

INTRODUCTION TO  
**Programming**  
in Java



An Interdisciplinary Approach

Robert Sedgewick • Kevin Wayne

Section 4.1

<http://introcs.cs.princeton.edu>

# 11. A Computing Machine

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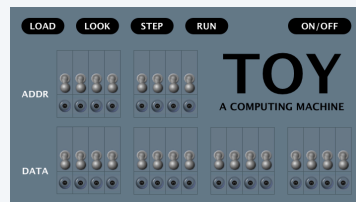
## 11. A Computing Machine

- Overview
- Data types
- Instructions
- Operating the machine
- Machine language programming

### What is TOY?

An imaginary machine similar to:

- Ancient computers.
- Today's smartphone processors.
- Countless other devices designed and built over the past 50 years.



Smartphone processor, 2010s



PDP-8, 1970s

### Reasons to study TOY

#### Prepare to learn about computer architecture

- How does your computer's processor work?
- What are its basic components?
- How do they interact?

#### Learn about machine-language programming.

- How do Java programs relate to computer?
- Key to understanding Java references.
- Still necessary in modern applications.

multimedia, computer games, embedded devices, scientific computing,...

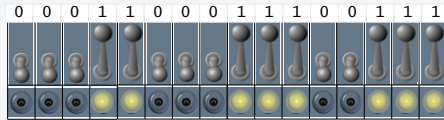
Learn **fundamental abstractions** that have informed processor design for decades.



## Bits and words

Everything in TOY is encoded with a sequence of *bits* (value 0 or 1).

- Why? Easy to represent two states (on and off) in real world.
- Bits are organized in 16-bit sequences called *words*.



More convenient for humans: *hexadecimal notation* (base 16)

- 4 *hex digits* in each word.
- Convert to and from binary 4 bits at a time.

0 0 0 1	1 0 0 0	1 1 1 0	0 1 1 1
1	8	E	7

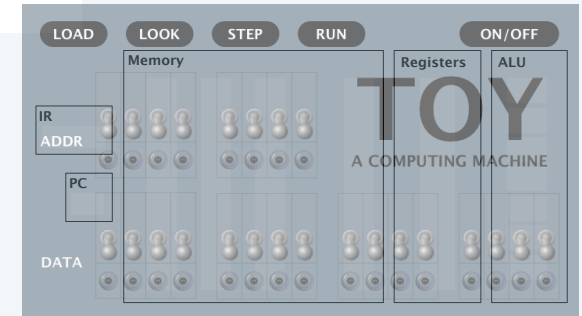
binary	hex
0000	0
0001	1
0010	2
0011	3
0100	4
0101	5
0110	6
0111	7
1000	8
1001	9
1010	A
1011	B
1100	C
1101	D
1110	E
1111	F

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## Inside the box

Components of TOY machine

- Memory
- Registers
- Arithmetic and logic unit (ALU)
- PC and IR



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## Memory

Holds data and instructions

- 256 words
- 16 bits in each word.
- Connected to registers.
- Words are *addressable*.

Use *hexadecimal* for addresses

- Number words from 00 to FF.
- *Think in hexadecimal*.

Memory							
00	0000	10	8A01	20	7101	F0	F0F0
01	FFFE	11	8B02	21	8AFF	F1	0505
02	000D	12	1CAB	22	7680	F2	000D
03	0003	13	9C03	23	7B00	F3	1000
04	0001	14	0001	24	CA2B	F4	0101
05	0000	15	0010	25	8CFF	F5	0010
06	0000	16	0100	26	156B	F6	0001
07	0000	17	1000	27	BC05	F7	0010
08	0000	18	0100	28	2AA1	F8	0100
09	0000	19	0010	29	2BB1	F9	1000
0A	0000	1A	0001	2A	C024	FA	0100
0B	0000	1B	0010	2B	0000	FB	0010
0C	0000	1C	0100	2C	0000	FC	0001
0D	0000	1D	1000	2D	0000	FD	0010
0E	0000	1E	0100	2E	0000	FE	0100
0F	0000	1F	0010	2F	0000	FF	0100

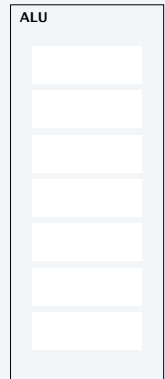
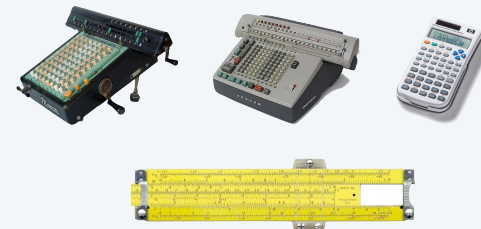
Table of 256 words *completely specifies* contents of memory.

