

# Segmentation and Clustering

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- **Segmentation:**  
Divide image  
into regions  
of similar contents
- **Clustering:**  
Aggregate pixels  
into regions  
of similar contents

# But Wait!

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- We speak of segmenting foreground from background
- Segmenting out skin colors
- Segmenting out the moving person
- How do these relate to “similar regions”?

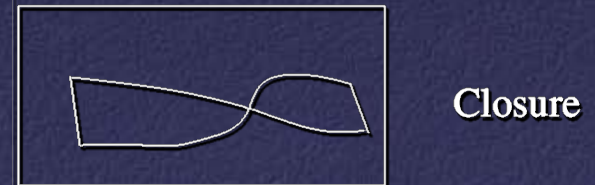
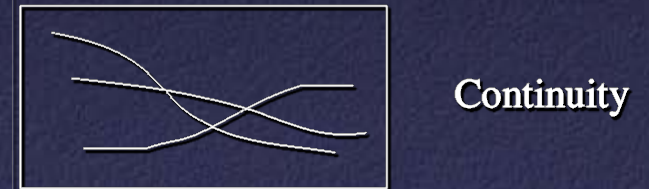
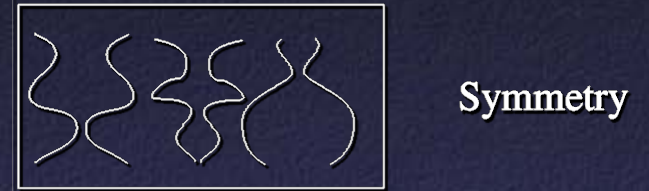
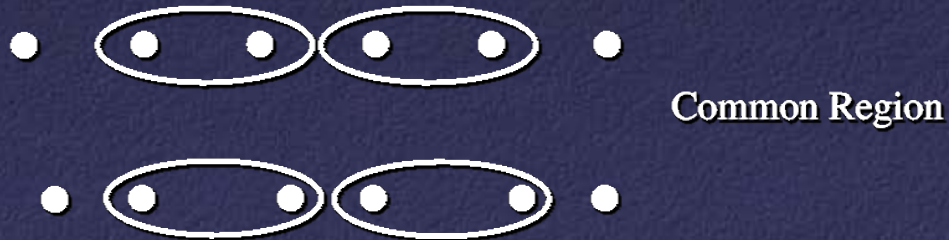


# Segmentation and Clustering

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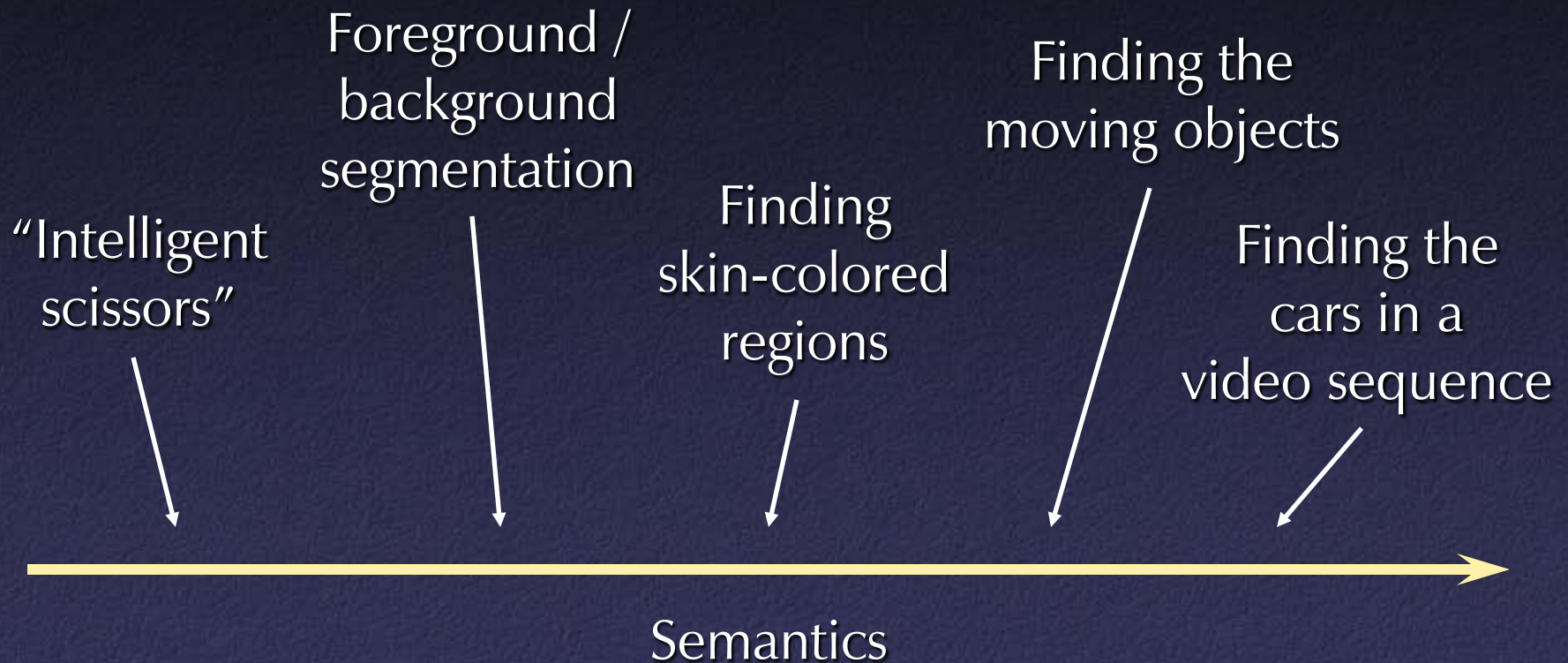
- Defining regions
  - Should they be compact? Smooth boundary?
- Defining similarity
  - Color, texture, motion, ...
- Defining similarity of regions
  - Minimum distance, mean, maximum

