

Introduction to Shape Analysis

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Princeton University
COS 526, Fall 2012

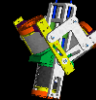


Motivation

Large repositories of 3D data are becoming available



Computer Graphics



Molecular Biology



Medicine



Cultural Heritage



Computer Vision

Lecture Outline

- Introduction
- Applications
- Problems
 - Feature detection

Lecture Outline

- Introduction
- Applications ←
- Problems
 - Feature detection

Applications

Examples:

- Computer graphics
- Geometric modeling
- Archaeology
- Urban planning
- Paleontology
- Molecular bio
- Medicine
- Art

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Reconstructing Frescoes from Thera
(Weyrich, Brown, Rusinkiewicz, et al.)

Applications

Examples:

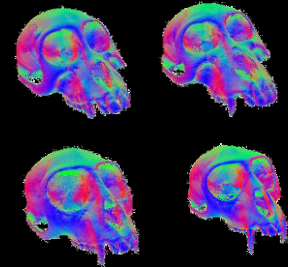
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Applications

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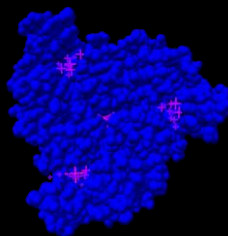
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Applications

Examples:

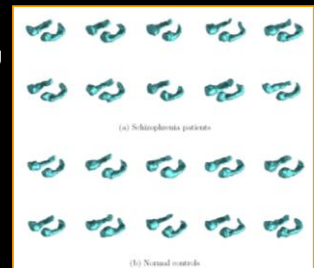
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Applications

Examples:

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Hippocampus-amygdala study in schizophrenia

Applications

Images courtesy of
Stanford University

Examples:

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Lecture Outline

Introduction

Applications

Problems ←

- Feature detection

Shape Analysis Problems

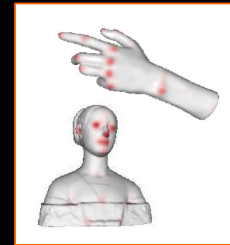
Examples:

- Feature detection
- Segmentation
- Labeling
- Registration
- Matching
- Recognition
- Classification
- Clustering
- Retrieval

Shape Analysis Problems

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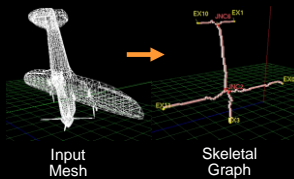
Schelling Points

“How can we find significant geometric features robustly?”

Shape Analysis Problems

Examples:

- Feature detection
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Input Mesh

Skeletal Graph

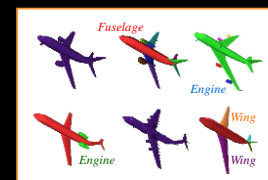
“How can we decompose a 3D model into its parts?”

Shape Analysis Problems

Images courtesy of
Ayellet Tal, Technion &
Princeton University

Examples:

- Feature detection
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Semantic Labels

(Golovinskiy, Lee, et al.)

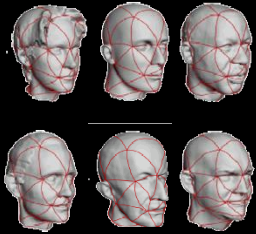
“How can we decompose a 3D model into its parts?”

Shape Analysis Problems

Images courtesy of Emil Prabh

Examples:

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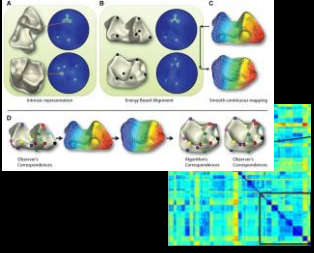
"How can we align features of 3D models?"

Shape Analysis Problems

Images courtesy of Florida State Univ.

Examples:

- Feature detection
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- Labeling
- Registration
- **Matching**
- Retrieval
- Recognition
- Classification
- Clustering



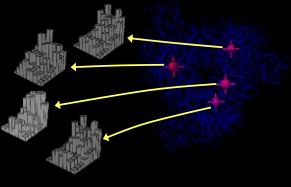
"How can we compute a measure of geometric similarity?"

Shape Analysis Problems

Images courtesy of Florida State Univ.

Examples:

- Feature detection
- Segmentation
- Labeling
- Registration
- Matching
- **Retrieval**
- Recognition
- Classification
- Clustering



Harmonic Shape Descriptors


"How can we find similar 3D shapes in a database?"

Shape Analysis Problems

Images courtesy of Florida State Univ.

Examples:

- Feature detection
- Segmentation
- Labeling
- Registration
- Matching
- Retrieval
- **Recognition**
- Classification
- Clustering




"How can we find a given 3D model in a large database?"

