# Introduction to Shape Analysis

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**Princeton University** 

COS 526, Fall 2014



### **Motivation**

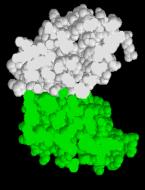


### Large repositories of 3D data are becoming available



Computer Graphics





Molecular Biology



Medicine



Cultural Heritage



**Computer Vision** 

### **Lecture Outline**



Introduction

**Applications** 

**Problems** 

Feature detection

### **Lecture Outline**



#### Introduction

Applications -

#### **Problems**

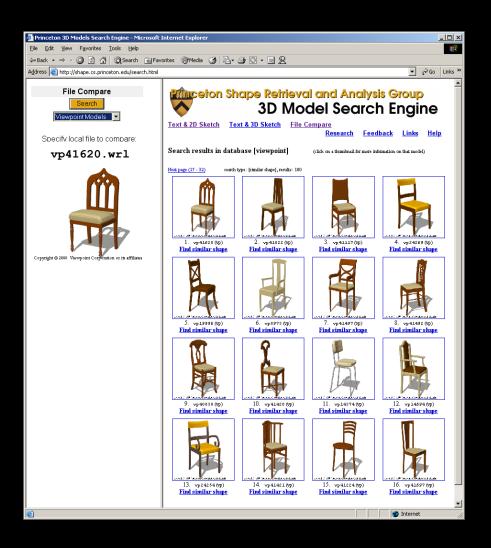
Feature detection



- Computer graphics
- Geometric modeling
- Archaeology
- Urban planning
- Paleontology
- Molecular bio
- Medicine
- Art



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Reconstructing Frescoes from Thera (Weyrich, Brown, Rusinkiewicz, et al.)

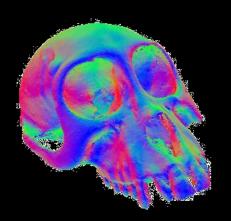


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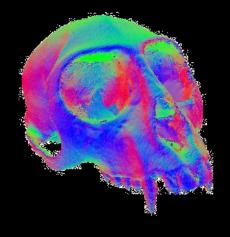


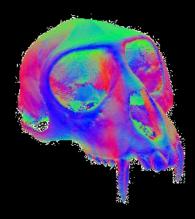


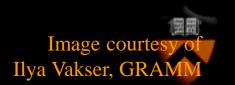
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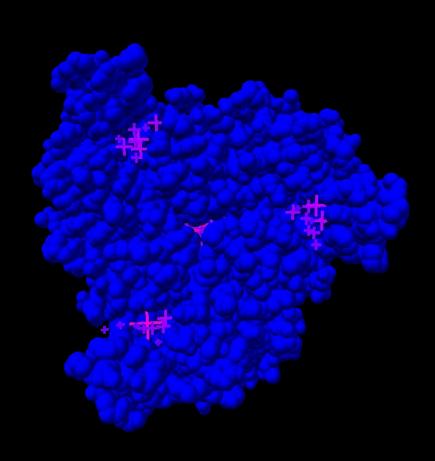








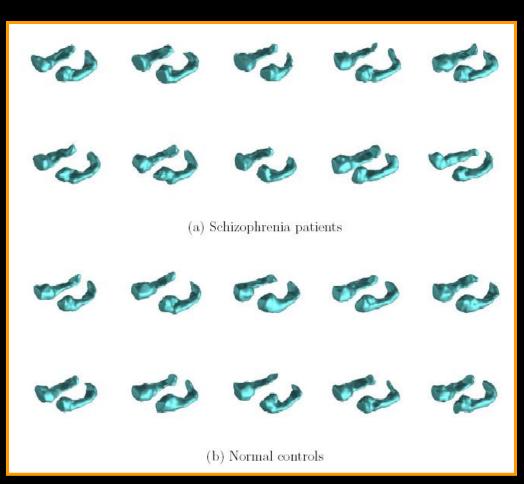
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#### **Examples:**

- Computer graphics
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Hippocampus-amygdala study in schizophrenia



- Computer graphics
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### **Lecture Outline**



Introduction

**Applications** 

#### Problems -

Feature detection

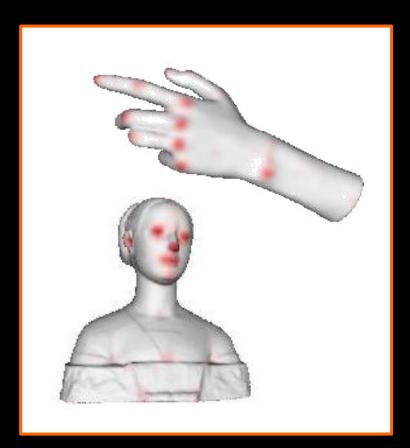


- Feature detection
- Segmentation
- Labeling
- Registration
- Matching
- Recognition
- Classification
- Clustering
- Retrieval



#### **Examples:**

- > Feature detection
- Segmentation
- Labeling
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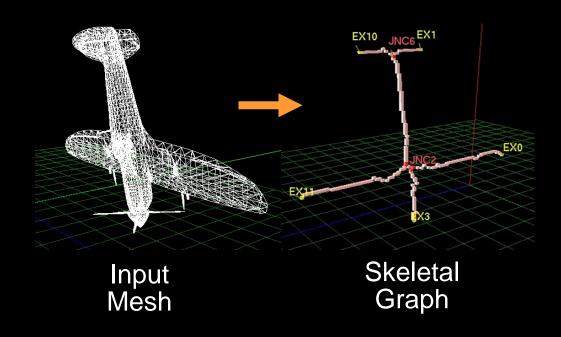
**Schelling Points** 

"How can we find significant geometric features robustly?"