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## Arithmetic and logic unit (ALU)

ALU.

- TOY's computational engine.
- A *calculator*, not a computer.
- *Hardware* that implements *all* data-type operations.
- How? Stay tuned for computer architecture lectures.



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## Registers

### Registers

- 16 words, addressable in hex from 0 to F (use names R0 through RF)
- Scratch space for calculations and data movement.
- Connected to memory and ALU
- *By convention, R0 is always 0.* ← often simplifies code (stay tuned)  
In our code, we often also keep 0001 in R1.

Registers	
R0	0 0 0 0
R1	0 0 0 5
R2	0 0 0 8
R3	0 0 0 D
R4	0 0 0 1
R5	0 0 0 0
R6	F A C E
R7	0 0 0 0
R8	F 0 0 1
R9	0 0 0 0
RA	0 0 0 0
RB	0 0 0 0
RC	0 0 0 0
RD	0 0 0 0
RE	0 0 0 0
RF	0 0 0 0

Q. Why not just connect memory directly to ALU?

A. Too many different memory names (addresses).

Q. Why not just connect memory locations to one another?

A. Too many different connections.

Table of 16 words *completely specifies* contents of registers.

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## Program counter and instruction register

TOY operates by executing a sequence of *instructions*.

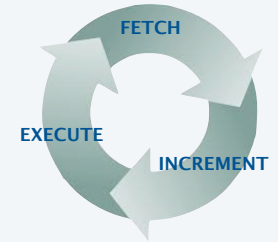
### Critical abstractions in making this happen

- Program Counter (PC). Memory address of next instruction.
- Instruction Register (IR). Instruction being executed.

PC	IR
10	9 A 0 0

### Fetch-increment-execute cycle

- Fetch: Get instruction from memory into IR.
- Increment: Update PC to point to *next* instruction.
- Execute: Move data to or from memory, change PC, or perform calculations, as specified by IR.



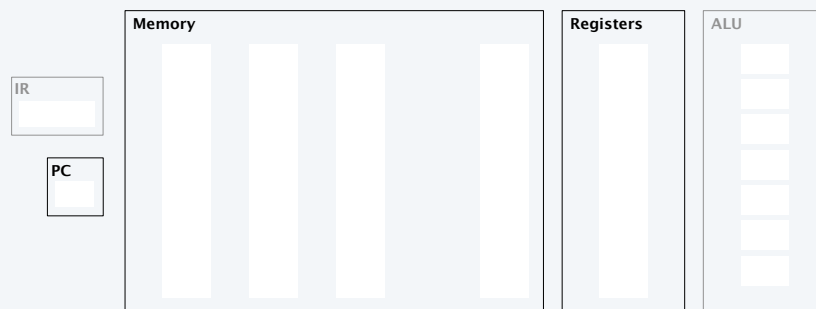
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## The state of the machine

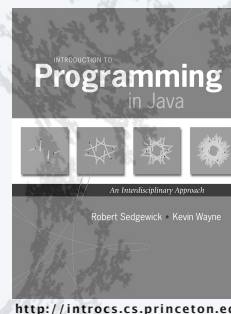
Contents of memory, registers, and PC at a particular time

- Provide a *record* of what a program has done.
- *Completely determines* what the machine will do.

ALU and IR hold intermediate states of computation

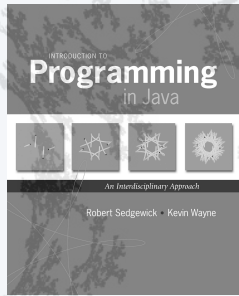


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## 11. A Computing Machine

- Overview
- Data types
- Instructions
- Operating the machine
- Machine language programming



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### TOY data type

A **data type** is a set of values and a set of operations on those values.

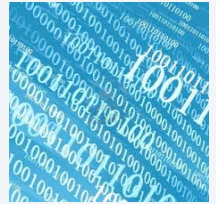
TOY's **data type** is 16-bit 2s complement integers.