Shape Analysis Problems

Images courtesy of Darpa E3D Project

Examples:

- Feature detection
- Segmentation
- Labeling
- Registration
- Matching
- Retrieval
- Recognition
- **Classification**
- Clustering



Query

Classes


"How can we determine the class of a 3D model?"

Shape Analysis Problems

Images courtesy of Viewpoint

Examples:

- Feature detection
- Segmentation
- Labeling
- Registration
- Matching
- Retrieval
- Recognition
- Classification
- **Clustering**



"How can we learn classes of 3D models automatically?"

A Quick Diversion ...

Images courtesy of
Georgia Tech and
www.dreamhorse.com

Which is harder to analyze?



3D Model



2D Image

Lecture Outline

Introduction

Applications

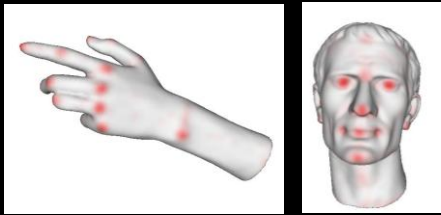
Problems

- Feature detection ←

Features

Definition (Merriam-Webster)

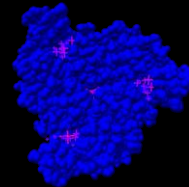
- "a prominent characteristic"



Point Features

Applications:

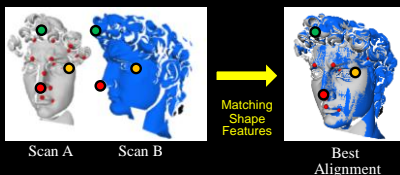
- Maintaining shape features as process mesh
- Matching shape features as align meshes
- Reasoning about part decomposition
- Visualization
- etc.



Point Features

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Point Feature Detection

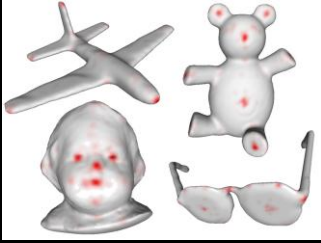
Goals:

- Invariant to transformations
- Robust to small surface deviations (holes, noise, etc.)
- Common across different surfaces in same class
- Semantic?



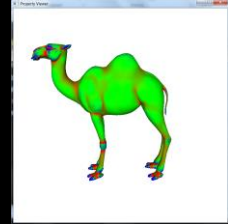
Point Feature Detection

Algorithmic methods to detect feature points?



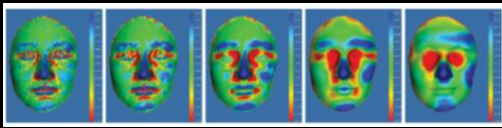
Point Feature Detection

Some relevant properties
Average geodesic distance
Gauss curvature
Differences of curvature
Shape diameter function
etc.



Point Feature Detection

Multiscale methods
Many methods consider scale-space persistence



Zou08

Feature Point Study

Ask people on the Amazon Mechanical Turk



Key question

How should we ask people which points are salient?

Key question

How should we ask people which points are salient?

- "Please select salient points"

Key question



How should we ask people which points are salient?

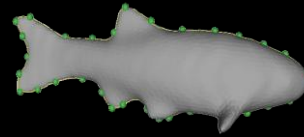
- "Please select salient points"
- Please select a pattern of points from which another person can recognize the object's class by viewing only those points

Key question



How should we ask people which points are salient?

- "Please select salient points"
- Please select a pattern of points from which another person can recognize the object's class by viewing only those points

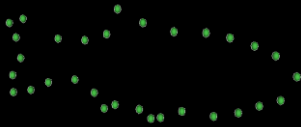


Key question



How should we ask people which points are salient?

- "Please select salient points"
- Please select a pattern of points from which another person can recognize the object's class by viewing only those points



Schelling approach



We asked people to:

- Please select points that you think other people will select

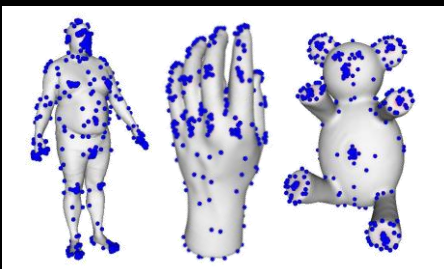
Based on the "focal point" theory of [Schelling60]

- A solution that people tend to use in the absence of communication, because it seems natural, special or relevant to them

Schelling Feature Points



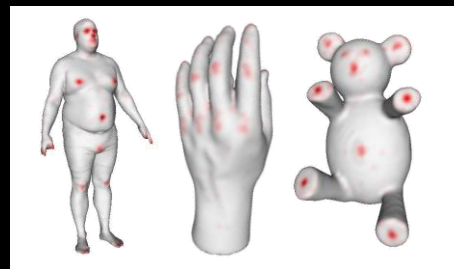
Schelling feature points



Schelling Feature Points



Schelling feature point distributions



Relation with geometric properties?