#### **Examples:**

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- Clustering

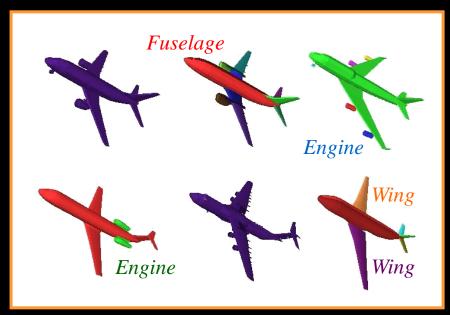


"How can we decompose a 3D model into its parts?"



#### **Examples:**

- Feature detection
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Semantic Labels

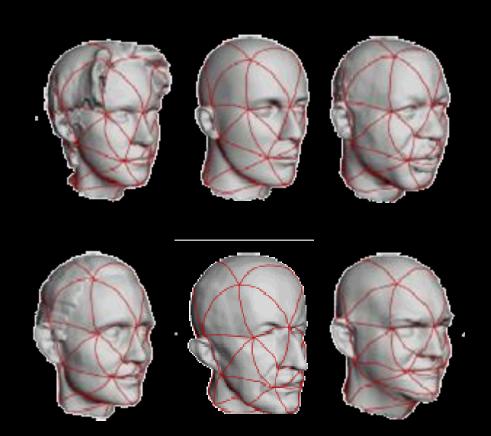
(Golovinskiy, Lee, et al.)

"How can we decompose a 3D model into its parts?"



#### **Examples:**

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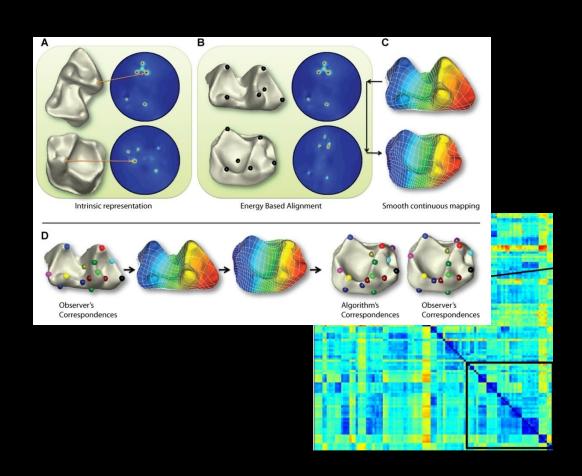


"How can we align features of 3D models?"



#### **Examples:**

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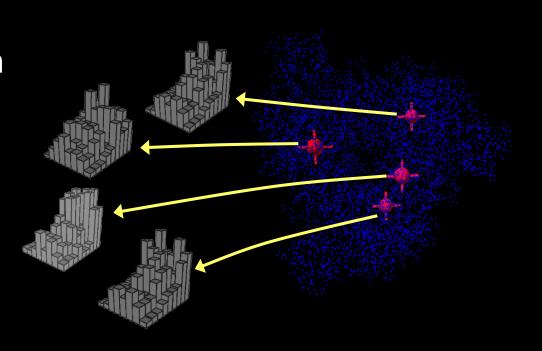


"How can we compute a measure of geometric similarity?"



#### **Examples:**

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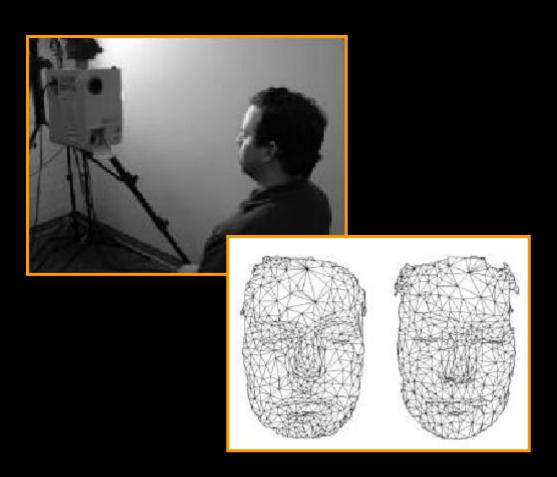
Harmonic Shape Descriptors

"How can we find similar 3D shapes in a database?"



#### **Examples:**

- Feature detection
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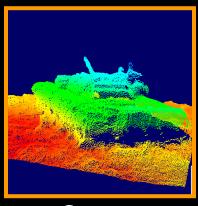


"How can we find a given 3D model in a large database?"



#### **Examples:**

- Feature detection
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Query



Classes

"How can we determine the class of a 3D model?"



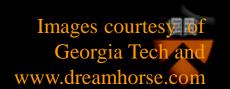
#### **Examples:**

- Feature detection
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"How can we learn classes of 3D models automatically?"