Two kinds of operations

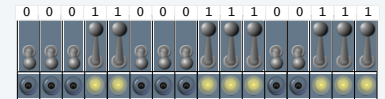
- Arithmetic.
- Bitwise.

All other types of data must be implemented with *software*

- 32-bit and 64-bit integers.
- 32-bit and 64-bit floating point values.
- Characters and strings.
- ...



All values are represented in 16-bit words.



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### TOY data type (original design): Unsigned integers

Values. 0 to  $2^{16}-1$ , encoded in binary (or, equivalently, hex).

Example.  $6375_{10}$ .

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
binary	0	0	0	1	1	0	0	0	1	1	1	0	0	1	1	1
				$2^{12}$	$+2^{11}$				$+2^7$	$+2^6$	$+2^5$			$+2^2$	$+2^1$	$+2^0$
hex	1				8				E				7			
	$1 \times 16^3$				$+ 8 \times 16^2$				$+ 14 \times 16$				$+ 7$			
	4096				+ 2048				+ 224				+ 7			

Operations.

- Add.
- Subtract.
- Test if 0.

Example.  $18E7 + 18E7 = 31CE$

	0	0	0	1	1	0	0	0	1	1	1	0	0	1	1	1
+	0	0	0	1	1	0	0	0	1	1	1	0	0	1	1	1
=	0	0	1	1	0	0	0	1	1	1	0	0	1	1	1	0

Warning. TOY ignores overflow.

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### TOY data type (better design): 2s complement

Values.  $-2^{15}$  to  $2^{15}-1$ , encoded in 16-bit 2s complement.

Operations.

- Add.
- Subtract.
- Test if positive, negative, or 0.

16 bit 2s complement

- 16-bit binary representation of  $x$  for positive  $x$ .
- 16-bit binary representation of  $2^{16} - |x|$  for negative  $x$ .

Useful properties

- Leading bit (bit 15) signifies sign.
- 0000000000000000 represents zero.
- Add/subtract is *the same* as for unsigned.

slight annoyance: one extra negative value

decimal	hex	binary
+32,767	7FFF	0111111111111111
+32,766	7FFE	0111111111111110
+32,765	7FFD	0111111111111101
...		
+3	0003	
+2	0002	
+1	0001	
0	0000	
-1	FFFF	
-2	FFFE	
-3	FFFD	
...		
-32,766	8002	1000000000000010
-32,767	8001	1000000000000001
-32,768	8000	1000000000000000

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## 2s complement: conversion

### To convert from decimal to 2s complement

- If greater than +32,767 or less than -32,768 report error.
- Convert to 16-bit binary.
- If not negative, done.
- If negative, *flip all bits and add 1*.

### Examples

+13 <sub>10</sub>	000000000001011	000D
-13 <sub>10</sub>	1111111111110101	FFF5
+256 <sub>10</sub>	000000100000000	0100
-256 <sub>10</sub>	111111100000000	FF00

### To convert from 2s complement to decimal

- If sign bit is 1, *flip all bits and add 1* and output minus sign.
- Convert to decimal.

### Examples

0001	000000000000001	1 <sub>10</sub>
FFFF	111111111111111	-1 <sub>10</sub>
FF0D	111111100001101	-243 <sub>10</sub>
00F3	000000011110011	+243 <sub>10</sub>

### To add/subtract

- Use same rules as for unsigned binary.
- (Still) ignore overflow.

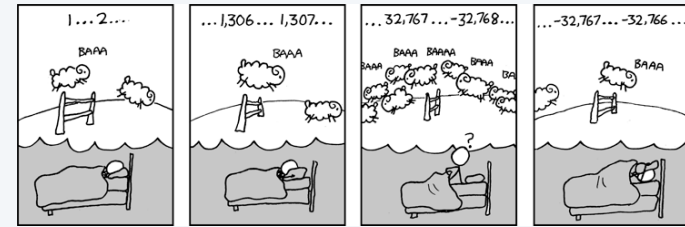
### Example

-256 <sub>10</sub>	111111100000000	FF00
+13 <sub>10</sub>	+000000000001011	+000D
= -243 <sub>10</sub>	=111111100001101	=FF0D