# Grouping Cues



# Segmentation and Clustering Applications

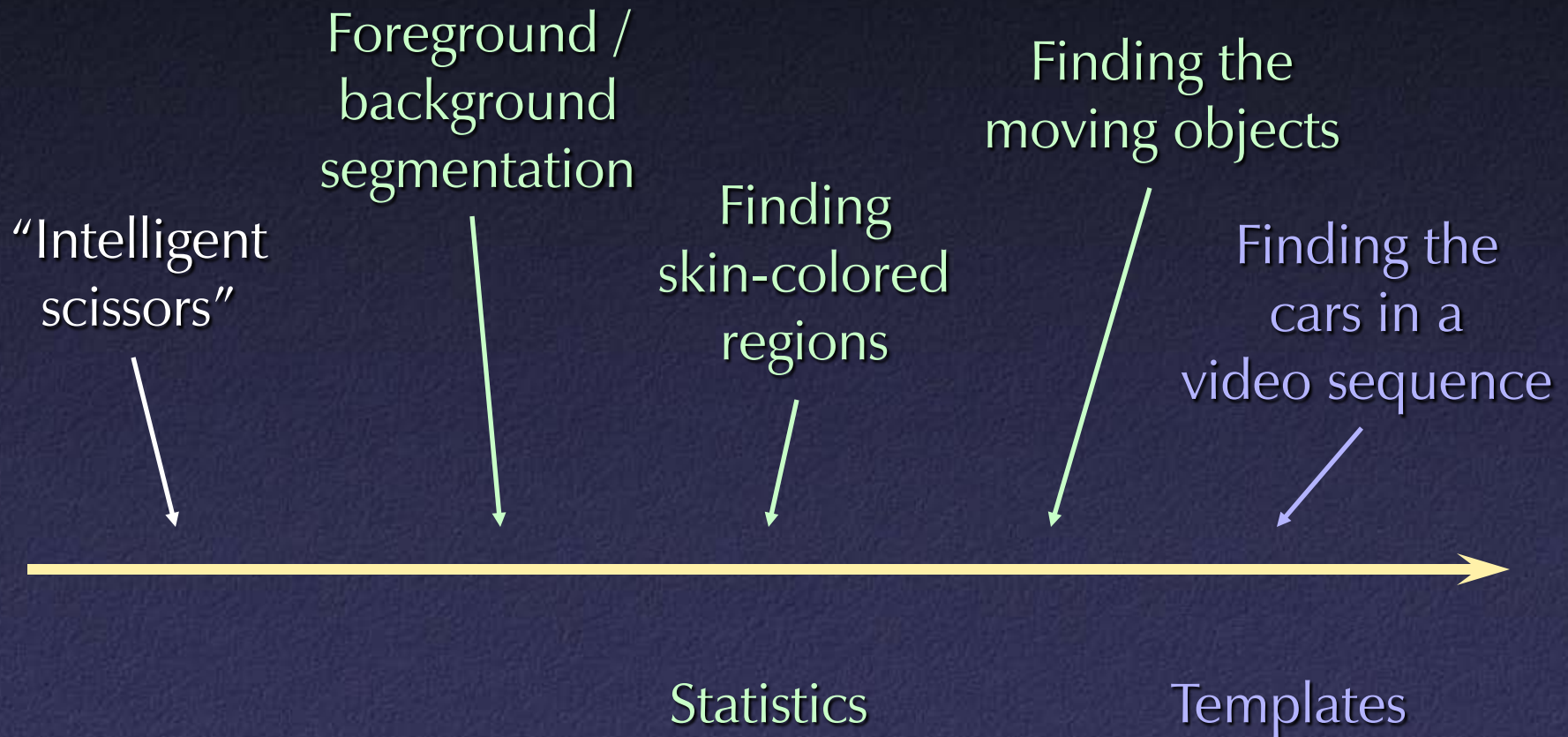
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# Segmentation and Clustering Applications

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# Clustering Based on Color

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- Let's make a few concrete choices:
  - Arbitrary regions
  - Similarity based on color only
  - Similarity of regions =  
distance between mean colors



# Simple Agglomerative Clustering

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- Start with each pixel in its own cluster
- Iterate:
  - Find pair of clusters with smallest inter-cluster distance
  - Merge
- Stopping threshold
- “Superpixels”: stop clustering early, pass result to more complex algorithms

# Simple Divisive Clustering

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- Start with whole image in one cluster
- Iterate:
  - Find cluster with largest intra-cluster variation
  - Split into two pieces that yield largest inter-cluster distance
- Stopping threshold

# Difficulties with Simple Clustering

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- Many possibilities at each iteration
- Computing distance between clusters or optimal split expensive
- Heuristics to speed this up:
  - For agglomerative clustering, approximate each cluster by average for distance computations
  - For divisive clustering, use summary (histogram) of a region to compute split



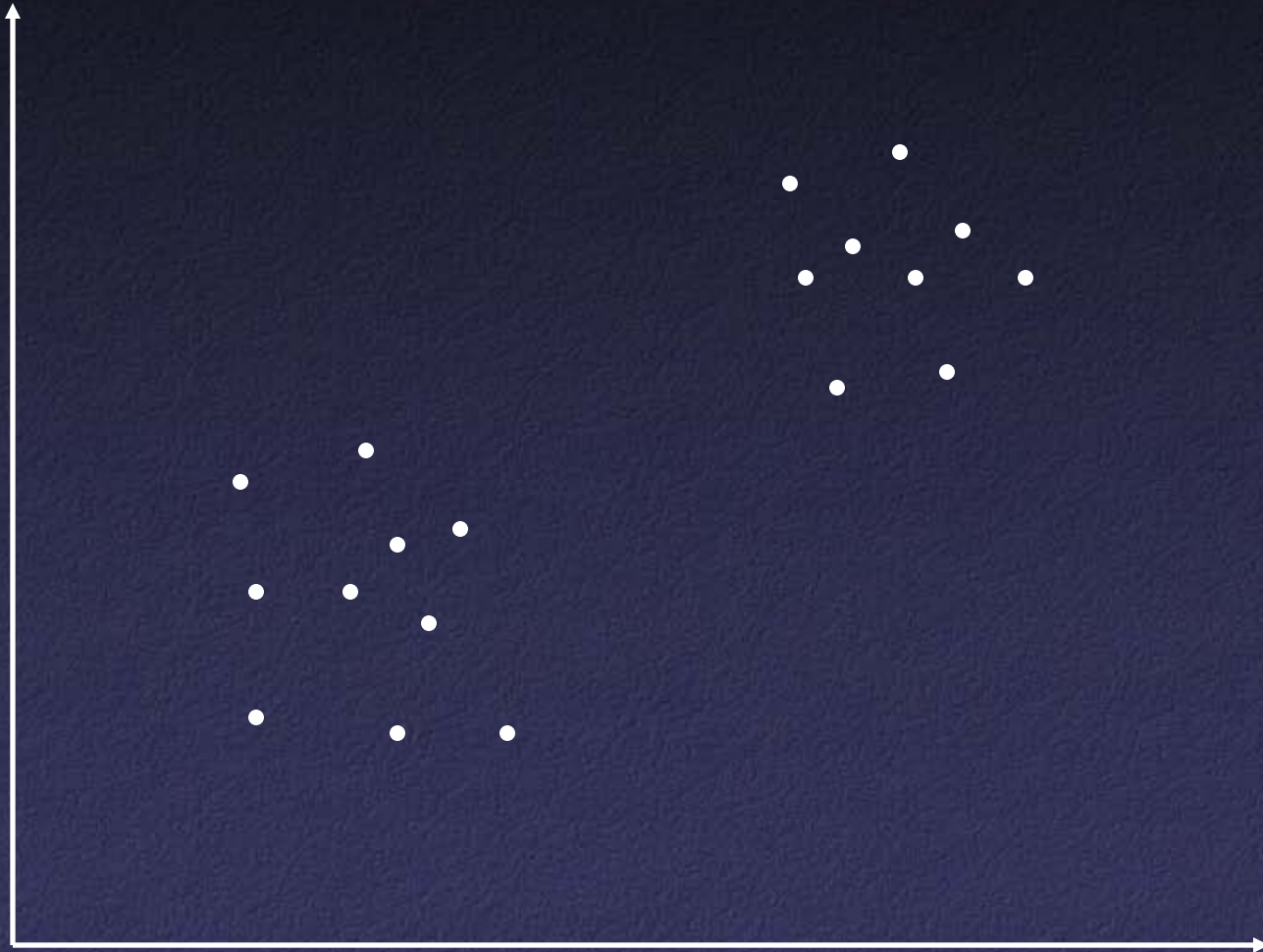
# $k$ -means Clustering

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- Instead of merging or splitting, start out with the clusters and move them around
  1. Pick number of clusters  $k$
  2. Randomly scatter  $k$  “cluster centers” in color space
  3. Repeat:
    - a. Assign each data point to its closest cluster center
    - b. Move each cluster center to the mean of the points assigned to it