# A Quick Diversion ...



### Which is harder to analyze?



3D Model



2D Image

### **Lecture Outline**



Introduction

**Applications** 

**Problems** 

Feature detection

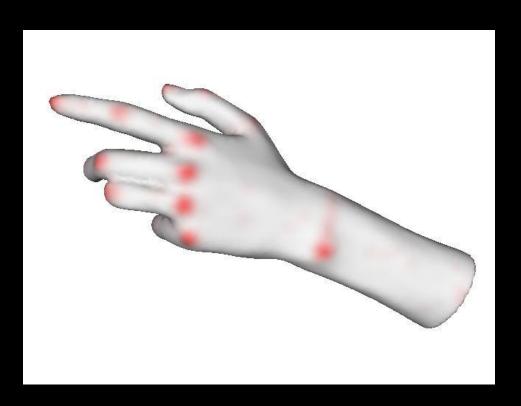


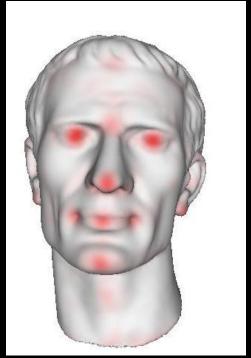
### **Features**



### Definition (Merriam-Webster)"

• "a prominent characteristic"



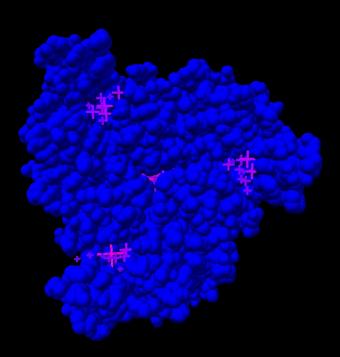


### **Point Features**



#### **Applications:**

- Maintaining shape features as process mesh
- Matching shape features as align meshes
- Reasoning about part decomposition
- Visualization
- etc.

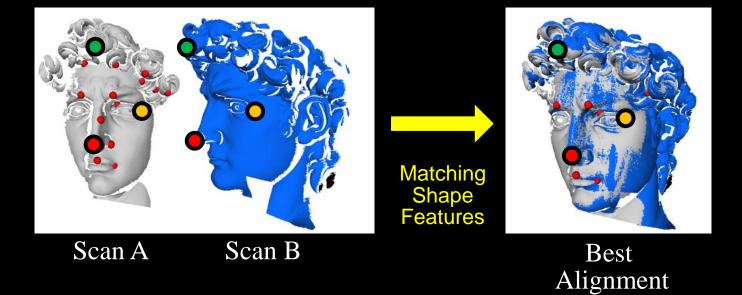


### **Point Features**



#### **Applications:**

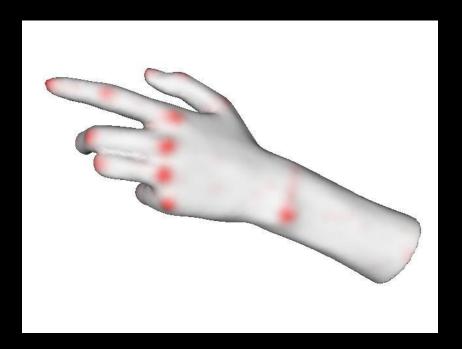
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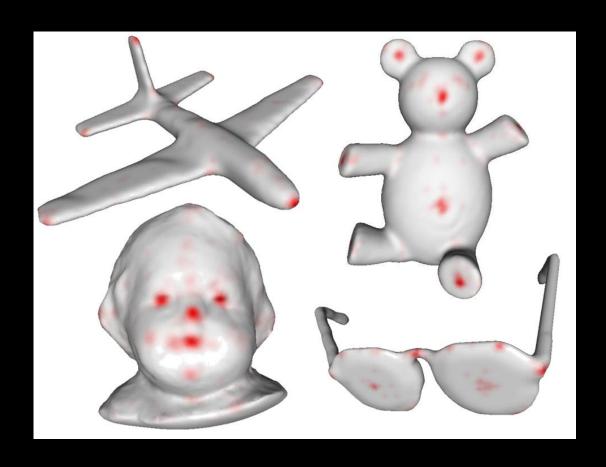
#### Goals:

- Invariant to transformations
- Robust to small surface deviations (holes, noise, etc.)
- Common across different surfaces in same class
- Semantic?





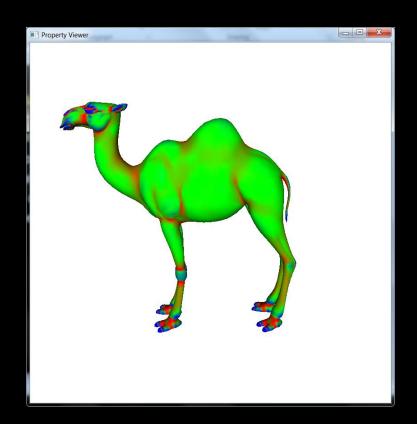
### Algorithmic methods to detect feature points?





### Some relevant properties

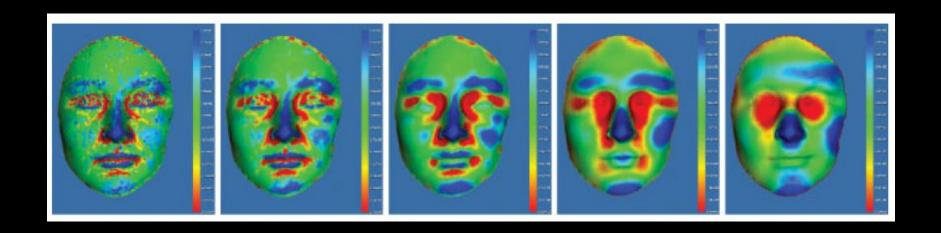
Average geodesic distance
Gauss curvature
Differences of curvature
Shape diameter function
etc.





#### Multiscale methods

Many methods consider scale-space persistence



# **Feature Point Study**



#### Ask people on the Amazon Mechanical Turk



# **Key question**



How should we ask people which points are salient?

# **Key question**



How should we ask people which points are salient?

