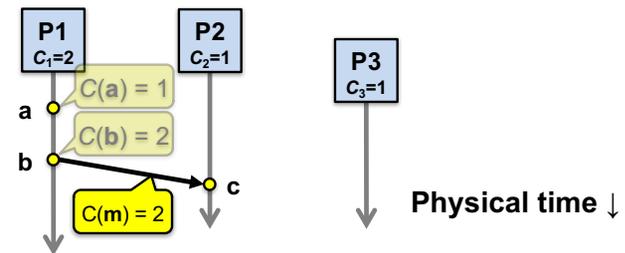
- Before executing an event b , $C_i \leftarrow C_i + 1$:
 - Set event time $C(b) \leftarrow C_i$



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The Lamport Clock algorithm

- Before executing an event b , $C_i \leftarrow C_i + 1$
- Send the local clock in the message m

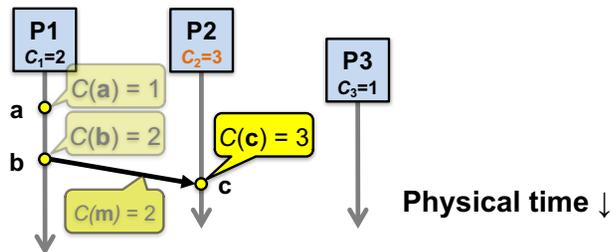


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The Lamport Clock algorithm

3. On process P_j receiving a message m :

- Set C_j and receive event time $C(c) \leftarrow 1 + \max\{C_j, C(m)\}$



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Lamport Timestamps: Ordering all events

- **Break ties** by appending the process number to each event:

1. Process P_i timestamps event e with $C_i(e).i$

2. $C(a).i < C(b).j$ when:

- $C(a) < C(b)$, or $C(a) = C(b)$ and $i < j$

- Now, for any two events a and b , $C(a) < C(b)$ or $C(b) < C(a)$
 - This is called a **total ordering** of events

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Making concurrent updates consistent

- Recall multi-site database replication:

- San Francisco (**P1**) deposited \$100:
- New York (**P2**) paid 1% interest:

We reached an **inconsistent state**

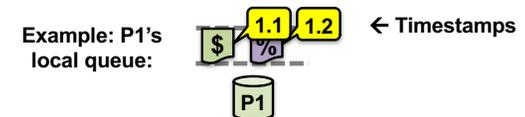
Could we design a system that uses **Lamport Clock total order** to make multi-site updates consistent?

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Totally-Ordered Multicast

Goal: All sites apply updates in (same) **Lamport clock order**

- Client sends update to **one** replica site j
 - Replica **assigns** it Lamport timestamp $C_j.j$
- **Key idea:** Place events into a sorted **local queue**
 - **Sorted** by increasing Lamport timestamps



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Totally-Ordered Multicast (Almost correct)

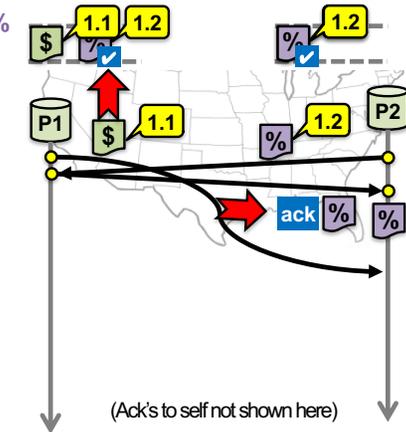
1. On **receiving** an update from **client**, broadcast to others (including yourself)
2. On **receiving** an **update from replica**:
 - a) Add it to your local queue
 - b) Broadcast an **acknowledgement message** to every replica (including yourself)
3. On **receiving** an **acknowledgement**:
 - Mark corresponding update **acknowledged** in your queue
4. **Remove and process** updates **everyone** has ack'ed from **head** of queue

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Totally-Ordered Multicast (Almost correct)

- P1 queues \$, P2 queues %
- P1 queues and **ack's** %
 - P1 marks % fully **ack'ed**
- P2 marks % fully **ack'ed**

✗ P2 processes %



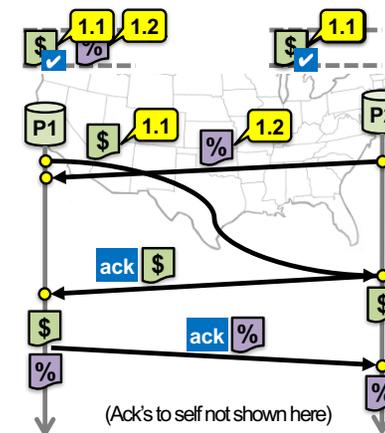
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Totally-Ordered Multicast (Correct version)

1. On **receiving** an update from **client**, broadcast to others (including yourself)
2. On **receiving or processing** an update:
 - a) Add it to your local queue, if **received** update
 - b) Broadcast an **acknowledgement message** to every replica (including yourself) **only from head of queue**
3. On **receiving** an **acknowledgement**:
 - Mark corresponding update **acknowledged** in your queue
4. **Remove and process** updates **everyone** has ack'ed from **head** of queue

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Totally-Ordered Multicast (Correct version)



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So, are we done?