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## Overflow in 2s complement

$$\begin{array}{r}
 32,767_{10} = 2^{15} - 1 \quad 0111111111111111 \quad 7FFF \\
 \uparrow \\
 \text{largest (positive) number} \\
 +1 + 000000000000001 \quad + 0001 \\
 = 100000000000000 \quad = 8000 = -2^{15} = -32,768_{10} \quad \leftarrow \text{smallest (negative) number}
 \end{array}$$



<http://xkcd.com/571/>

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## TOY data type: Bitwise operations

### Operations

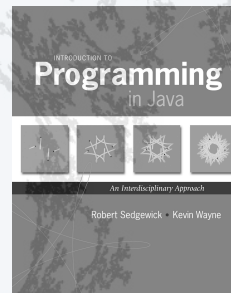
- Bitwise AND.
- Bitwise XOR.
- Shift left.
- Shift right.

	0	1	0	1	1	0	0	1	0	1	0	0	1	0	0	0	x	y	x AND y
AND	0	0	0	1	1	1	1	1	0	0	0	0	0	1	0	1	0	0	0
=	0	0	0	1	1	0	0	1	0	0	0	0	0	0	0	0	1	1	1
	0	1	0	1	1	0	0	1	0	1	0	0	1	0	0	0	x	y	x XOR y
XOR	0	0	0	1	1	1	1	1	0	0	0	0	1	0	1	0	0	1	
=	0	1	0	0	0	1	1	0	0	1	0	0	1	1	0	1	1	0	1
	0	0	0	0	1	1	0	0	0	0	0	1	0	0	1				
Shift left 3	0	1	1	1	0	0	0	0	1	0	0	0	0	0	0			fill with 0s	
	0	0	0	0	1	1	0	0	0	0	0	0	1	0	0	1			
Shift right 3	0	0	0	0	0	0	0	1	1	1	0	0	0	0	0	1			fill with 0s

Special note: Shift left/right operations also implement multiply/divide by powers of 2 for integers.

shift right fills with 1s if leading bit is 1

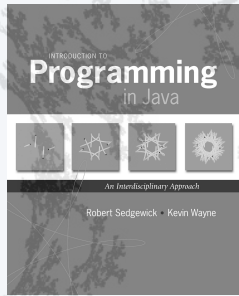
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### TOY instructions

ANY 16-bit (4 hex digit) value defines a TOY instruction.

First hex digit specifies which instruction.

Each instruction changes machine state in well-defined ways.

category	opcodes	implements	changes
operations	1 2 3 4 5 6	data-type operations	registers
data movement	7 8 9 A B	data moves between registers and memory	registers, memory
flow of control	0 C D E F	conditionals, loops, and functions	PC

opcode	instruction
0	halt
1	add
2	subtract
3	and
4	xor
5	shift left
6	shift right
7	load address
8	load
9	store
A	load indirect
B	store indirect
C	branch if zero
D	branch if positive
E	jump register
F	jump and link

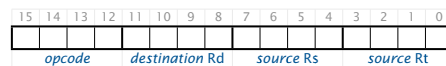
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### Encoding instructions

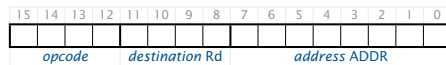
ANY 16-bit (4 hex digit) value defines a TOY instruction.

#### Two different instruction formats

- Type 1: Opcode and 3 registers.



- Type 2: Opcode, 1 register, and 1 memory address.



#### Examples

1 C A B	add RA to RB and put result in RC
8 B 0 1	load contents of memory location 01 into RB

opcode		instruction
0	1	halt
1	1	add
2	1	subtract
3	1	and
4	1	xor
5	1	shift left
6	1	shift right
7	2	load address
8	2	load
9	2	store
A	1	load indirect
B	1	store indirect
C	2	branch if zero
D	2	branch if positive
E	2	jump register
F	2	jump and link

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### A TOY program

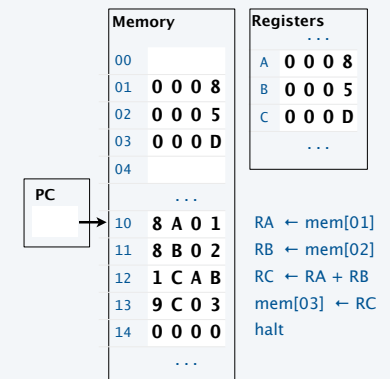
#### Add two integers

- Load operands from memory into registers.
- Add the registers.
- Put result in memory.

```
Load into RA data from mem[01]
Load into RB data from mem[02]
Add RA and RB and put result into RC
Store RC into mem[03]
Halt
```