"Please select salient points"

### **Key question**



### How should we ask people which points are salient?

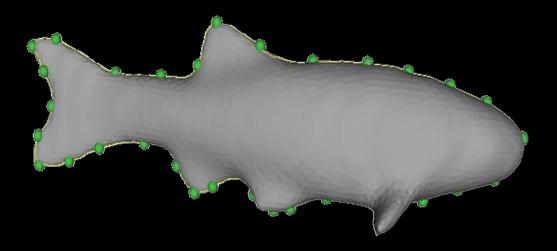
- "Please select salient points"
- Please select a pattern of points from which another person can recognize the object's class by viewing only those points

### **Key question**



### How should we ask people which points are salient?

- "Please select salient points"
- Please select a pattern of points from which another person can recognize the object's class by viewing only those points

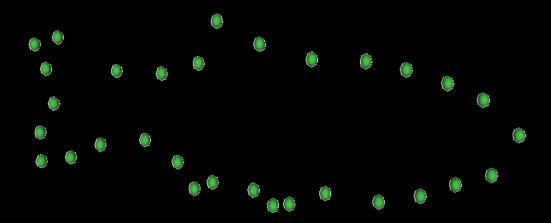


### Key question



### How should we ask people which points are salient?

- "Please select salient points"
- Please select a pattern of points from which another person can recognize the object's class by viewing only those points



### Schelling approach



### We asked people to:

Please select points that you think other people will select

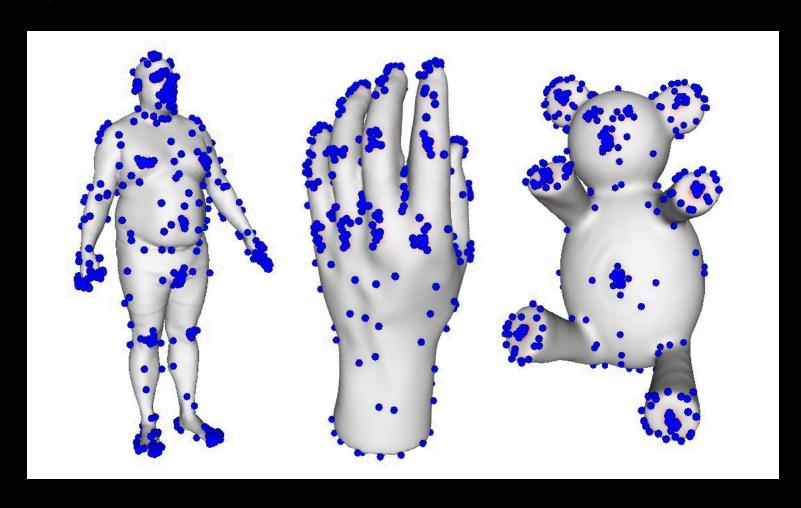
### Based on the "focal point" theory of [Schelling60]

 A solution that people tend to use in the absence of communication, because it seems natural, special or relevant to them

### **Schelling Feature Points**



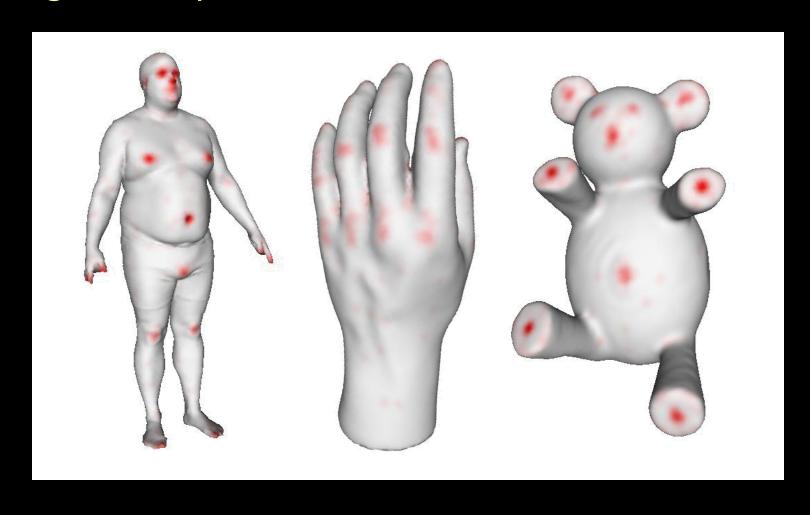
### Schelling feature points



### **Schelling Feature Points**



### Schelling feature point distributions



### Local properties

- Curvatures
- Mesh Saliency
- HKS at small t

### Global properties

- HKS at large t
- SDF [Shapira 08]
- Symmetry
- Segment Center
- AGD
- Etc.

