


COS 318: Operating Systems


Synchronization: Mutual Exclusion

Jaswinder Pal Singh
Computer Science Department
Princeton University


(<http://www.cs.princeton.edu/courses/cos318/>)



“Too Many Cookies” Problem




- ◆ Roommates Lance and Qizhe want a bag of cookies in the room at all times, but don't want to buy too many cookies
- ◆ They buy cookies independently, using the following sequence
 - Look in cabinet: Out of cookies
 - Leave for Wawa to buy cookies
 - Arrive at Wawa
 - Buy a bag of cookies
 - Arrive home and put cookies in cabinet




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“Too Many Cookies” Problem




	Qizhe	Lance
15:00	Look in cabinet: out of cookies	
15:05	Leave for Wawa	
15:10	Arrive at Wawa	Look in cabinet: out of cookies
15:15	Buy a bag of cookies	Leave for Wawa
15:20	Arrive home; put cookies away	Arrive at Wawa
15:25		Buy a bag of cookies
		Arrive home; put cookies away

- ◆ Oh No! Too many cookies.



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Using A Note?




Qizhe and Lance's Cookie Optimization Algorithm:

```

if (noCookies) { // check if roommate left a note
  if (noNote) {
    leave note; // let them know you went to Wawa
    buy cookies;
    remove note;
  }
}

```

- ◆ Any issue with this approach?



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Using A Note?

Qizhe

```
if (noCookies) {
  if (noNote) {
    leave note;
    buy cookies;
    remove note;
  }
}
```

Lance

```
if (noCookies) {
  if (noNote) {
    leave note;
    buy cookies;
    remove note;
  }
}
```



- ◆ Any issue with this approach?



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Why Solution #1 Does Not Work

Qizhe

```
3:00
3:05
3:10 if (noMilk) {
3:15   if (noNote) {
3:20     leave Note;
3:25     buy milk;
3:30     remove Note } }
```

Lance

```
if (noMilk) {
  if (noNote) {
    leave Note;
    buy milk;
    remove Note } }
```



Threads can get context-switched at any time !



Possible Solution #2: Leave Note First

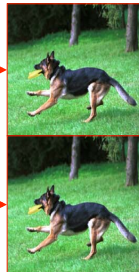
Qizhe

```
leave noteA
if (noNoteB) {
  if (noCookies)
    buy cookies
}
remove noteA
```



Lance

```
leave noteB
if (noNoteA) {
  if (noCookies)
    buy cookies
}
remove noteB
```



Didn't buy cookies

Didn't buy cookies

- ◆ Does this method work?



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Possible Solution #3: One Spin-waits

- ◆ Problem was that threads checked once and moved on
 - So have one of them spin-wait on the note

Qizhe

```
leave noteA
while (noteB)
  do nothing;
if (noCookies)
  buy cookies;
remove noteA
```

Lance

```
leave noteB
if (noNoteA) {
  if (noCookies)
    buy cookies
}
remove noteB
```

- ◆ Would this fix the problem?
- ◆ Yes, but complicated, different code for different threads, busy waiting wasteful, and not fair



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Threads Example: Shared Counter

- ◆ Google gets millions of hits a day. Uses multiple threads (on multiple processors) to speed things up.
- ◆ Simple shared state error: each thread increments a shared counter to track the number of hits today:

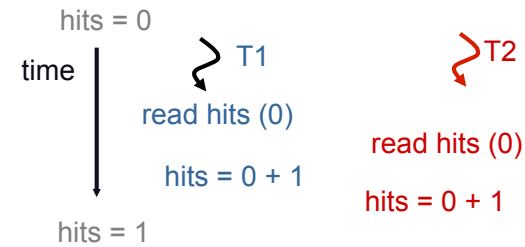
```
...  
hits = hits + 1;  
...
```

- ◆ What happens when two threads execute this code concurrently?



Problem with Shared Counters

- ◆ One possible result: lost update!

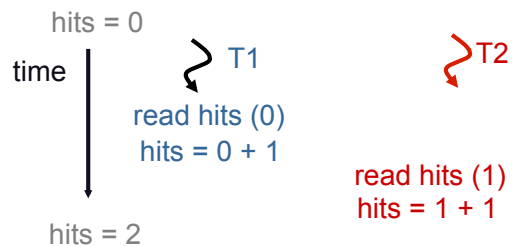


- ◆ **Another possible result: everything works**
 - Bugs are frequently intermittent. Makes debugging hard.
 - This is called a “race condition”



Problem with Shared Counters

- ◆ Another possible result: everything works!