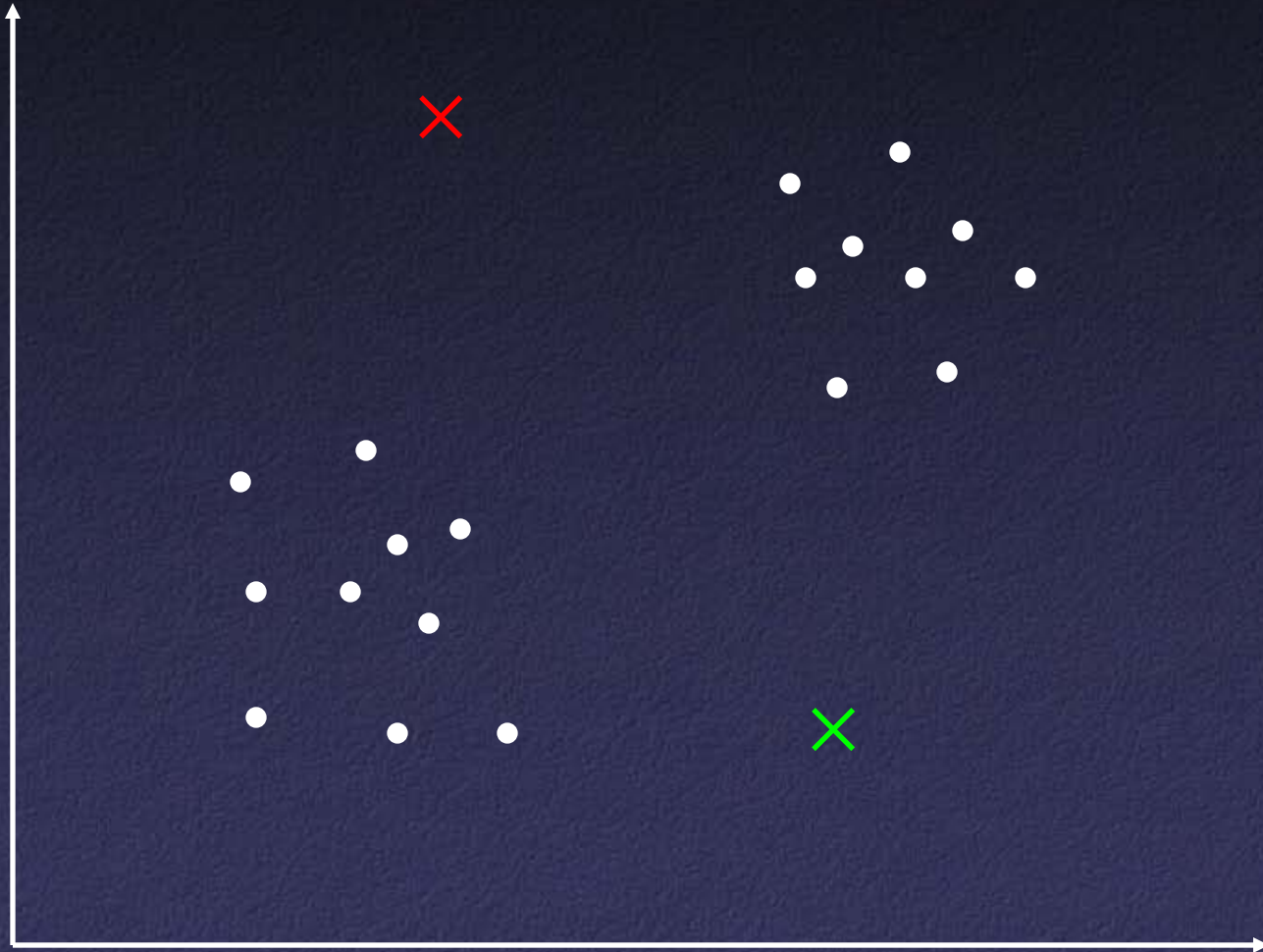
# $k$ -means Clustering

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# $k$ -means Clustering

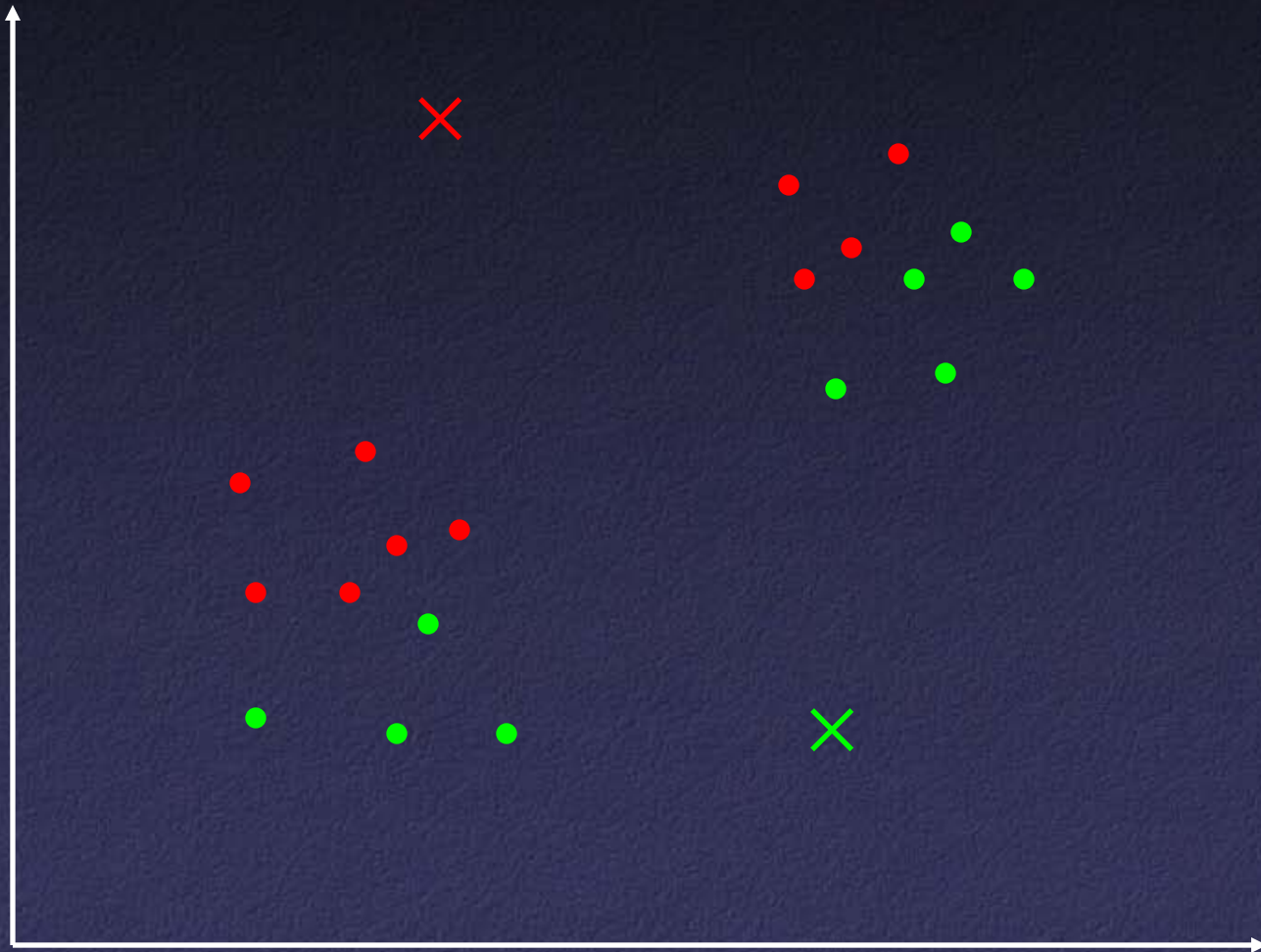
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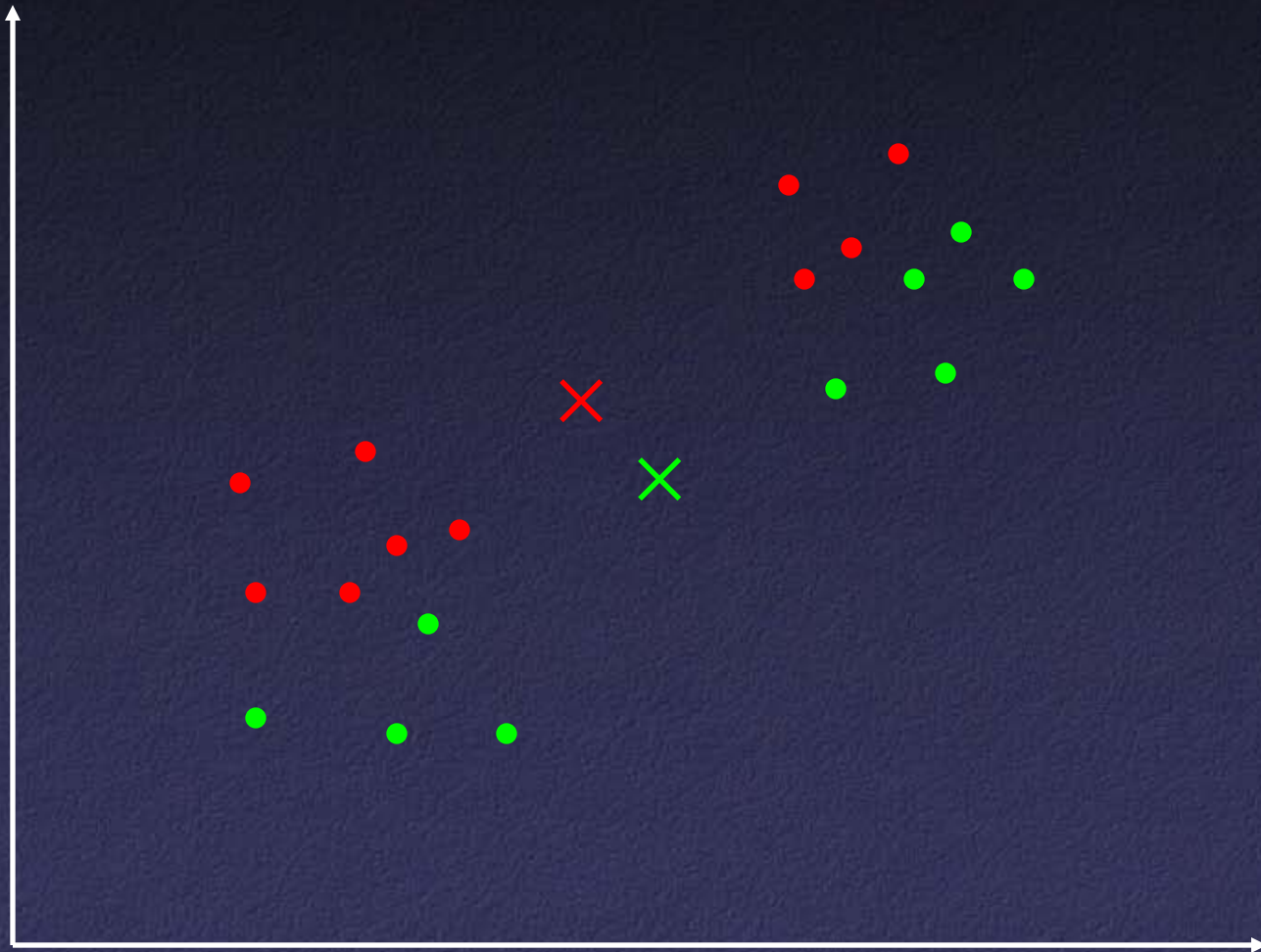
# $k$ -means Clustering