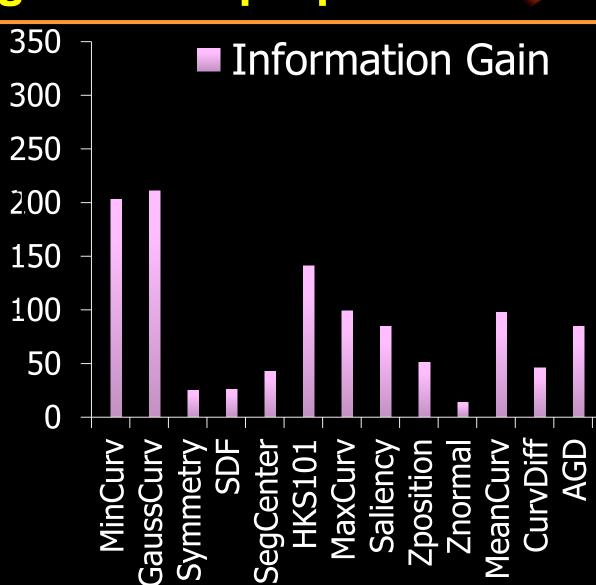


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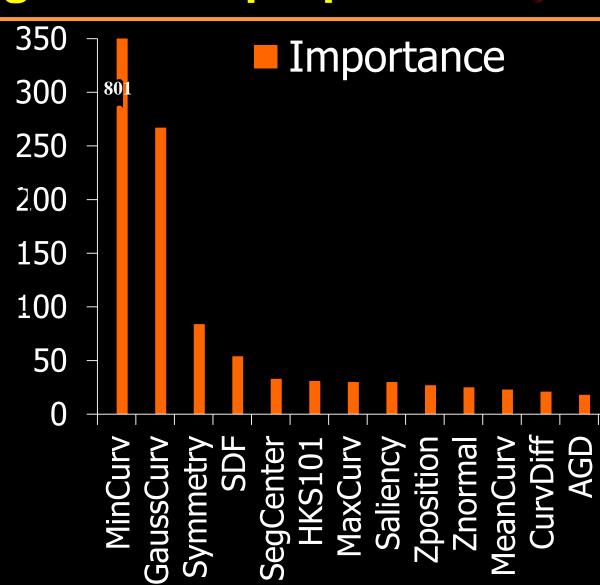


### Local properties

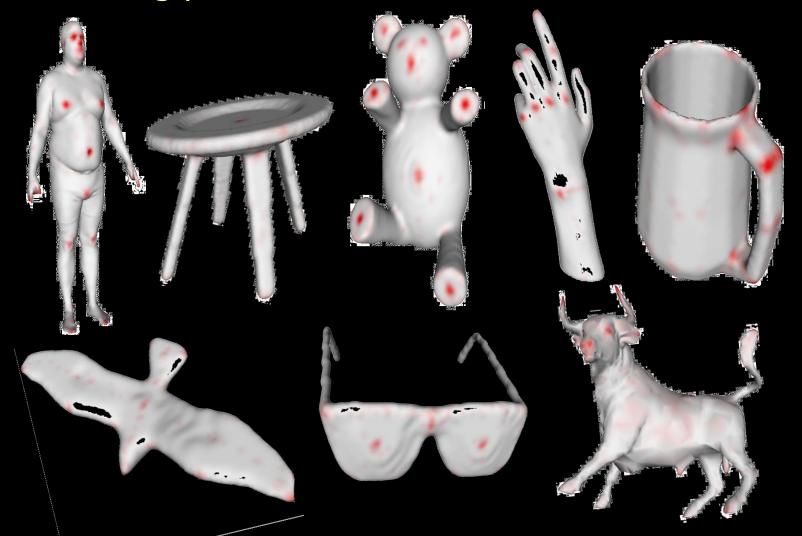
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### Global properties

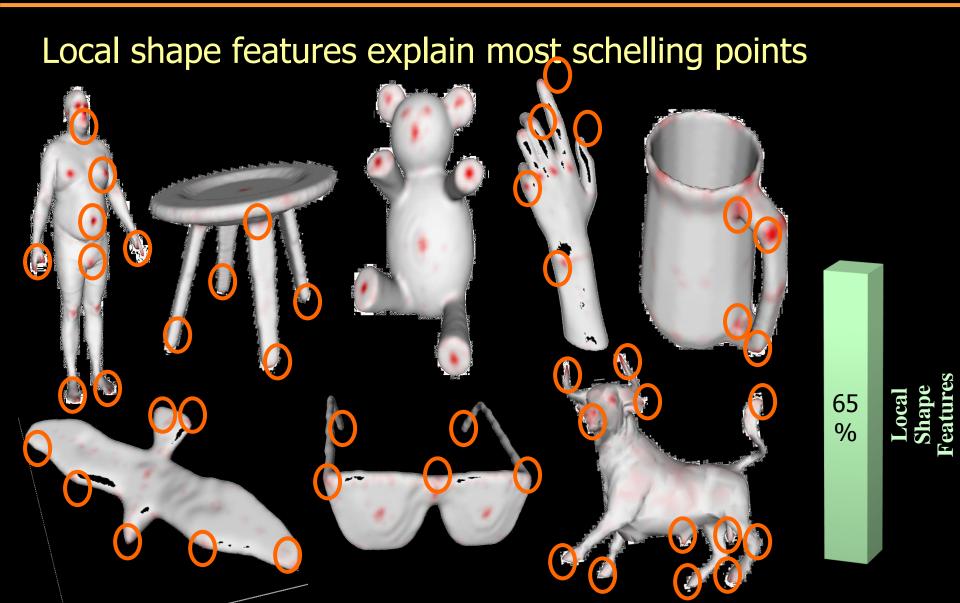
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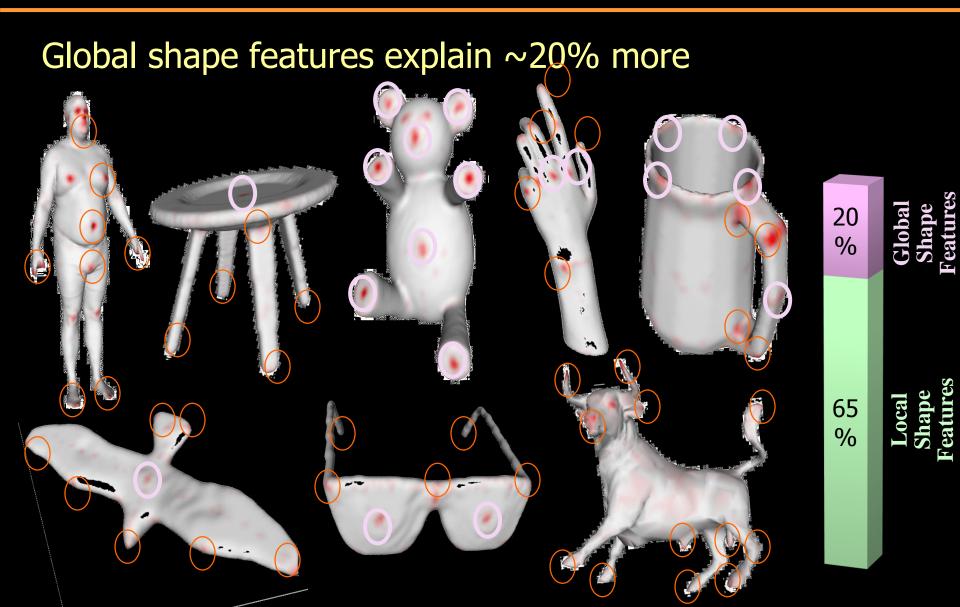
### Schelling point distribution



