

Radiosity

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COS 526, Fall 2012

Radiosity



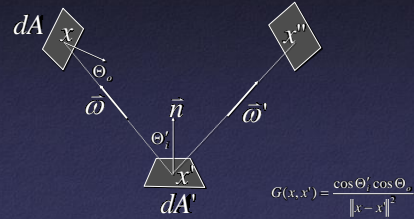
John B. Wallace
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Overview

- Radiosity equation
- Solution methods
 - Computing form factors
 - Selecting basis functions for radiosity
 - Solving linear system of equations
 - Meshing surfaces into elements
 - Rendering images

Rendering Equation

$$L(x' \rightarrow x'') = L_e(x' \rightarrow x'') + \int_S f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$



Radiosity Equation

$$L(x' \rightarrow x'') = L_e(x' \rightarrow x'') + \int_S f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$

Assume everything is Lambertian $f_r(x \rightarrow x' \rightarrow x'') = \rho(x')/\pi$

$$L(x') = L_e(x') + \frac{\rho(x')}{\pi} \int_S L(x) V(x, x') G(x, x') dA$$

Convert to Radiosities $B = \int_{\Omega} L_{\omega} \cos \theta d\omega \quad B = \pi L$

$$B(x') = B_e(x') + \rho(x') \int_S B(x) V(x, x') G(x, x') dA$$

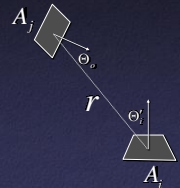
Radiosity Approximation

$$B(x') = B_e(x') + \rho(x') \int_S B(x) V(x, x') G(x, x') dA$$

Discretize surfaces into elements

$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

where $F_{ij} = \frac{1}{A_i} \int_{A_i} \int_{A_j} \frac{V_{ij} \cos \theta_i' \cos \theta_j}{\pi r^2} dA_j dA_i$



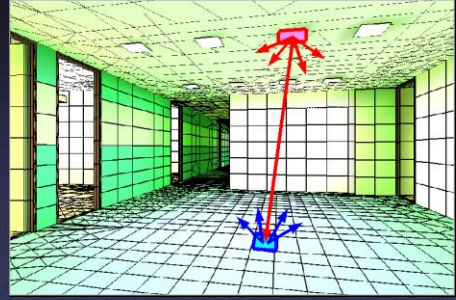
System of Equations

$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

$$B_i - \rho_i \sum_{j=1}^N B_j F_{ij} = E_i$$

$$\begin{bmatrix} 1 - \rho_1 F_{11} & \dots & \dots & -\rho_1 F_{1N} \\ -\rho_2 F_{21} & 1 - \rho_2 F_{22} & \dots & -\rho_2 F_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_N F_{N1} & \dots & \dots & 1 - \rho_N F_{NN} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_N \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_N \end{bmatrix}$$

Intuition



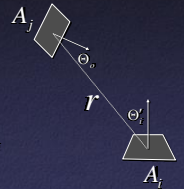
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Form Factor

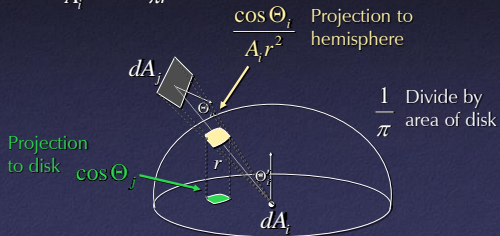
- Fraction of energy leaving element i that arrives at element j

$$F_{ij} = \frac{1}{A_i} \int_{A_i} \int_{A_j} \frac{V_{ij} \cos \Theta'_i \cos \Theta_o}{\pi r^2} dA_j dA_i$$