Q. How can you tell whether a word is an instruction?

A. If the PC has its address, it *is* an instruction!

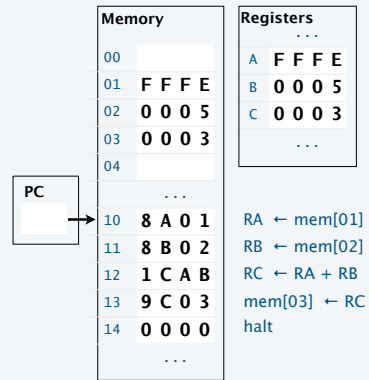


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## Same program with different data

### Add two integers

- Load operands from memory into registers.
- Add the registers.
- Put result in memory.



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## INTRODUCTION TO Programming in Java

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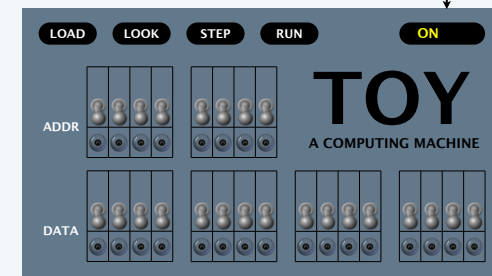
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## Outside the box

### User interface

- Switches.
- Lights.
- Control Buttons.

First step: Turn on the machine!

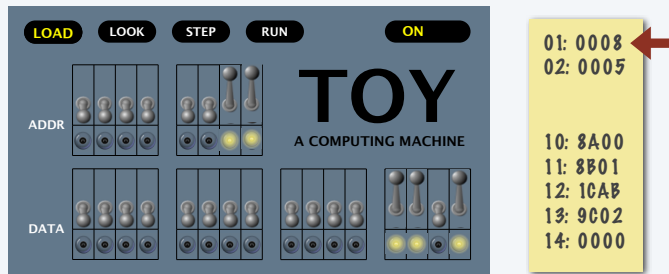


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## Loading data into memory

### To load data

- Set 8 memory address switches.
- Set 16 data switches to data encoding.
- Press LOAD to load data from switches into addressed memory word.

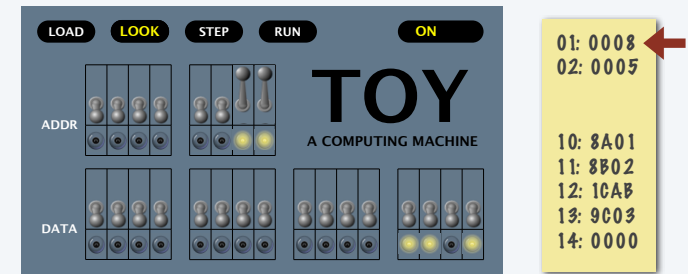


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## Looking at what's in the memory

### To double check that you loaded the data correctly

- Set 8 memory address switches.
- Press LOOK to examine the addressed memory word.



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## Loading instructions into memory

### Use the *same* procedure as for data

- Set 8 memory address switches.
- Set 16 data switches to *instruction* encoding.
- Press LOAD to load *instruction* from switches into addressed memory word.

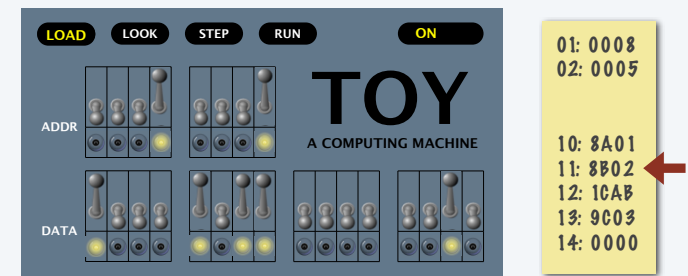


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## Loading instructions into memory

### Use the *same* procedure as for data

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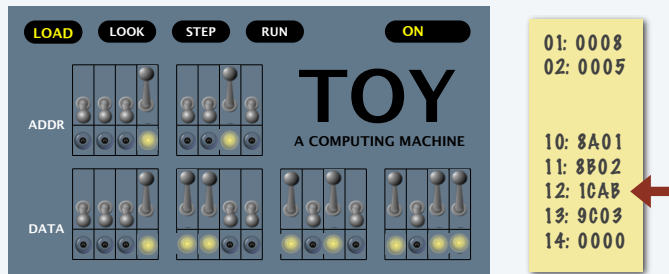
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## Loading instructions into memory