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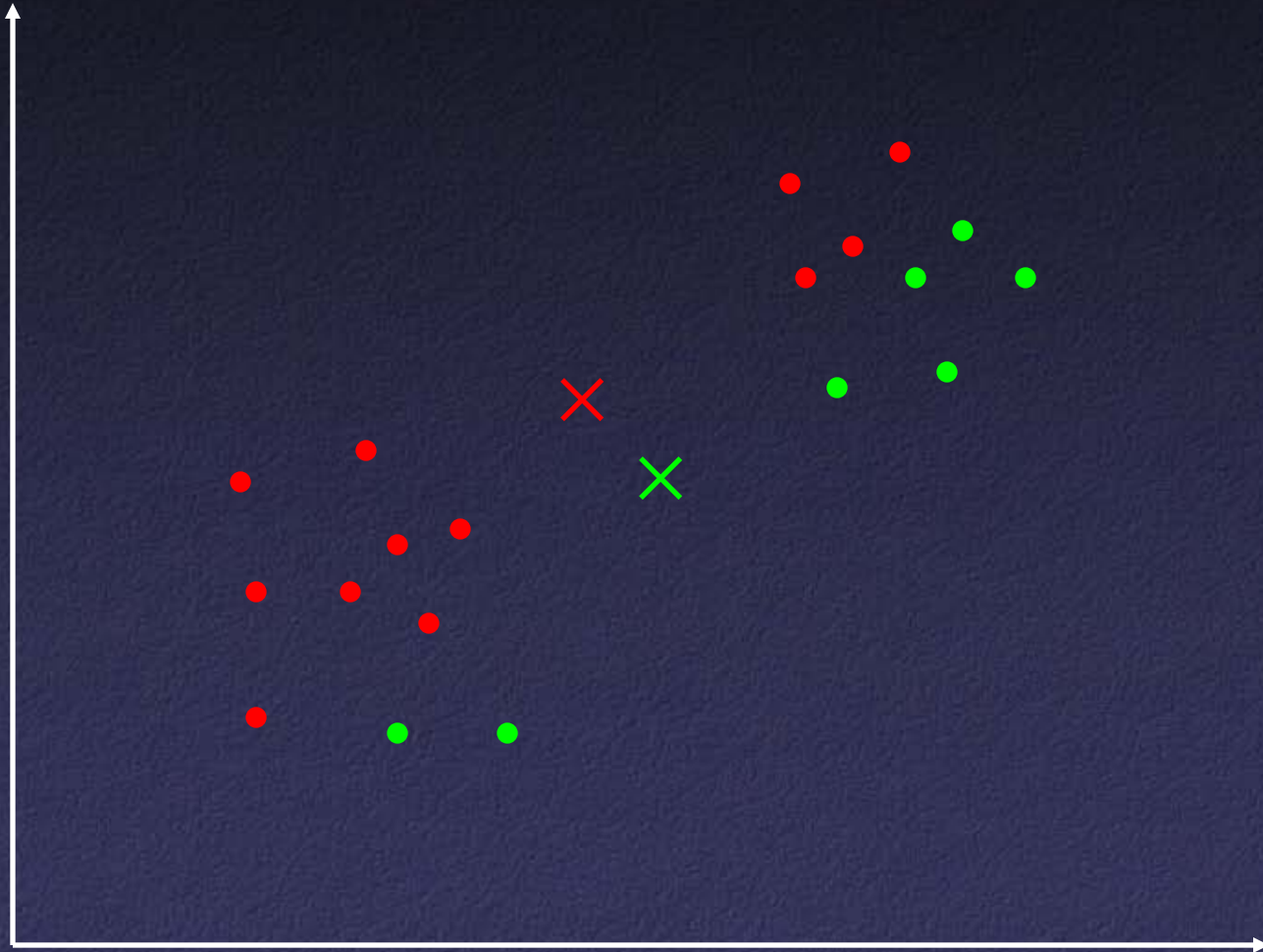
# $k$ -means Clustering