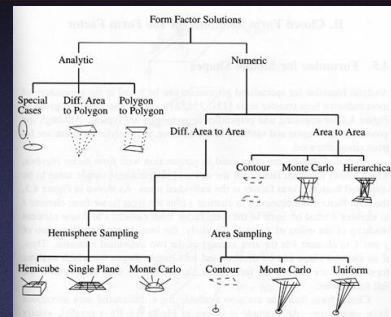


Form Factor Intuition

$$F_{di-dj} = \frac{1}{A_i} \frac{V_{ij} \cos \Theta_i \cos \Theta_j}{\pi r^2}$$

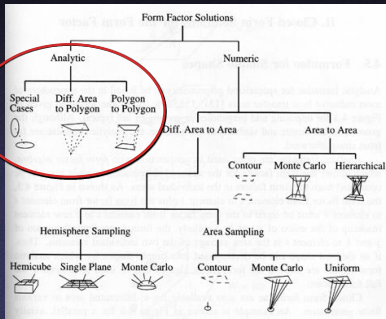


Computing Form Factors



Cohen & Wallace

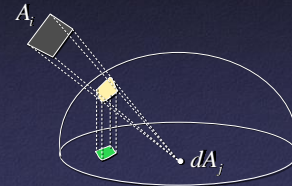
Computing Form Factors



Cohen & Wallace

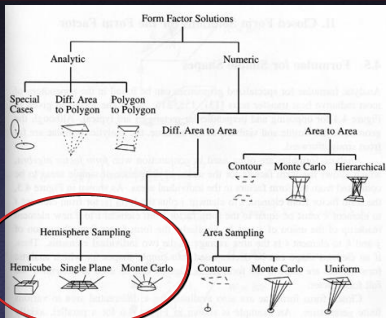
Analytic Form Factors

- Derive equation for projected area
 - Possible only for simple cases



Partial visibility is problematic

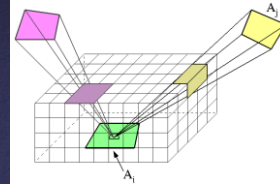
Computing Form Factors



Cohen & Wallace

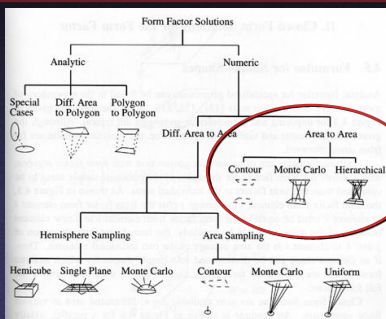
Hemicube

- Compute form factor with image-space precision
 - Render scene from centroid of A_i
 - Use z-buffer to determine visibility of other surfaces
 - Count “pixels” to determine projected areas



Approximating A_i with point leads to errors
Regular sampling leads to aliasing artifacts

Computing Form Factors



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Monte Carlo Sampling

- Compute form factor by random sampling
 - Select random points on elements
 - Intersect line segment to evaluate V_{ij}
 - Evaluate F_{ij} by Monte Carlo integration

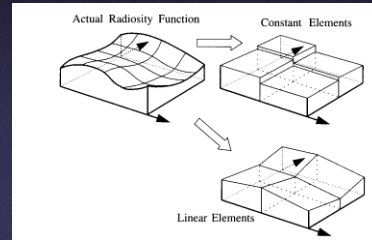
$$F_{ij} = \frac{1}{A_i} \int_{A_i} \int_{A_j} \frac{V_{ij} \cos \Theta'_i \cos \Theta_o}{\pi r^2} dA_j dA_i$$

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Selecting a Basis Function

- Store radiosity function on surface mesh
 - Piecewise-constant, piecewise-linear, wavelets, etc.



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Solving the System of Equations

- Challenges:
 - Size of matrix
 - Cost of computing form factors
 - Computational complexity

$$\begin{bmatrix}
 1 - \rho_1 F_{1,1} & \cdot & \cdot & \cdot & -\rho_1 F_{1,n} \\
 -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \cdot & \cdot & -\rho_2 F_{2,n} \\
 \cdot & \cdot & \cdot & \cdot & \cdot \\
 \cdot & \cdot & \cdot & \cdot & \cdot \\
 -\rho_{n-1} F_{n-1,1} & \cdot & \cdot & \cdot & 1 - \rho_{n-1} F_{n-1,n} \\
 -\rho_n F_{n,1} & \cdot & \cdot & \cdot & 1 - \rho_n F_{n,n}
 \end{bmatrix}
 \begin{bmatrix}
 B_1 \\
 B_2 \\
 \cdot \\
 \cdot \\
 B_n
 \end{bmatrix}
 =
 \begin{bmatrix}
 E_1 \\
 E_2 \\
 \cdot \\
 \cdot \\
 E_n
 \end{bmatrix}$$

Solving the System of Equations

- Solution methods:
 - Invert the matrix – $O(n^3)$
 - Iterative methods – $O(n^2)$
 - Hierarchical methods – $O(n)$

Gauss-Seidel Iteration

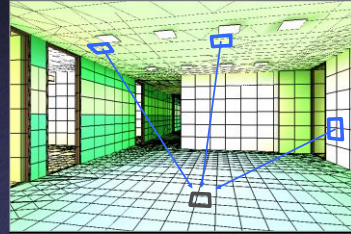
- 1 for all i
- 2 $B_i = E_i$
- 3 while not converged
- 4 for each i in turn
- 5 $B_i = E_i + \rho_i \sum_{j \neq i} B_j F_{ij}$
- 6 display the image using B_i as the intensity of patch i .