- ◆ **Another possible result: everything works**
 - Bugs are frequently intermittent. Makes debugging hard.
 - This is called a “race condition”



Race Conditions

- ◆ Race condition: accesses to shared state that can lead to a timing dependent error
 - whether it happens depends on how threads are scheduled
- ◆ Difficult to avoid because:
 - **Must make sure all possible schedules are safe.**
 - Number of possible schedule permutations is huge.
 - One or more of them may be “bad”
 - They are intermittent
 - Timing dependent => small changes can hide or reveal bug
 - Adding a print statement
 - Running on a different machine



It's Actually Even Worse

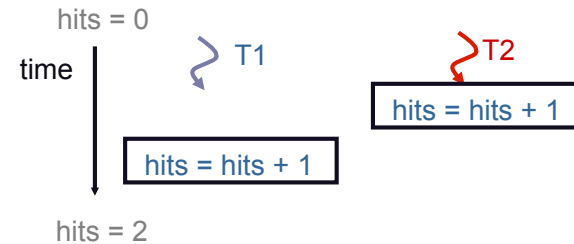
- ◆ Compilers reorder instruction issue within a thread
 - To optimize register usage and hence run code faster
- ◆ Hardware reorders instruction execution/completion
 - E.g. write buffers, etc
- ◆ All done to optimize execution speed
- ◆ But they don't know about multiple threads and issues across them



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Preventing Race Conditions: Atomicity

- ◆ Atomic unit = instruction sequence guaranteed to execute indivisibly (also called a "critical section").
 - If two threads execute the same atomic unit at the same time, one thread will execute the whole sequence before the other begins



- ◆ How to make multiple instrs seem like an atomic one?



Providing Atomicity

- ◆ Have hardware provide better primitives than atomic load and store.
- ◆ Build higher-level programming abstractions on this new hardware support.
- ◆ Example: using locks as an atomic building block

Acquire --- wait until lock is free, then grab it

Release --- unlock/release the lock, waking up a waiter if any

These must be atomic operations --- if two threads are waiting for the lock, and both see it is free, only one grabs it!



Preventing Race Conditions: Atomicity

- ◆ Cookies problem

```
Acquire(lock);  
if (noCookies)  
    buy cookies;  
Release(lock);
```

} Critical section

Desirable Properties:

1. At most one holder, or thread in critical section, at a time (**safety**)
2. If no one is holding the lock, an acquire gets the lock (**progress**)
3. If all lock holders finish and there are no higher priority waiters, waiter eventually gets the lock (**progress**)



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Rules for Using Locks

- ◆ Lock is initially free
- ◆ Always acquire before accessing shared data structure
- ◆ Always release after finishing with shared data
 - Only the lock holder can release
- ◆ Don't access shared data without lock



Some Definitions

- ◆ **Synchronization:**
 - Ensuring proper cooperation among threads
 - Mutual exclusion, event synchronization
- ◆ **Mutual exclusion:**
 - Ensuring that only one thread does a particular thing at a time. One thread doing it excludes another from doing it at the same time.
- ◆ **Critical section:**
 - Piece of code that only one thread can "be in" at a given time. Only one thread at a time will be allowed to get into the section of code.
- ◆ **Lock:** prevents someone from doing something
 - Lock before entering critical section, before accessing shared data
 - Unlock when leaving, after done accessing shared data
 - Wait if locked
- ◆ **Event synchronization:**
 - Making sure an event in one thread does not happen before/after an event in another thread



Implementing Mutual Exclusion (Locks)

What makes a good solution?

- ◆ Only one process/thread inside a critical section at a time
- ◆ No assumptions need to be made about CPU speeds
- ◆ A process/thread inside a critical section should not be blocked by any process outside the critical section
- ◆ No one waits forever

- ◆ Should work for multiprocessors
- ◆ Should allow same code for all processes/threads



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Simple Lock Variables

```
Acquire(lock) {                               Release(lock) {
while (lock.value == 1)                         lock.value = 0;
;                                               }
lock.value = 1;
}

Thread 1:                                       Thread 2:
Acquire(lock) {                                 Acquire(lock) {
while (lock.value == 1)                         while (lock.value == 1)
;                                               ;
(context switch) →                               (context switch)
lock.value = 1; ←                               (context switch)
}                                               lock.value = 1;
(context switch) →                               }
lock.value = 1;                               }
```



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Prevent Context Switches in Critical Section