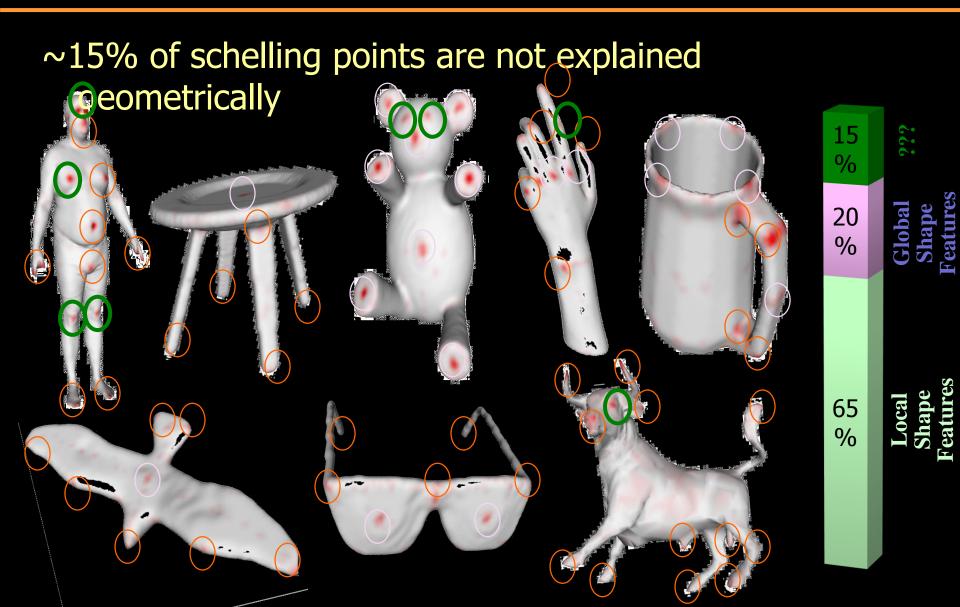








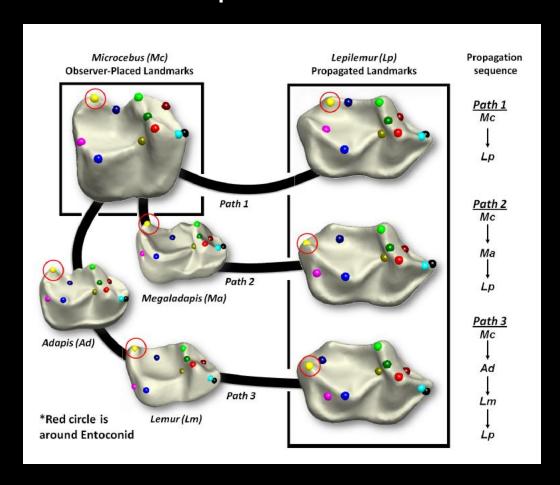




### Summary



### Geometric analysis can yield insights into features and relationships in 3D surface data

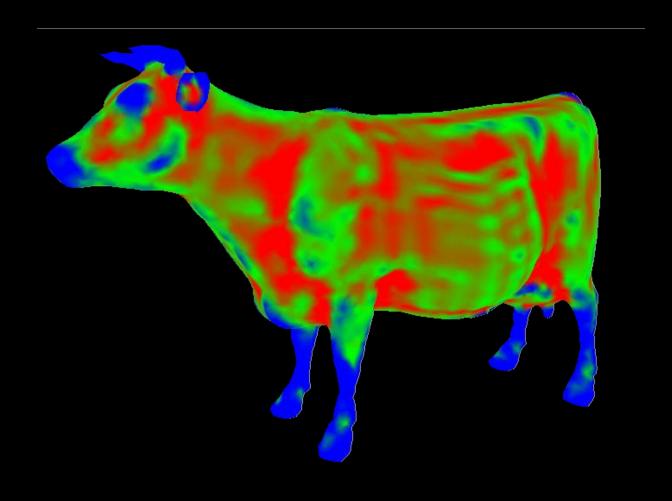


## Extra Slides

# Curvature

### Curvature





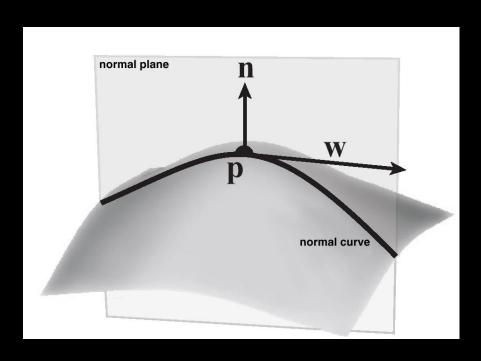
### **Curvature**



Curvature  $\kappa$  of a curve is reciprocal of radius of circle that best approximates it