Use the *same* procedure as for data

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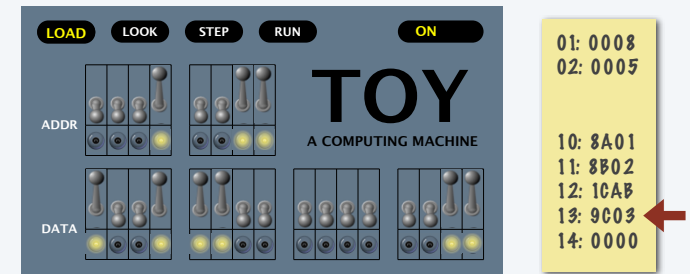


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## Loading instructions into memory

Use the *same* procedure as for data

- Set 8 memory address switches.
- Set 16 data switches to *instruction* encoding.
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## Loading instructions into memory

Use the *same* procedure as for data

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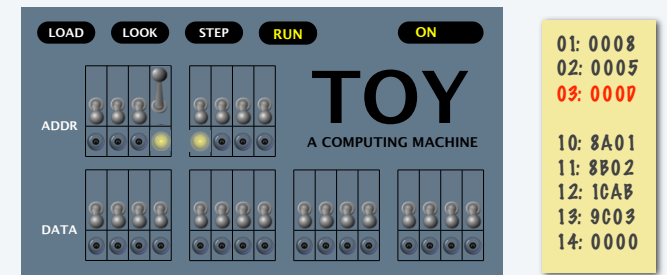
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## Running a program

To run a program, set the address switches to the address of first instruction and press RUN.

[ data lights may flash, but all go off when HALT instruction is reached ]

To see the output, set the address switches to the address of expected result and press LOOK.



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## Same program with different data

**Load different data:** Set address and data switches and press LOAD.

**Run the program:** Set address switches to the address of first instruction and press RUN.

**Look at the output:** Set address switches to the address of expected result and press LOOK. ←

TOY  
A COMPUTING MACHINE

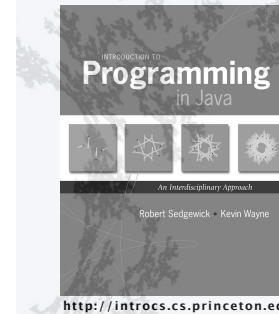
LOAD LOOK STEP RUN ON

ADDR

DATA

01: FFFE  
02: 0005  
03: 0003  
10: 8A01  
11: 8B02  
12: 1CA8  
13: 9C03  
14: 0000

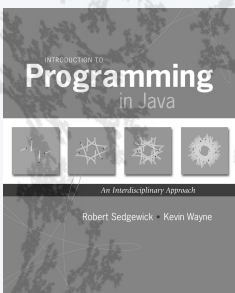
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## Machine language programming

TOY instructions support the same **basic programming constructs** that you learned in Java.

- Primitive data types.
- Assignment statements.
- Conditionals and loops.
- Standard input and output (this section).
- Arrays (this section).

*and* can support advanced constructs, as well.

- Functions and libraries.
- Objects.

## Conditionals and loops

To control the flow of instruction execution

- Test a register's value.
- Change the PC, depending on the value.

opcode	instruction
C	branch if zero
D	branch if positive

Example: Absolute value of RA

10	DA 1 2	If RA > 0 set PC to 12 (skip 11)
11	2A 0 A	Subtract RA from 0 (R0) and put result into RA
12	...	



To infinity and beyond!

Example: Typical while loop (assumes R1 is 0001)

10	CA 1 5	If RA = 0 set PC to 15	while (a != 0) {
11	...		...
12	...		...
13	2AA 1	Decrement RA by 1	a--;
14	C 0 1 0	Set PC to 10	}
15	...		