- Does *totally-ordered multicast* solve the problem of *multi-site replication in general*?
- Not by a long shot!
- 1. Our protocol **assumed**:
 - No **node failures**
 - No **message loss**
 - No **message corruption**
- 2. All to all communication **does not scale**
- 3. **Waits forever** for message delays (**performance?**)

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Take-away points: Lamport clocks

- Can **totally-order** events in a distributed system: that's useful!
 - We saw an application of Lamport clocks for totally-ordered multicast
- **But**: while by construction, $a \rightarrow b$ implies $C(a) < C(b)$,
 - The converse is not necessarily true:
 - $C(a) < C(b)$ does not imply $a \rightarrow b$ (possibly, $a \parallel b$)

Can't use Lamport clock timestamps to infer causal relationships between events

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Wednesday Topic:
Vector Clocks &
Distributed Snapshots

Friday Precept:
RPCs in Go

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Why global timing?

- Suppose there were an **infinitely-precise and globally consistent** time standard
- That would be very handy. For example:
 1. *Who got last seat on airplane?*
 2. **Mobile cloud gaming**: *Which was first, A shoots B or vice-versa?*

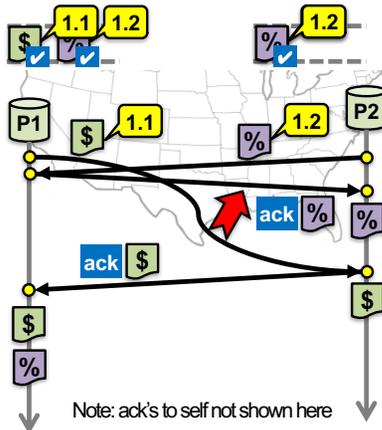


3. *Does this file need to be recompiled?*

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Totally-Ordered Multicast (Attempt #1)

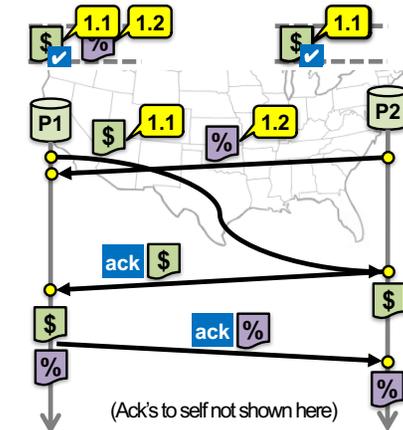
- P1 queues \$, P2 queues %
- P1 queues and ack's %
 - P1 marks % fully ack'ed
- P2 marks % fully ack'ed
 - P2 processes %
- P2 queues and ack's \$
 - P2 processes \$
- P1 marks \$ fully ack'ed
 - P1 processes \$, then %



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Totally-Ordered Multicast (Correct version)

- P1 queues \$, P2 queues %
- P1 queues %
- P2 queues and ack's \$
 - P2 processes \$
- P1 marks \$ fully ack'ed
 - P1 processes \$
 - P1 ack's %
- P1 marks % fully ack'ed
 - P1 processes %
- P2 marks % fully ack'ed
 - P2 processes %



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Time standards

- **Universal Time (UT1)**
 - In concept, based on astronomical observation of the sun at 0° longitude
 - Known as "Greenwich Mean Time"
- **International Atomic Time (TAI)**
 - Beginning of TAI is midnight on January 1, 1958
 - Each second is 9,192,631,770 cycles of radiation emitted by a Cesium atom
 - Has diverged from UT1 due to slowing of earth's rotation
- **Coordinated Universal Time (UTC)**
 - TAI + leap seconds, to be within 0.9 seconds of UT1
 - Currently TAI - UTC = 36

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VC application: Order processing

- Suppose we are running a **distributed order processing system**
- Each process = a different user
- Each event = an order
- A user has seen all orders with $V(\text{order}) < \text{the user's current vector}$

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