Defined at a point **p** in a direction w

Line has  $\kappa = 0$ 

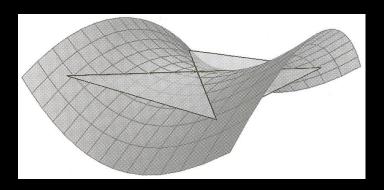


### **Principal Curvatures**



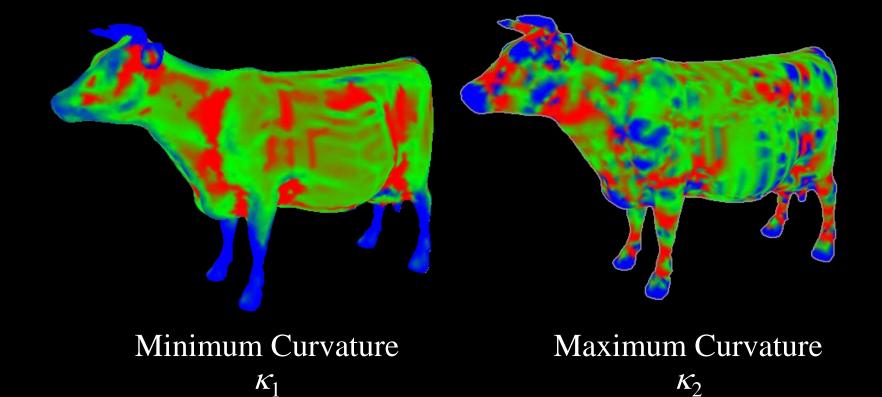
The curvature at a point varies between some minimum and maximum – these are the *principal curvatures*  $\kappa_1$  and  $\kappa_2$ 

They occur in the *principal directions*  $d_1$  and  $d_2$  which are perpendicular to each other



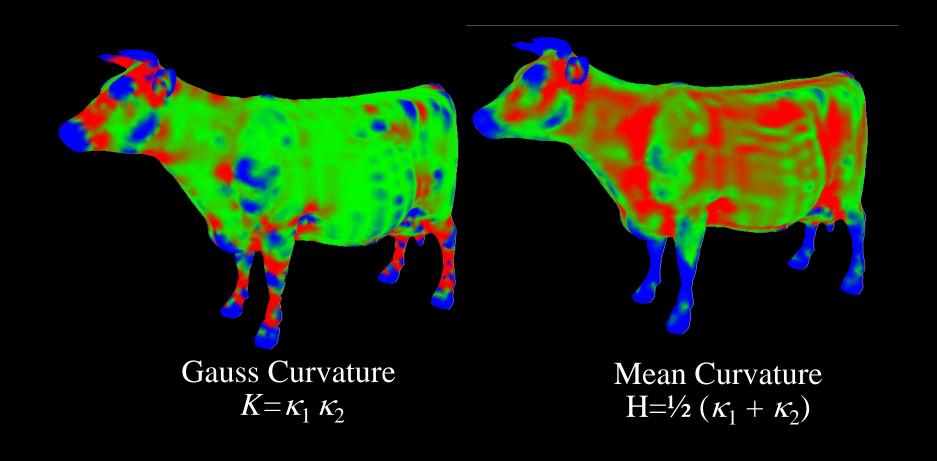
### **Principal Curvatures**





### **Gaussian and Mean Curvature**







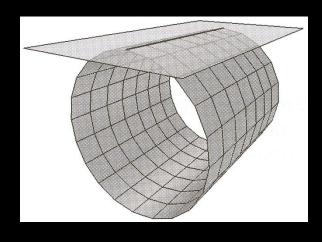
### Planar points:

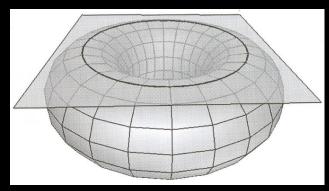
- Zero Gaussian curvature and zero mean curvature
- Tangent plane intersects surface at infinity points

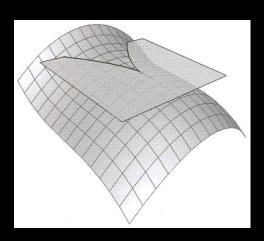


### Parabolic points:

- Zero Gaussian curvature, non-zero mean curvature
- Tangent plane intersects surface along 1 curves



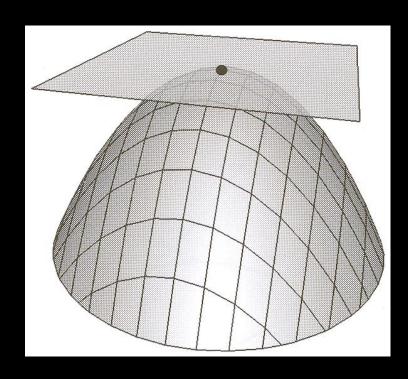






### Elliptical points:

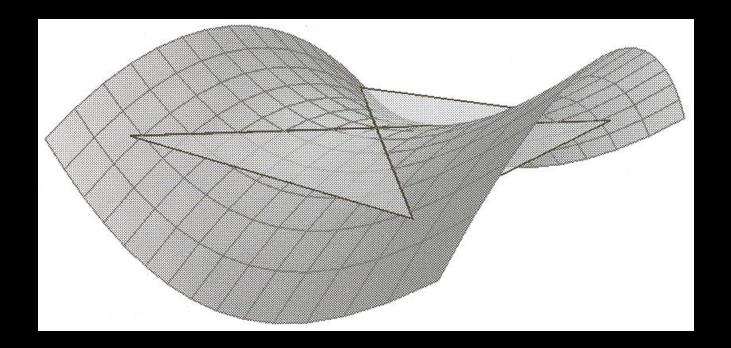
- Positive Gaussian curvature
- Convex/concave depending on sign of mean curvature
- Tangent plane intersects surface at 1 point