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# $k$ -means Clustering

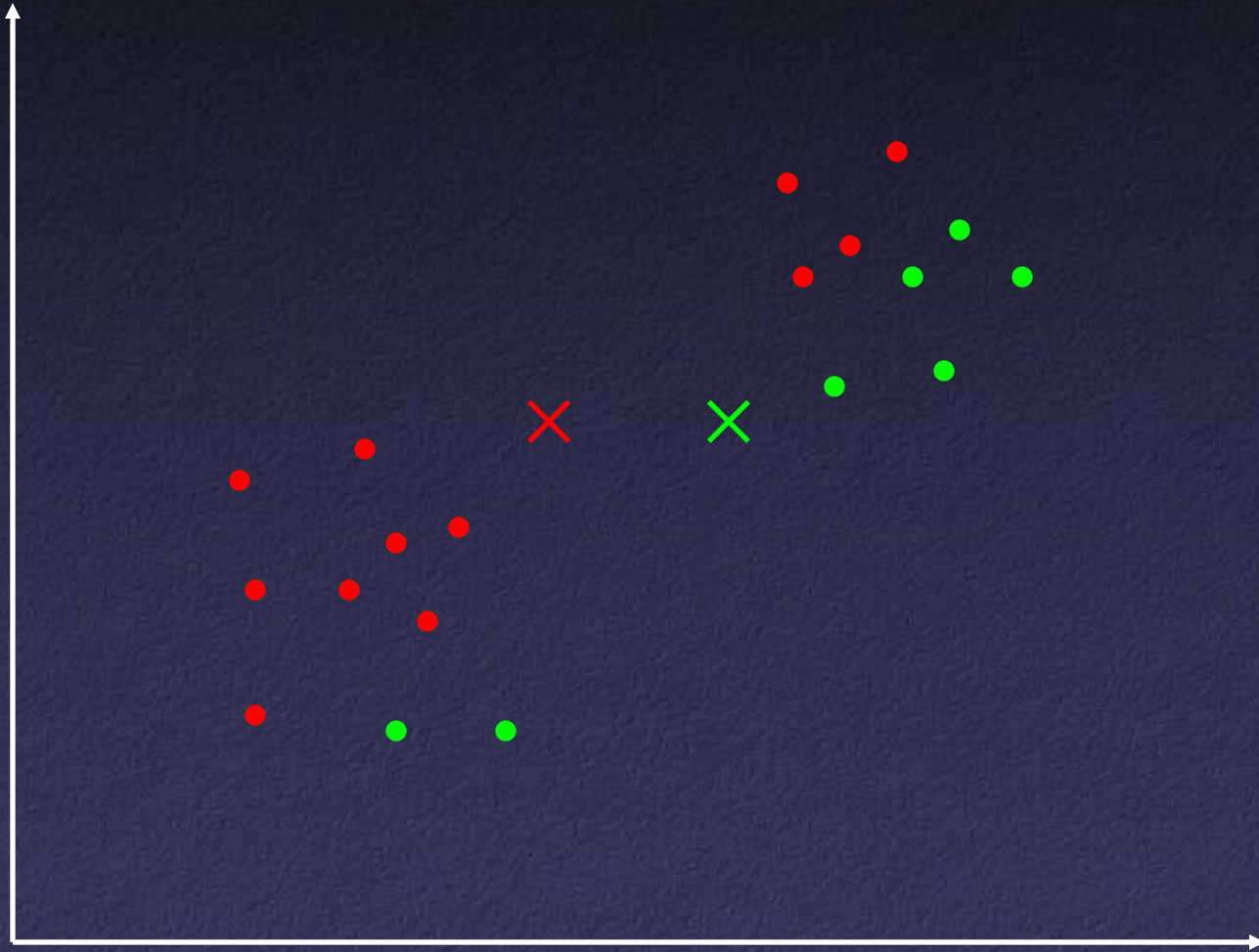
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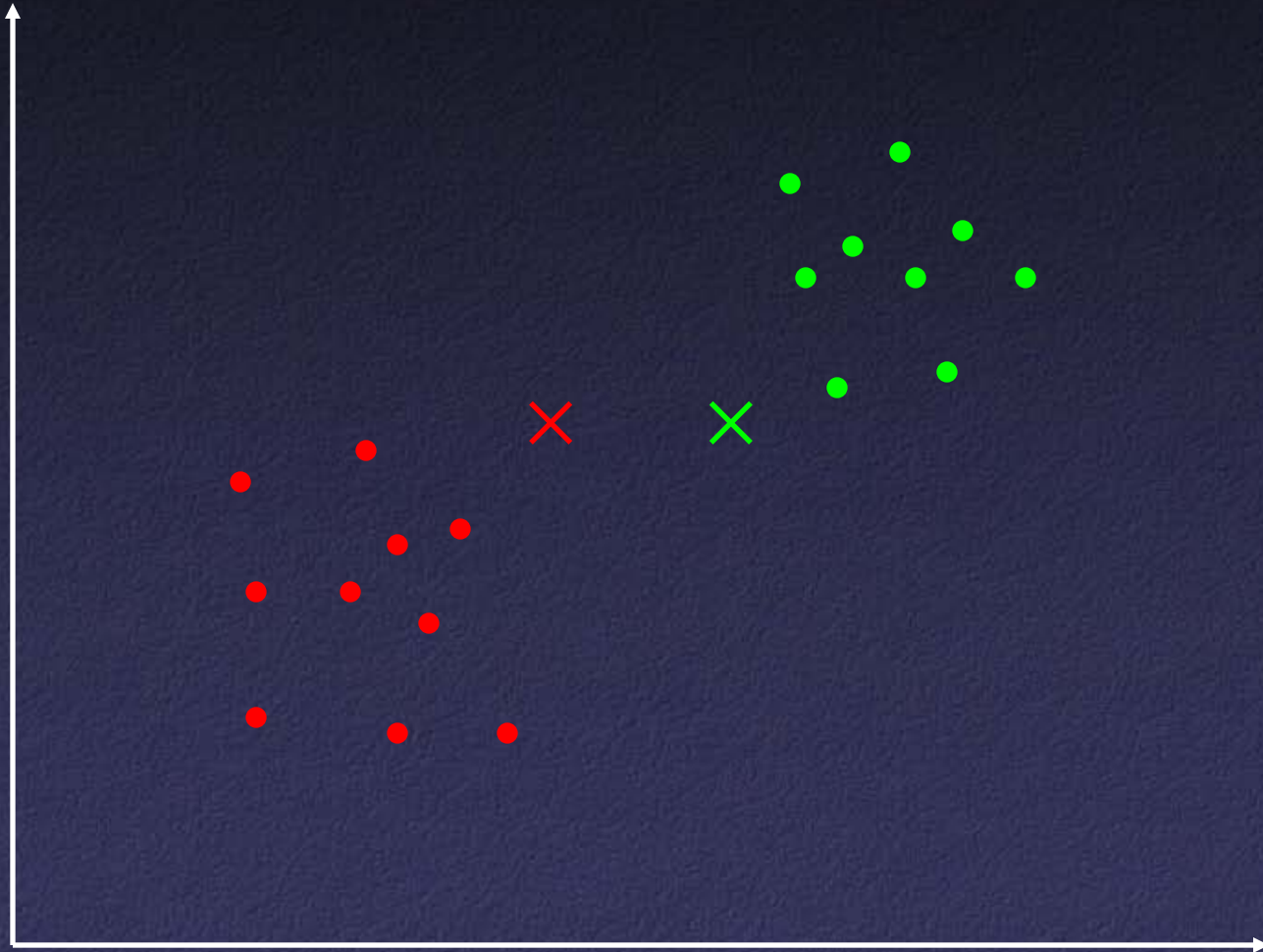
# $k$ -means Clustering