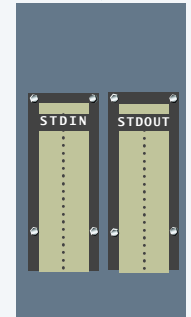
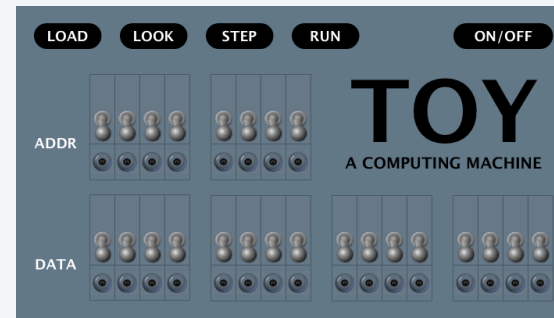
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## Standard input and output

An immediate problem

- We can't be using switches and lights all the time!
- One solution: Paper tape.

Need to bolt new I/O devices to the side of the machine.

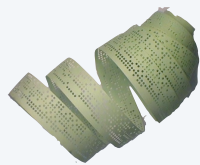


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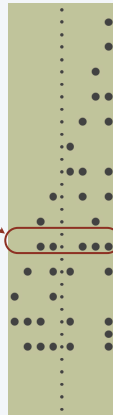
## Standard input and output

Punched paper tape

- Encode 16-bit words in two 8-bit rows.
- To write a word, punch a hole for each 1.
- To read a word, shine a light behind the tape and sense the holes.



0 0 0 0 0 0 0 0 0 0 0 1 1 0 1 1 1



TOY mechanism

- Connect hardware to memory location FF.
- To write the contents of a register to stdout, store to FF.
- To read from stdin into a register, load from FF.

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## Flow control and standard output example: Fibonacci numbers

N	F <sub>N</sub>	Memory	Register trace
0	0	00 0 0 0 A	C 1 1 2 3 5 8 13 21 34 55 89
1	1	01 0 0 0 1	B 0 1 1 2 3 5 8 13 21 34 55
2	1	02	A A 9 8 7 6 5 4 3 2 1 0
3	2	...	
4	3	10 8 1 0 1	R1 ← 1
5	5	11 8 C 0 1	RC ← 1
6	8	12 2 B B B	RB ← 0
7	13	13 8 A 0 0	RA ← mem[00]
8	21	14 C A 1 A	if (RA == 0) PC ← 1A
9	34	15 9 C F F	write RC to stdout
10	55	16 1 C B C	RC ← RB + RC
		17 2 B C B	RB ← RC - RB
		18 2 A A 1	RA ← RA - 1
		19 C 0 1 4	PC ← 14
		1A 0 0 0 0	halt
		...	

```
int c = 1;
int b = 0;
int a = N;
while (a != 0) {
  StdOut.print(c);
  c = b + c;
  b = c - b;
  a--;
}
```

STDOUT

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## Arrays

### To implement an array

- Keep items in an array contiguous starting at mem address a.
- Access  $a[i]$  at  $\text{mem}[a+i]$ .

### To access an array element, use *indirection*

- Keep array address in a register.
- Add index
- Indirect load/store uses contents of a register.

opcode	instruction
7	load address
A	load indirect
B	store indirect

### Array of length 11

```

80 0 0 0 0
81 0 0 0 1
82 0 0 0 1
83 0 0 0 2
84 0 0 0 3
85 0 0 0 5
86 0 0 0 8
87 0 0 0 D
88 0 0 1 5
89 0 0 2 2
8A 0 0 3 7
    
```

### Example: Indirect store

12	7680	Load the address 80 into R6	array starts at mem location 80
13	7B00	Set RB to 0	b is the index
...			
16	156B	$R5 \leftarrow R6 + RB$	compute address of $a[b]$
17	BC05	$\text{mem}[R5] \leftarrow RC$	$a[b] \leftarrow c$
18	1BB1	$RB \leftarrow RB + 1$	increment b
...			

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## Arrays example: Read an array from standard input

### To implement an array

- Keep items in an array contiguous starting at mem location a.
- Access  $a[i]$  at  $\text{mem}[a+i]$ .

PC	Instruction	Assembly
10	7 1 0 1	$R1 \leftarrow 1$
11	8 A F F	$RA \leftarrow N$
12	7 6 8 0	$R6 \leftarrow 80$
13	7 B 0 0	$RB \leftarrow 0$
14	C A 1 B	if ( $RA == 0$ ) $PC \leftarrow 1B$
15	8 C F F	read RC from stdin
16	1 5 6 B	$R5 \leftarrow R6 + RB$
17	B C 0 5	$\text{mem}[R5] \leftarrow RC$
18	1 B B 1	$RB \leftarrow RB + 1$
19	2 A A 1	$RA \leftarrow RA - 1$
1A	C 0 1 4	$PC \leftarrow 14$
1B		[begin array processing code]

Stay tuned.  
Full trace in next lecture.