### Hyperbolic points:

- Negative Gaussian curvature
- Tangent plane intersects surface along 2 curves





### Mesh Saliency:

- Motivated by models of perceptual salience
- Difference between mean curvature blurred with  $\sigma$  and blurred with  $2\sigma$



### Tensor voting

- Extract points {q<sub>i</sub>} in neighborhood
- Compute covariance matrix M
- Analyze eigenvalues and eigenvectors of M (via SVD)
- Eigenvectors are Principal Axes

$$\mathbf{M} = \frac{1}{n} \sum_{i=1}^{n} \begin{bmatrix} q_i^x q_i^x & q_i^x q_i^y & q_i^x q_i^z \\ q_i^y q_i^x & q_i^y q_i^y & q_i^y q_i^z \\ q_i^z q_i^x & q_i^z q_i^y & q_i^z q_i^z \end{bmatrix}$$

**Covariance Matrix** 

$$\mathbf{M} = \mathbf{U}\mathbf{S}\mathbf{U}^{t}$$

$$\mathbf{S} = \begin{bmatrix} \lambda_{a} & 0 & 0 \\ 0 & \lambda_{b} & 0 \\ 0 & 0 & \lambda_{c} \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} A_{x} & A_{y} & A_{z} \\ B_{x} & B_{y} & B_{z} \\ C_{x} & C_{y} & C_{z} \end{bmatrix}$$

Eigenvalues & Eigenvectors

### Tensor voting

- Extract points {q<sub>i</sub>} in neighborhood
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### **Covariance Matrix**

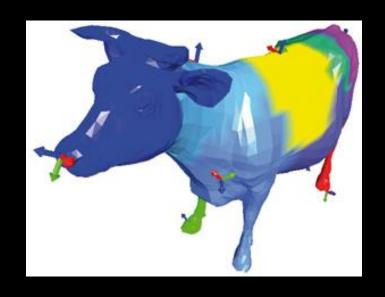
$$\mathbf{M} = \mathbf{U}\mathbf{S}\mathbf{U}^{t}$$

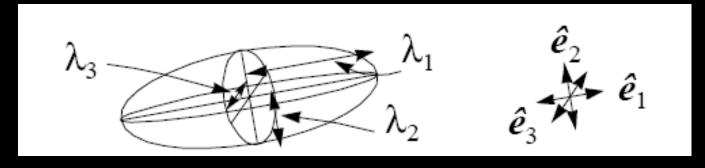
$$\mathbf{S} = \begin{bmatrix} \lambda_{a} & 0 & 0 \\ 0 & \lambda_{b} & 0 \\ 0 & 0 & \lambda_{c} \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} A_{x} & A_{y} & A_{z} \\ B_{x} & B_{y} & B_{z} \\ C_{x} & C_{y} & C_{z} \end{bmatrix}$$

Eigenvalues & Eigenvectors

Eigenvectors are "Principal Axes of Inertia"

Eigenvalues are variances of the point distribution in those directions







### Provides estimate of normal direction

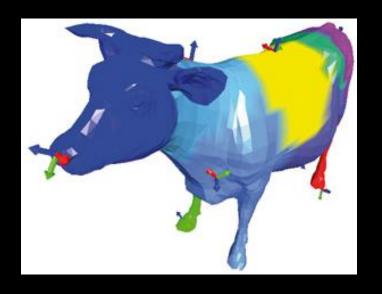
• Eigenvector (principal axis) associated with smallest eigenvalue

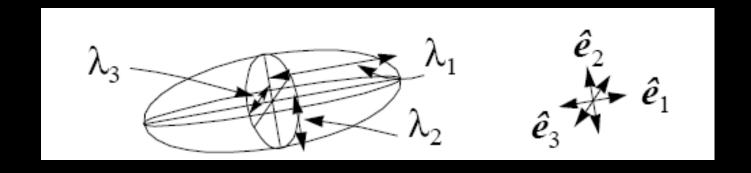




## Helps us construct a local coordinate frame for every point

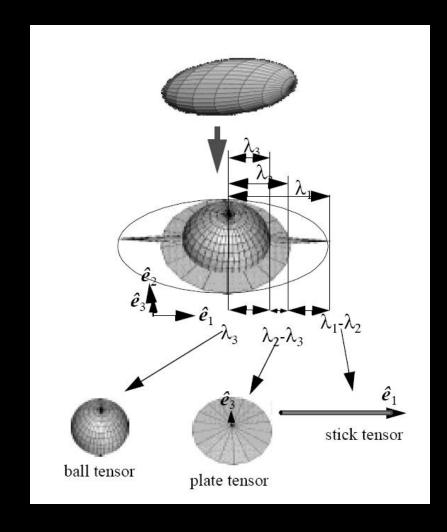
- Map  $\hat{e}_1$  to X axis
- Map ê<sub>2</sub> to Y axis
- Map  $\hat{e}_3$  to Z axis







Helps differentiate nearly plane-like, from stick-like, from sphere-like, etc.





Helps differentiate nearly plane-like, from stick-like, from sphere-like, etc.

