Spanner: Google's Globally-Distributed Database



COS 418: *Distributed Systems* Precept 6

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Agenda

- Review {linear, serial, strict serial}izability
- Review concurrency controls
- Spanner
- Pro tips for Assignment 3

ACID properties of transactions

- <u>Atomicity</u>: Either all constituent operations of the transaction complete successfully, or **none** do
- <u>Consistency</u>: Each transaction in isolation preserves a set of integrity constraints on the data
- **Isolation:** Transactions' behavior not impacted by presence of **other concurrent transactions**
- **Durability:** The transaction's **effects survive failure** of volatile (memory) or non-volatile (disk) storage

Review *izability

Some context

- Terms come from two different communities (database and distributed systems).
 Overloaded!
- All refer to interleaving operations
- Definitions
 - Operation: typically refers to a single access operation (e.g., read, write)
 - Transaction: one or more operations that must be committed atomically

Linearizability

- Guarantee for a single operation on a single object
- Informally, writes should appear instantaneously within the system
- All later reads as defined by wall-clock time (i.e., real-time) reflect the written value or some later written value
- 'Strong Consistency' in CAP theorem
 - Yes, we use consistency in ACID to mean something different

Serializability

- Guarantee for transactions, or one or more operations on one or more objects
- A set of transactions over some objects should execute as though each transaction ran in *some* serial order (doesn't specify which one!)
- No real-time (i.e., world-clock) constraints; in other words, no deterministic order for transactions
- 'Isolation' in ACID properties

Strict serializability

- Linearizability + serializability
- Transactions have some serial behavior and that behavior corresponds to wall-clock time
- Straightforward to reason about for nonoverlapping transactions
- What about overlapping transactions?

Review concurrency controls

ACID properties of transactions

- Atomicity: write-ahead logs and checkpoints
- <u>Consistency</u>: application logic
- Isolation: concurrency controls (locks, 2PL, OCC, MVCC)
- **Durability:** write-ahead logs and checkpoints

ACID properties of transactions

- Atomicity: write-ahead logs and checkpoints
- <u>Consistency</u>: application logic

Isolation: concurrency controls (locks, 2PL, OCC, MVCC)

• **Durability:** write-ahead logs and checkpoints

Concurrency controls

- Global lock: simple, but slow
- Per-object lock: doesn't guarantee serializability (isolation)
- 2PL: gives serializability, but leaves opportunities on the table and can deadlock
- OCC: performs well if few conflicts, but poorly if many conflicts
- MVCC: snapshot isolation, not serializability

Distributed Transactions

Consider partitioned data over servers



- Why not just use 2PL?
 - Grab locks over entire read and write set
 - Perform writes
 - Release locks (at commit time)

Consider partitioned data over servers



- How do you get serializability?
 - On single machine, single COMMIT op in the WAL
 - In distributed setting, assign global timestamp to txn (at sometime after lock acquisition and before commit)
 - Centralized txn manager
 - Distributed consensus on timestamp (not all ops)

Strawman: Consensus per txn group?



- Single Lamport clock, consensus per group?
 - Linearizability composes!
 - But doesn't solve concurrent, non-overlapping txn problem

Spanner: Google's Globally-Distributed Database

OSDI 2012

Google's Setting

- Dozens of zones (datacenters)
- Per zone, 100-1000s of servers
- Per server, 100-1000 partitions (tablets)
- Every tablet replicated for fault-tolerance (e.g., 5x)

Scale-out vs. fault tolerance



- Every tablet replicated via Paxos (with leader election)
- So every "operation" within transactions across tablets actually a replicated operation within Paxos RSM
- Paxos groups can stretch across datacenters!
 (COPS took same approach *within* datacenter)

Disruptive idea:

Do clocks **really** need to be arbitrarily unsynchronized?

Can you engineer some max divergence?