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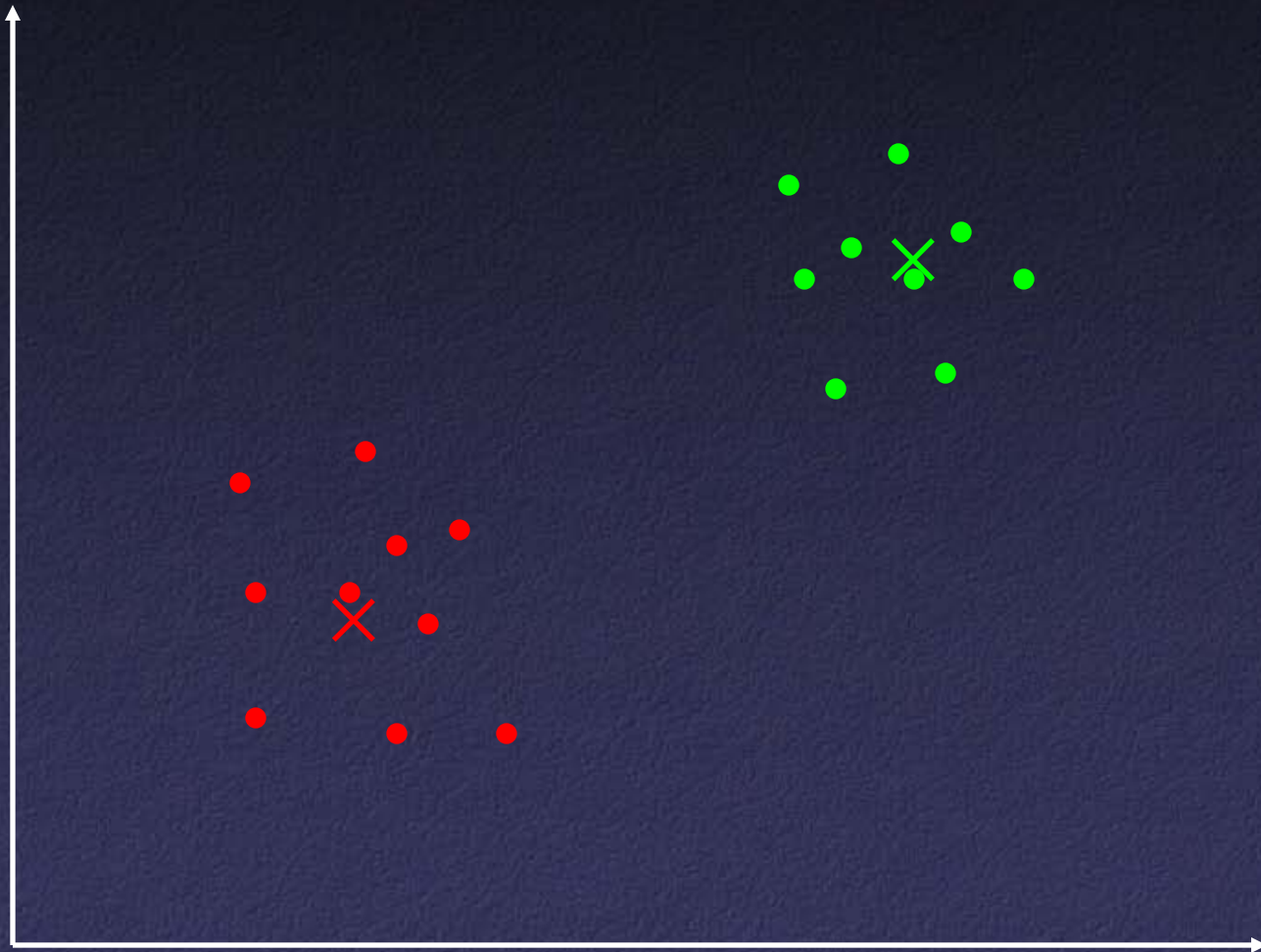
# $k$ -means Clustering

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# $k$ -means Clustering

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# Results of Clustering

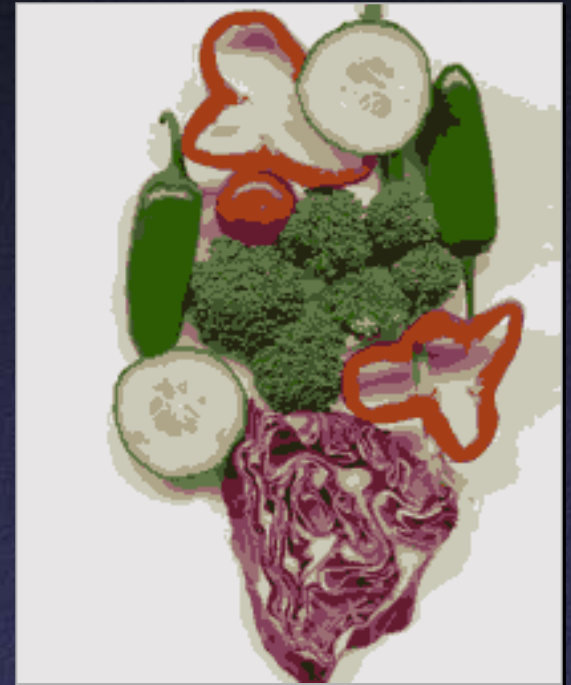
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Original Image



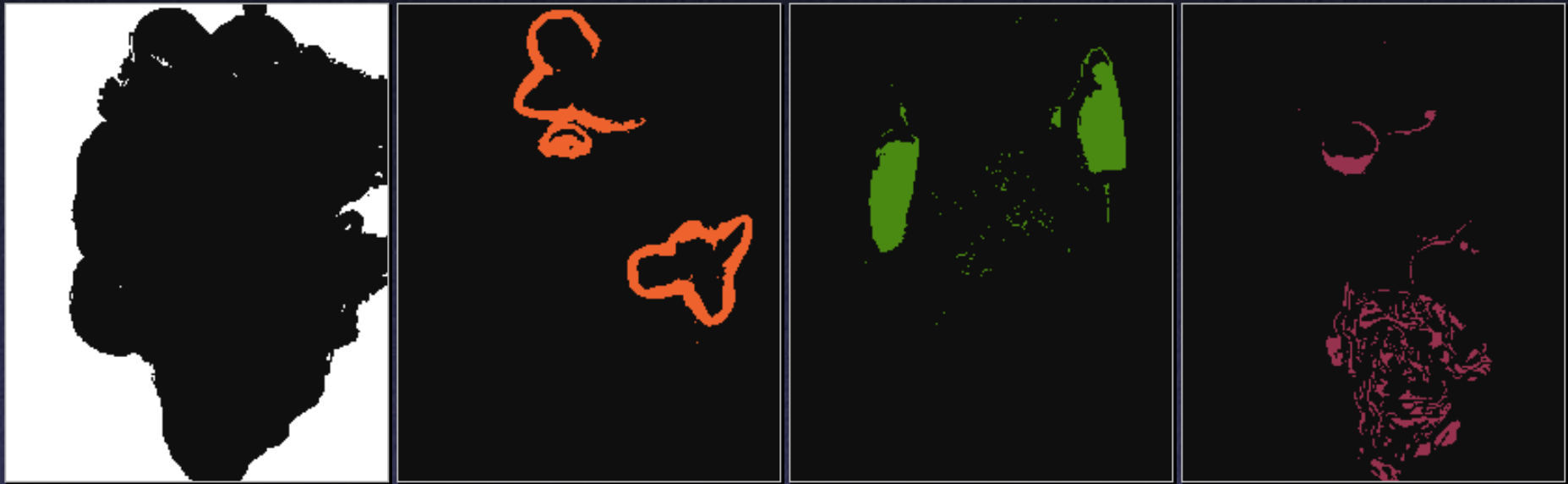
$k$ -means,  $k=5$



$k$ -means,  $k=11$

# Results of Clustering

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Sample clusters with  $k$ -means clustering  
based on color