Gauss-Seidel Iteration

- Iteratively relax rows of linear system
- Effectiveness depends on sparsity of matrix

Gauss-Seidel Iteration

- Interpretation: gather radiosity to elements



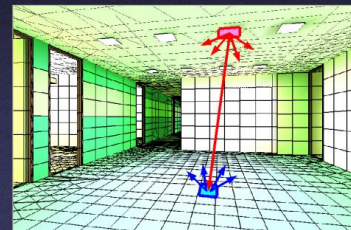
Progressive Radiosity

```

1 for all i
2    $B_i = E_i$ 
3    $\Delta B_i = E_i$ 
4 while not converged
5   pick i, such that  $\Delta B_i * A_i$  is largest
6   for every patch j
7      $\Delta rad = \Delta B_i * \rho_j F_{ji}$ 
8      $\Delta B_j = \Delta B_j + \Delta rad$ 
9      $B_j = B_j + \Delta rad$ 
10   $\Delta B_i = 0$ 
11 display the image using  $B_i$  as the intensity of patch i.
    
```

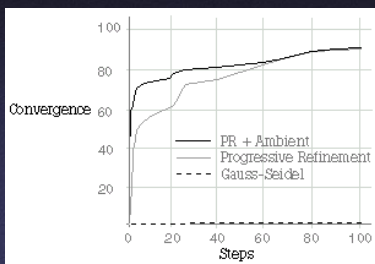
Progressive Radiosity

- Iteratively shoot "unshot" radiosity from elements
- Select shooters in order of unshot radiosity



Progressive Radiosity

- Adaptive refinement



Yeap

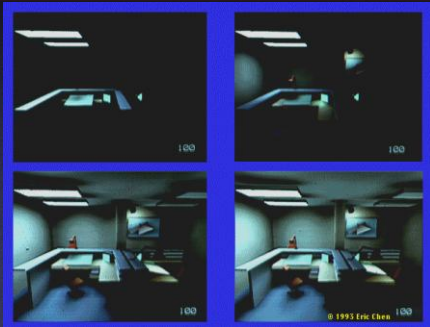
Progressive Radiosity



PROGRESSIVE SOLUTION

The above images show increasing levels of global diffuse illumination. From left to right: 0 bounces, 1 bounce, 3 bounces.

Progressive Radiosity



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Surface Meshing Goals

- Store radiosity across surface
 - Represents function well
 - Few elements
 - Few visible artifacts

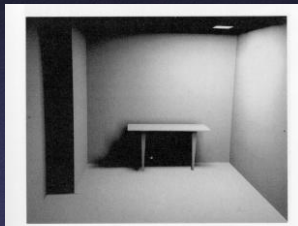
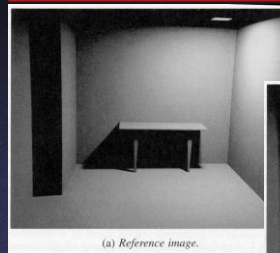


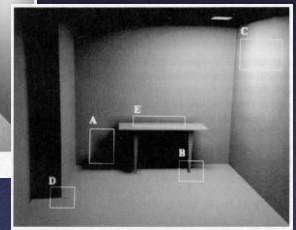
Figure 6.2: A radiosity image computed using a uniform mesh.

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Artifacts of Bad Surface Meshing



(a) Reference image.



(b) Artifacts introduced by the approximation.

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Error Image

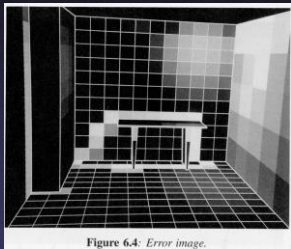


Figure 6.4: Error image.



(a) Reference image.



(b) Artifacts introduced by the approximation.

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Error Image

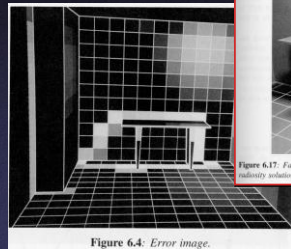


Figure 6.4: Error image.



Figure 6.37: Failure to resolve a discontinuity in value. This is a closeup of the radiosity solution shown in Figure 6.2.