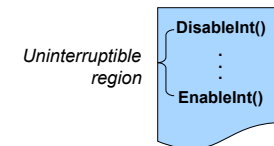
- ◆ On a uniprocessor, operations are atomic as long as a context switch doesn't occur
- ◆ Context switches are caused either by actions the thread takes (e.g. traps etc) or by external interrupts
- ◆ The former can be controlled
- ◆ Disable interrupts during certain portions of code?
 - Delay the handling of external events



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Why Enable or Disable Interrupts

- ◆ Interrupts are important
 - Process I/O requests (e.g. keyboard)
 - Implement preemptive CPU scheduling
- ◆ Disabling interrupts can be helpful
 - Introduce uninterruptible code regions
 - Think sequentially most of the time
 - **Delay** handling of external events



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“Disable Interrupts” to Implement Mutex

```
Acquire(lock) {
  disable interrupts;
  while (lock.value != 0)
    ;
  lock.value = 1;
  enable interrupts;
}

Release(lock) {
  disable interrupts;
  lock.value = 0;
  enable interrupts;
}
```

- ◆ Issues:
 - May disable interrupts forever
 - Not designed for user code to use
 - Does not work with multiprocessors



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Fix “Disable Forever” problem?

```
Acquire(lock) {
  disable interrupts;
  while (lock.value != 0) {
    enable interrupts;
    disable interrupts;
  }
  lock.value = 1;
  enable interrupts;
}

Release(lock) {
  disable interrupts;
  lock.value = 0;
  enable interrupts;
}
```

Disable interrupts only when accessing lock.value variable

Issues:

- Consume CPU cycles
- Won't work with multiprocessors (like all attempts above)



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Another Implementation

```
Acquire(lock) {
    disable interrupts;
    if (lock.value != 0)
    {
        Enqueue me for lock;
        Yield();
    }
    lock.value = 1;
    enable interrupts;
}

Release(lock) {
    disable interrupts;
    if (anyone in queue) {
        Dequeue a thread;
        make it ready;
    }
    lock.value = 0;
    enable interrupts;
}
```

Avoid busy-waiting

Issues

- Working for multiprocessors



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Atomic Operations

- ◆ A thread executing an atomic instruction can't be preempted or interrupted while it's doing it
- ◆ Atomic operations on same memory value are serialized
 - **Even on multiprocessors!**
 - Result is consistent with some sequential ordering of operations
 - Without atomic ops, simultaneous writes by different threads may produce a garbage value, or read that happens simultaneously with a write may read garbage value
- ◆ Don't usually require special privileges, can be user level



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Peterson's Algorithm

- ◆ See textbook

```
int turn;
int interested[N];

void enter_region(int process)
{
    int other;

    other = 1 - process;
    interested[process] = TRUE;
    turn = process;
    while(turn == process && interested[other] == TRUE);
}
```

- ◆ L. Lamport, "A Fast Mutual Exclusion Algorithm," *ACM Trans. on Computer Systems*, 5(1):1-11, Feb 1987.
 - 5 writes and 2 reads



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Atomic Read-Modify-Write Instructions

- ◆ LOCK prefix in x86
 - Make a specific of set instructions atomic
 - Can be used to implement Test&Set
- ◆ Exchange (xchg, x86 architecture)
 - Swap register and memory
 - Atomic (even without LOCK)
- ◆ Fetch&Add or Fetch&Op
 - Atomic instructions for large shared memory multiprocessors
- ◆ Load linked and store conditional (LL-SC)
 - Two separate instructions (LL, SC) that are used together
 - Read value in one instruction (load linked)
 - Do some operations;
 - When time to store, check if value has been modified. If not, ok; otherwise, jump back to start



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A Simple Solution with Test&Set

- ◆ Define TAS(lock)
 - If successfully set (wasn't already set when tested but this operation set it), return 1;
 - Otherwise, return 0;

- ◆ Any issues with the following solution?

```
Acquire(lock) {
    while (!TAS(lock.value))
        ;
}

Release(lock.value) {
    lock.value = 0;
}
```



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Mutex with Less Waiting?

```
Acquire(lock) {
    while (!TAS(lock.guard))
        ;
    if (lock.value) {
        enqueue the thread;
        block and lock.guard = 0;
    } else {
        lock.value = 1;
        lock.guard = 0;
    }
}

Release(lock) {
    while (!TAS(lock.guard))
        ;
    if (anyone in queue) {
        dequeue a thread;
        make it ready;
    } else {
        lock.value = 0;
        lock.guard = 0;
    }
}
```

- ◆ Separate access to lock variable from value of it



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Example: Protect a Shared Variable

```
Acquire(lock); /* system call */
count++;
Release(lock) /* system call */
```