# Other Distance Measures

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- Suppose we want to have compact regions
- New feature space: 5D  
(2 spatial coordinates, 3 color components)
- Points close in this space are close both in color and in actual proximity



# Results of Clustering

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Sample clusters with  $k$ -means clustering  
based on color and distance

# Other Distance Measures

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- Problem with simple Euclidean distance: what if coordinates range from 0-1000 but colors only range from 0-255?
  - Depending on how things are scaled, gives different weight to different kinds of data
- Weighted Euclidean distance: adjust weights to emphasize different dimensions

$$\|x - y\|^2 = \sum c_i (x_i - y_i)^2$$

# Mahalanobis Distance

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- Automatically assign weights based on actual variation in the data

$$\|\vec{x} - \vec{y}\|^2 = (\vec{x} - \vec{y})^T \mathbf{C}^{-1} (\vec{x} - \vec{y})$$

where C is covariance matrix of all points

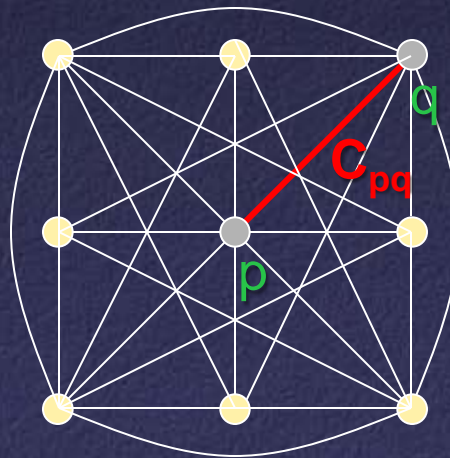
- Gives each dimension “equal” weight
- Also accounts for correlations between different dimensions



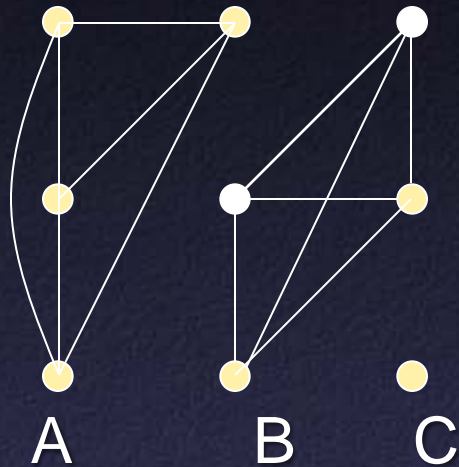
# Segmentation Based on Graph Cuts

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- Create weighted graph:
  - Nodes = pixels in image
  - Edge between each pair of nodes
  - Edge weight = similarity (intensity, color, texture, etc.)



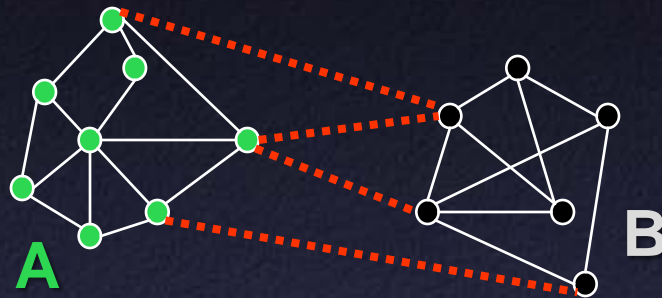
# Segmentation Based on Graph Cuts



- Partition into disconnected segments
- Easiest to break links that have low cost (low similarity)
  - similar pixels should be in the same segments
  - dissimilar pixels should be in different segments

# Cuts in a Graph

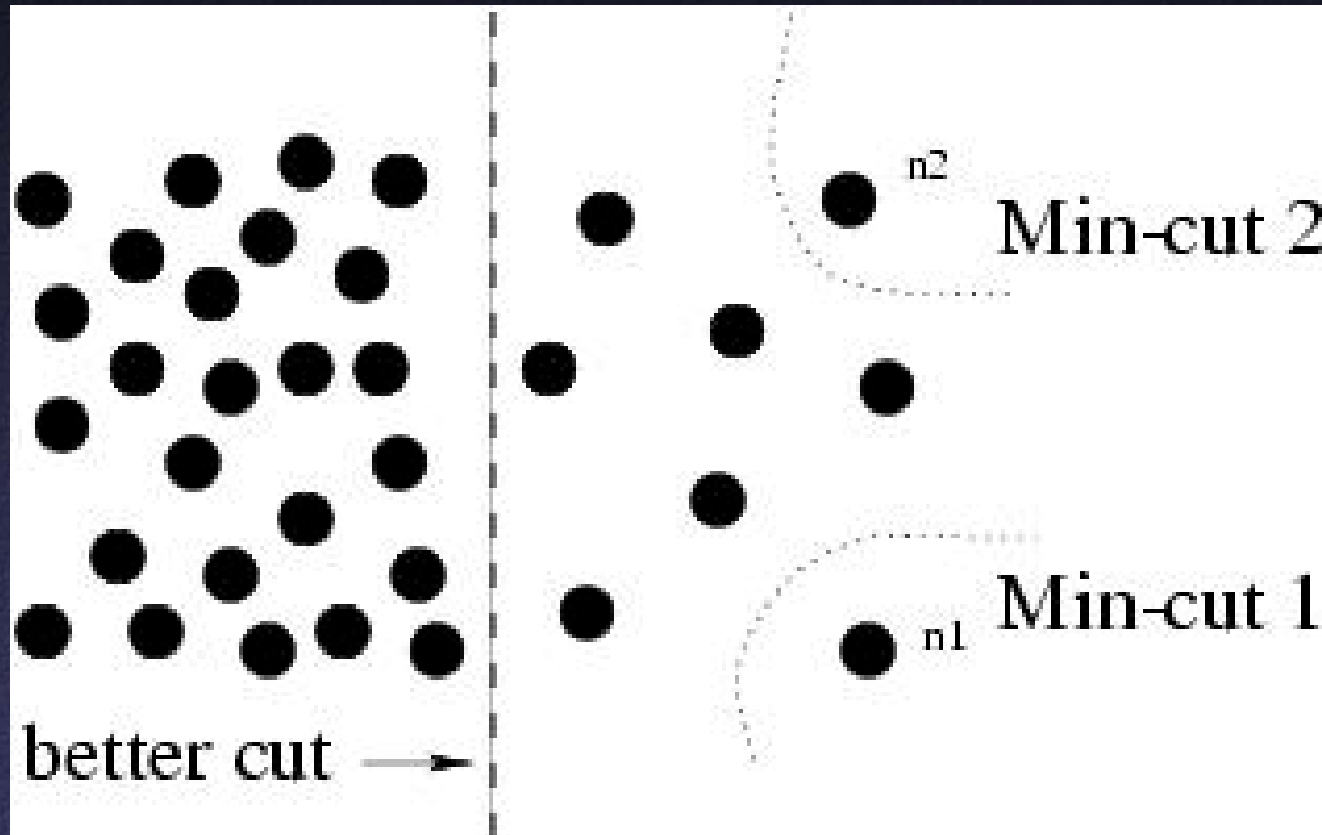
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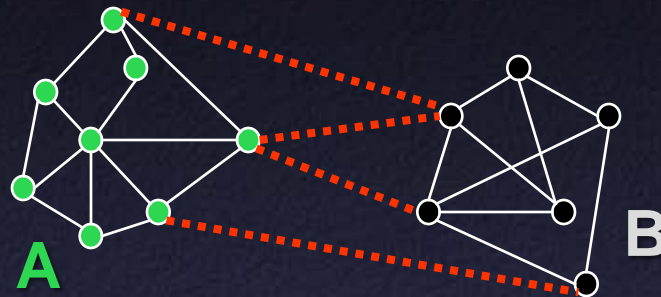
- Link Cut
  - set of links whose removal makes a graph disconnected
  - cost = sum of costs of all edges
- Min-cut
  - fast (polynomial-time) algorithm
  - gives segmentation