Local properties

- Curvatures
- Mesh Saliency
- HKS at small t

Global properties

- HKS at large t
- SDF [Shapira 08]
- Symmetry
- Segment Center
- AGD
- Etc.

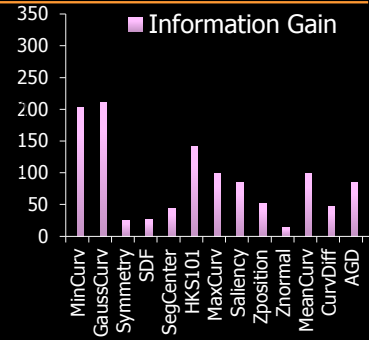
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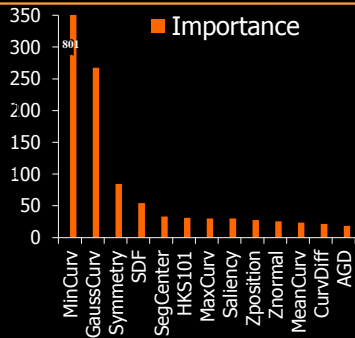
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Relation with geometric properties?

Schelling point distribution



Relation with geometric properties?

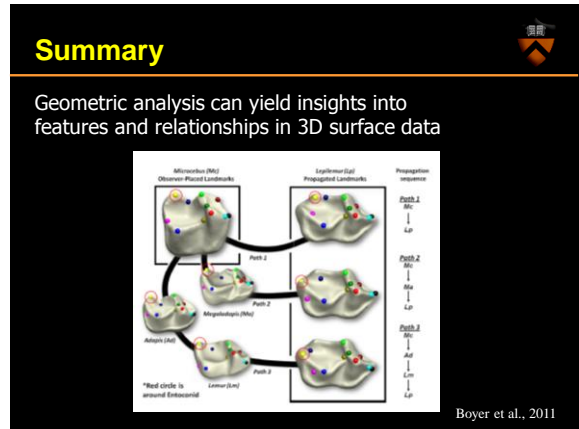
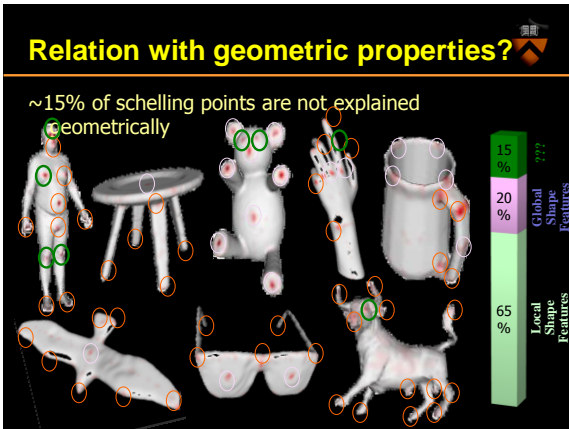
Local shape features explain most schelling points



Relation with geometric properties?

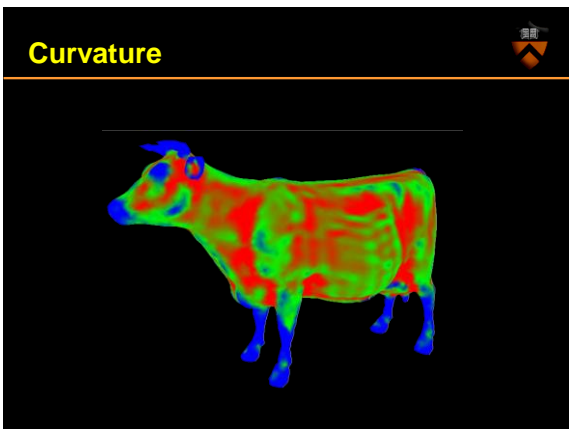
Global shape features explain ~20% more





Extra Slides

Curvature



Curvature

Curvature κ of a curve is reciprocal of radius of circle that best approximates it

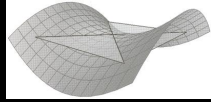
Defined at a point p in a direction w

Line has $\kappa = 0$

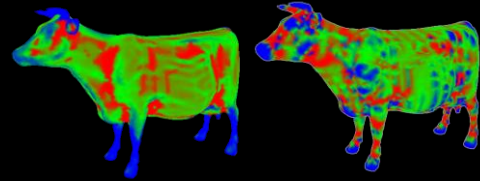
Principal Curvatures

The curvature at a point varies between some minimum and maximum – these are the *principal curvatures* κ_1 and κ_2

They occur in the *principal directions* d_1 and d_2 which are perpendicular to each other



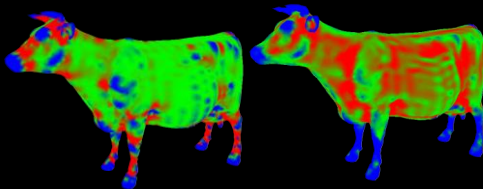
Principal Curvatures



Minimum Curvature
 κ_1

Maximum Curvature
 κ_2

Gaussian and Mean Curvature



Gauss Curvature
 $K = \kappa_1 \kappa_2$

Mean Curvature
 $H = \frac{1}{2} (\kappa_1 + \kappa_2)$

What Does Curvature Tell Us?