TrueTime

• "Global wall-clock time" with bounded uncertainty



Consider event e_{now} which invoked tt = TT.new(): Guarantee: tt.earliest <= t_{abs}(e_{now}) <= tt.latest

Timestamps and TrueTime



Commit Wait and Replication



Client-driven transactions

Client:

- 1. Issues reads to leader of each tablet group, which acquires read locks and returns most recent data
- 2. Locally performs writes
- 3. Chooses coordinator from set of leaders, initiates commit
- 4. Sends commit message to each leader, include identify of coordinator and buffered writes
- 5. Waits for commit from coordinator

Commit Wait and 2-Phase Commit

- On commit msg from client, leaders acquire local write locks
 - If non-coordinator:
 - Choose prepare ts > previous local timestamps
 - Log prepare record through Paxos
 - Notify coordinator of prepare timestamp
 - If coordinator:
 - Wait until hear from other participants
 - Choose commit timestamp >= prepare ts, > local ts
 - Logs commit record through Paxos
 - Wait commit-wait period
 - Sends commit timestamp to replicas, other leaders, client
- All apply at commit timestamp and release locks

Commit Wait and 2-Phase Commit



Example



Time	<8	8	15
My friends	[X]	[]	
My posts			[P]
X's friends	[me]	[]	

Read-only optimizations

- Given global timestamp, can implement read-only transactions lock-free (snapshot isolation)
- Step 1: Choose timestamp s_{read} = TT.now.latest()
- Step 2: Snapshot read (at s_{read}) to each tablet
 Can be served by any up-to-date replica

Disruptive idea:

Do clocks **really** need to be arbitrarily unsynchronized?

Can you engineer some max divergence?

TrueTime Architecture



Compute reference [earliest, latest] = now $\pm \epsilon$

TrueTime implementation

- now = reference now + local-clock offset
 - ϵ = reference ϵ + worst-case local-clock drift
 - = 1ms + 200 µs/sec



- What about faulty clocks?
 - Bad CPUs 6x more likely in 1 year of empirical data

Known unknowns > unknown unknowns

Rethink algorithms to reason about uncertainty

Pro tips

The single greatest source of headand heartache

Not following Figure 2 (and, more generally, the paper) exactly

Ex. 1: heartbeat RPCs

- These are just empty AppendEntries RPCs!
- That means you must handle all the same checks as you would for AppendEntries
- Otherwise, bad things can happen
- If just return true, leader thinks that follower's log matches the leader's log up through prevLogIndex

Ex. 2: handling conflicts

- If the follower's log isn't as long as the leaders, conflict!
- Can't just truncate follower's log after prevLogIndex. Only do so if an existing entry conflicts with the leader's
- If all entries match, follower must keep any additional log entries it has. Why?

Ex. 3: reset timers precisely!

- There are only three scenarios
 - Receive AppendEntries RPC from current leader
 - Start election
 - Grant vote to another peer
- Tempting to reset timers everywhere; why not?

Ex. 4: (re)start elections

- We must start a new election if our election timer fires, even if we were already a candidate in the middle of an election
- What can happen if we don't?

Ex. 5: abdicating the throne

- No matter what happens, if we receive a request with a higher term, convert to follower and update currentTerm
- Don't forget to also change votedFor!

Ex. 6: when and when not to be lazy

- When checking whether a log is up to date, follow section 5.4! Checking length is insufficient
- If a step says 'reply false', return immediately and don't execute subsequent steps

Ex. 7: applying log entries

- If the commitIndex (index of highest log entry known to be committed) is ever greater than lastApplied (index of highest log entry applied to state machine), apply!
- Don't need to do right away, but should have dedicated way of handling so we don't have multiple channels trying to apply the same entry
- P.S. don't forget to check commitIndex > lastApplied...

Ex. 8: matchIndex vs. nextIndex

- nextIndex is optimistic: assume that follower has all entries from previous interaction unless we received a negative response
- matchIndex is conservative: only update when we know a higher index log entry has been known to be replicated

Ex. 9: ignore RPCs from old terms!

• Yeah, don't forget that

Monday lecture

Conflicting/concurrent writes in eventual/causal systems: OT + CRDTs

(aka how Google Docs works)