(b) Artifacts introduced by the approximation.

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Adaptive Meshing

- Refine mesh in areas of high residual



Yeap

Adaptive Meshing

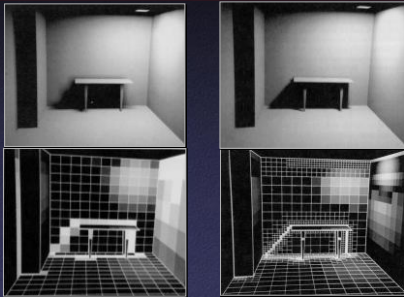


Uniform mesh

Adaptive mesh

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Error Comparison

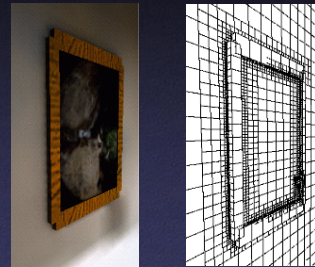


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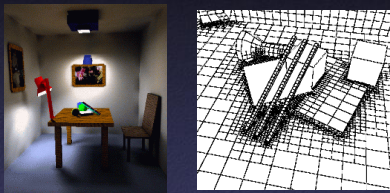
Uniform

Adaptive

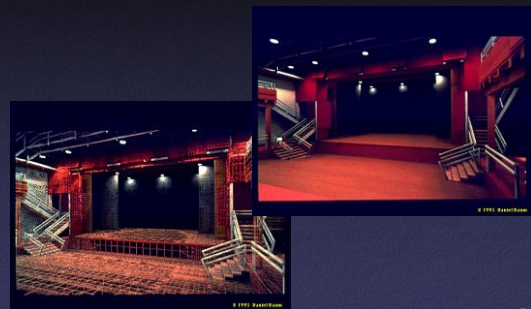
Adaptive Meshing



Adaptive Meshing



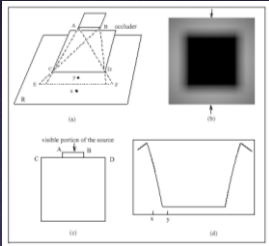
Adaptive Meshing



Baum

Discontinuity Meshing

- Capture discontinuities in radiosity across a surface with explicit mesh boundaries



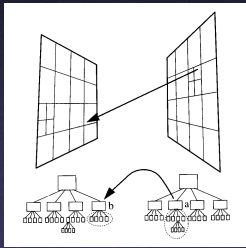
Discontinuity Meshing

- Capture discontinuities in radiosity across a surface with explicit mesh boundaries

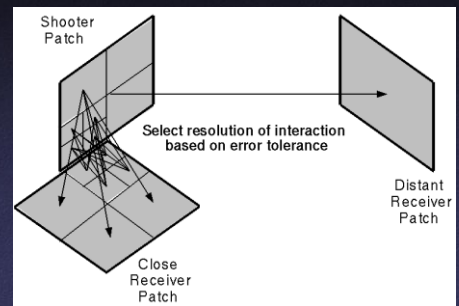


Hierarchical Radiosity

- Estimate errors, refine elements if too large



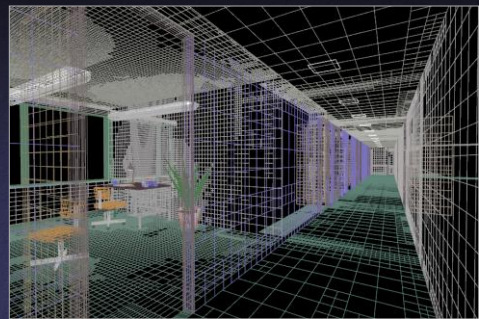
Hierarchical Radiosity



Hierarchical Radiosity



Hierarchical Radiosity



Hierarchical Radiosity

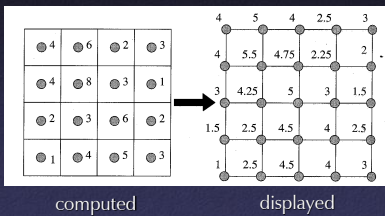


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Displaying Radiosity

- Usually, simple interpolation (Gouraud shading)



- Can also try to preserve discontinuities...

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Wallace

Extensions

- Non-diffuse environments
 - Directional radiosity functions
 - Extended form factors
 - Multipass methods
- Participating media
 - Path integrals in form factors
- Dynamic scenes
 - Incremental updates
- Parallel solvers
 - Decomposition
 - Scheduling