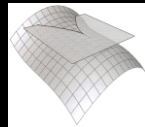
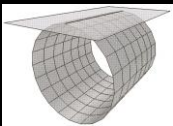
Planar points:

- Zero Gaussian curvature and zero mean curvature
- Tangent plane intersects surface at infinity points

What Does Curvature Tell Us?

Parabolic points:

- Zero Gaussian curvature, non-zero mean curvature
- Tangent plane intersects surface along 1 curves



What Does Curvature Tell Us?

Elliptical points:

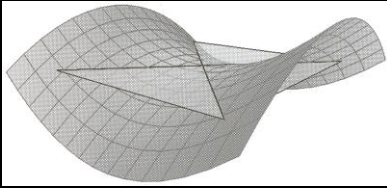
- Positive Gaussian curvature
- Convex/concave depending on sign of mean curvature
- Tangent plane intersects surface at 1 point



What Does Curvature Tell Us?

Hyperbolic points:

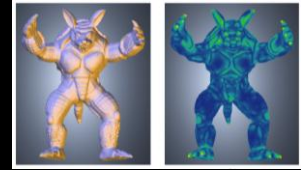
- Negative Gaussian curvature
- Tangent plane intersects surface along 2 curves



What Does Curvature Tell Us?

Mesh Saliency:

- Motivated by models of perceptual saliency
- Difference between mean curvature blurred with σ and blurred with 2σ



Lee05

Principal Component Analysis (PCA)

Principal Component Analysis (PCA)

Tensor voting

- Extract points $\{q_i\}$ in neighborhood
- Compute covariance matrix M
- Analyze eigenvalues and eigenvectors of M (via SVD)
- Eigenvectors are Principal Axes

$$M = \frac{1}{n} \sum_{i=1}^n \begin{bmatrix} q_i^x q_i^x & q_i^x q_i^y & q_i^x q_i^z \\ q_i^y q_i^x & q_i^y q_i^y & q_i^y q_i^z \\ q_i^z q_i^x & q_i^z q_i^y & q_i^z q_i^z \end{bmatrix}$$

Covariance Matrix

$$M = USU^T$$

$$S = \begin{bmatrix} \lambda_x & 0 & 0 \\ 0 & \lambda_y & 0 \\ 0 & 0 & \lambda_z \end{bmatrix} \quad U = \begin{bmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{bmatrix}$$

Eigenvalues & Eigenvectors

Principal Component Analysis (PCA)

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Covariance Matrix

$$M = USU^T$$

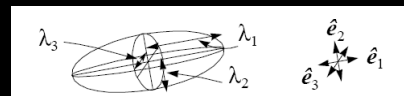
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Eigenvalues & Eigenvectors

Principal Component Analysis (PCA)

Eigenvectors are "Principal Axes of Inertia"

Eigenvalues are variances of the point distribution in those directions



What Does PCA Tell Us?

Provides estimate of normal direction

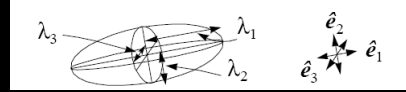
- Eigenvector (principal axis) associated with smallest eigenvalue



What Does PCA Tell Us?

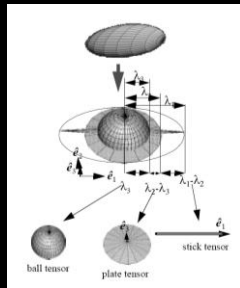
Helps us construct a local coordinate frame for every point

- Map \hat{e}_1 to X axis
- Map \hat{e}_2 to Y axis
- Map \hat{e}_3 to Z axis



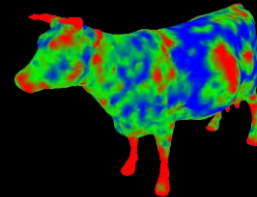
What Does PCA Tell Us?

Helps differentiate nearly plane-like, from stick-like, from sphere-like, etc.



What Does PCA Tell Us?

Helps differentiate nearly plane-like, from stick-like, from sphere-like, etc.



$$\lambda_2 / (\lambda_1 + \lambda_2 + \lambda_3)$$