- ◆ Acquire(mutex) system call
 - Pushing parameter, sys call # onto stack
 - Generating trap/interrupt to enter kernel
 - Jump to appropriate function in kernel
 - Verify process passed in valid pointer to mutex
 - Minimal spinning
 - Block and unblock process if needed
 - Get the lock
- ◆ Execute “count++;”
- ◆ Release(mutex) system call



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Available Primitives and Operations

- ◆ Test-and-set
 - Works at either user or kernel level
- ◆ System calls for block/unblock
 - **Block** takes some token and goes to sleep
 - **Unblock** “wakes up” a waiter on token



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Block and Unblock System Calls

Block(lock)

- Spin on lock.guard
- Save the context to TCB
- Enqueue TCB to lock.q
- Clear lock.guard
- Call scheduler

Unblock(lock)

- Spin on lock.guard
- Dequeue a TCB from lock.q
- Put TCB in ready queue
- Clear lock.guard



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Always Block

```

Acquire(lock) {
    while (!TAS(lock.value))
        Block( lock );
}

Release(lock) {
    lock.value = 0;
    Unblock( lock );
}
    
```

- ◆ Good
 - Acquire won't make a system call if TAS succeeds
- ◆ Bad
 - TAS instruction locks the memory bus
 - Block/Unblock still has substantial overhead



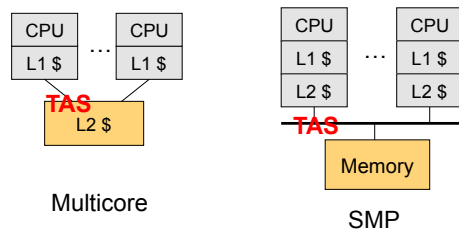
Always Spin

```

Acquire(lock) {
    while (!TAS(lock.value))
        while (lock.value)
            ;
}

Release(lock) {
    lock.value = 0;
}
    
```

- ◆ Two spinning loops in Acquire() ?



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Optimal Algorithms

- ◆ What is the optimal solution to spin vs. block?
 - Know the future
 - Exactly when to spin and when to block
- ◆ But, we don't know the future
 - There is **no** online optimal algorithm
- ◆ Offline optimal algorithm
 - Afterwards, derive exactly when to block or spin ("what if")
 - Useful to compare against online algorithms



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Competitive Algorithms

- ◆ An algorithm is c -competitive if for every input sequence σ

$$C_A(\sigma) \leq c \times C_{opt}(\sigma) + k$$

- c is a constant
- $C_A(\sigma)$ is the cost incurred by algorithm A in processing σ
- $C_{opt}(\sigma)$ is the cost incurred by the optimal algorithm in processing σ
- ◆ What we want is to have c as small as possible
 - Deterministic
 - Randomized



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Constant Competitive Algorithms

```

Acquire(lock, N) {
    int i;

    while (!TAS(lock.value)) {
        i = N;
        while (!lock.value && i)
            i--;

        if (!i)
            Block(lock);
    }
}
    
```

- ◆ Spin up to N times if the lock is held by another thread
- ◆ If the lock is still held after spinning N times, block
- ◆ If spinning N times is equal to the context-switch time, what is the competitive factor of the algorithm?



Approximate Optimal Online Algorithms

- ◆ Main idea
 - Use past to predict future
- ◆ Approach
 - Random walk
 - Decrement N by a unit if the last Acquire() blocked
 - Increment N by a unit if the last Acquire() didn't block
 - Recompute N each time for each Acquire() based on some lock-waiting distribution for each lock

- ◆ Theoretical results
 - $E C_A(\sigma(P)) \leq (e/(e-1)) \times E C_{opt}(\sigma(P))$

The competitive factor is about 1.58.



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The Big Picture

Concurrent applications/software				
Shared Objects	Barrier	Bounded Buffer		
High-Level Atomic API (portable)	Mutex	Semaphores	Monitors/Condition Variables	Send/Recv
Low-Level Atomic Ops (specific)	Load/store	Interrupt disable/enable	Test&Set	Other atomic instructions
	Interrupts (I/O, timer)	Multiple processors		



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Summary

- ◆ Disabling interrupts for mutex
 - There are many issues
 - When making it work, it works for only uniprocessors
- ◆ Atomic instruction support for mutex
 - Atomic load and stores are not good enough
 - Test&set and other instructions are the way to go
- ◆ Competitive spinning
 - Spin at the user level most of the time
 - Make no system calls in the absence of contention
 - Have more threads than processors