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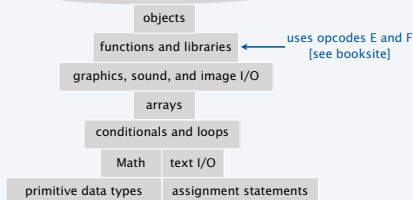
## TOY vs. your laptop

### Two different computing machines

- Both implement basic data types, conditionals, loops, and other low-level constructs.
- Both can have arrays, functions, and other high-level constructs.
- Both have infinite input and output streams.



any program you might want to write



Q. Is 256 words enough to do anything useful?

A. Yes! (Stay tuned for next lecture.)

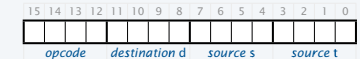
OK, we definitely want a faster version with more memory when we can afford it...

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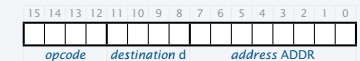
## TOY reference card

opcode	operation	format	pseudo-code
0	HALT	1	HALT
1	add	1	$R[d] \leftarrow R[s] + R[t]$
2	subtract	1	$R[d] \leftarrow R[s] - R[t]$
3	and	1	$R[d] \leftarrow R[s] \& R[t]$
4	xor	1	$R[d] \leftarrow R[s] \wedge R[t]$
5	shift left	1	$R[d] \leftarrow R[s] \ll R[t]$
6	shift right	1	$R[d] \leftarrow R[s] \gg R[t]$
7	load addr	2	$R[d] \leftarrow ADDR$
8	load	2	$R[d] \leftarrow \text{mem}[ADDR]$
9	store	2	$\text{mem}[ADDR] \leftarrow R[d]$
A	load indirect	1	$R[d] \leftarrow \text{mem}[R[t]]$
B	store indirect	1	$\text{mem}[R[t]] \leftarrow R[d]$
C	branch zero	2	if ( $R[d] == 0$ ) $PC \leftarrow ADDR$
D	branch positive	2	if ( $R[d] > 0$ ) $PC \leftarrow ADDR$
E	jump register	2	$PC \leftarrow R[d]$
F	jump and link	2	$R[d] \leftarrow PC; PC \leftarrow ADDR$

### Format 1



### Format 2



**ZERO** R0 is always 0.

**STANDARD INPUT** Load from FF.

**STANDARD OUTPUT** Store to FF.

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## TEQ 1 on TOY

Q. What is the interpretation of

1A75 as a TOY instruction?

1A75 as a 2s complement integer value?

0FFF as a TOY instruction?

0FFF as a 2s complement integer value?

8888 as a TOY instruction?

8888 as a 2s complement integer value? (Answer in base 16).

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## TEQ 2 on TOY

Q. How does one flip all the bits in a TOY register ?

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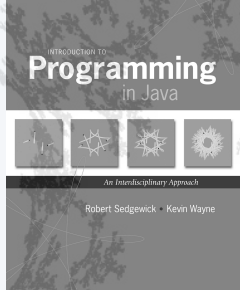
## TEQ 3 on TOY

Q. What does the following TOY program leave in R2 ?

10	<b>7 C 0 A</b>	RC $\leftarrow$ 10 <sub>10</sub>
11	<b>7 1 0 1</b>	R1 $\leftarrow$ 1
12	<b>7 2 0 1</b>	R2 $\leftarrow$ 1
13	<b>1 2 2 2</b>	R2 $\leftarrow$ R2 + R2
14	<b>2 C C 1</b>	RC $\leftarrow$ RC - 1
15	<b>D C 1 3</b>	if (RC > 0) PC $\leftarrow$ 13
16	<b>0 0 0 0</b>	HALT

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COMPUTER SCIENCE  
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## 11. A Computing Machine

- Overview
- Data types
- Instructions
- Operating the machine
- Machine language programming

<http://intros.cs.princeton.edu>

INTRODUCTION TO  
**Programming**  
in Java



An Interdisciplinary Approach

Robert Sedgewick • Kevin Wayne

Section 4.1

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## 11. A Computing Machine