# But Min Cut Is Not Always the Best Cut...



# Cuts in a Graph

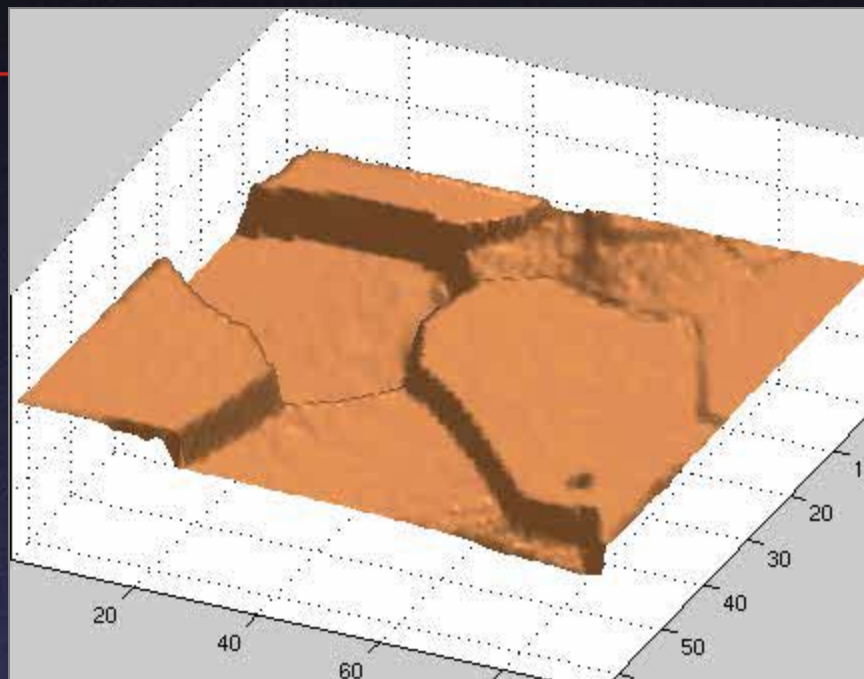


- Normalized Cut
  - removes penalty for large segments

$$Ncut(A, B) = \frac{cut(A, B)}{volume(A)} + \frac{cut(A, B)}{volume(B)}$$

- volume(A) = sum of costs of all edges that touch A
- no fast **exact** algorithms...

# Interpretation as a Dynamical System



Treat the links as springs and shake the system

- elasticity proportional to cost
- vibration “modes” correspond to segments
  - can compute these by solving a generalized eigenvector problem
  - for more details, see

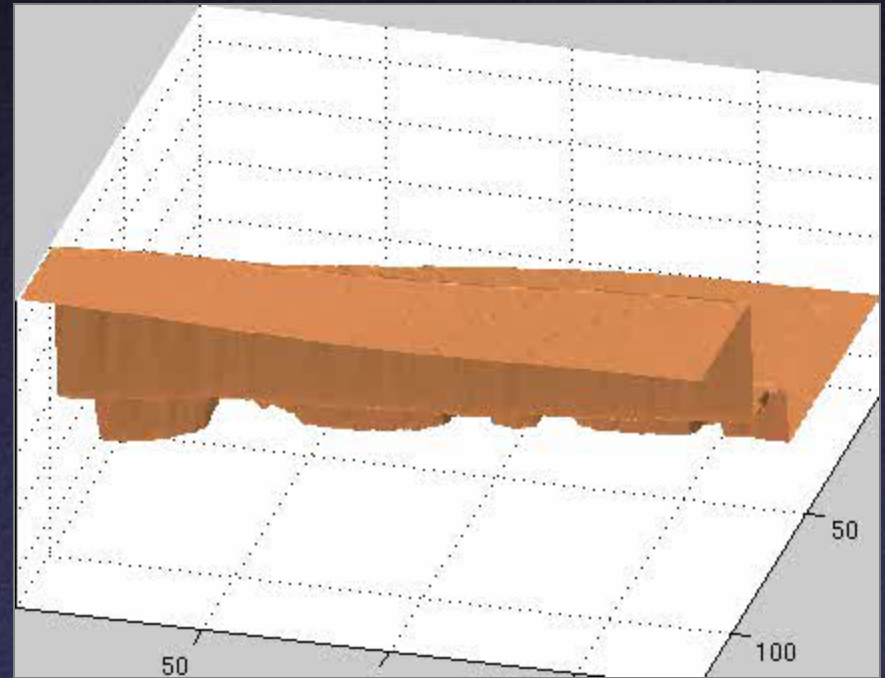
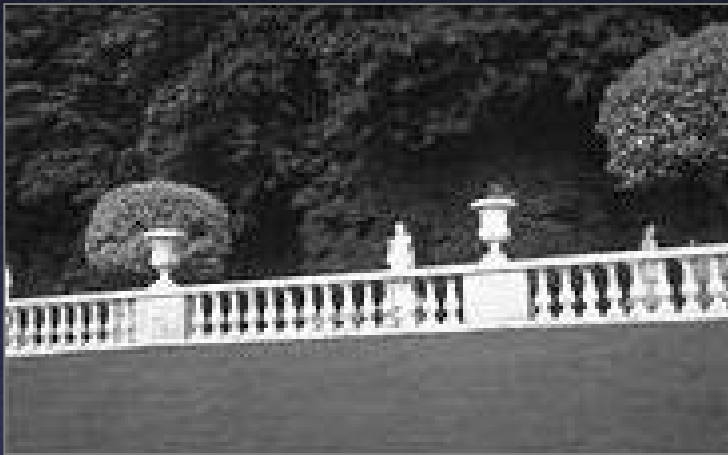
J. Shi and J. Malik, *Normalized Cuts and Image Segmentation*, CVPR, 1997

[Based on slide by S. Seitz]



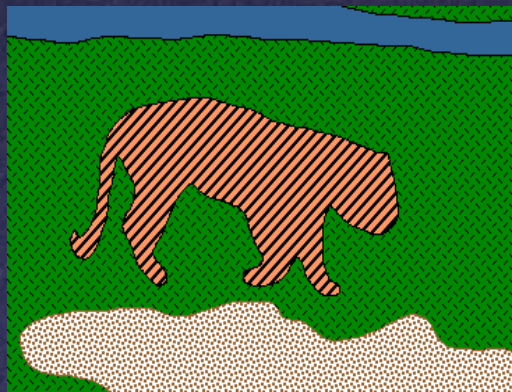
# Interpretation as a Dynamical System

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# Designing Grouping Features

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## Low-level cues

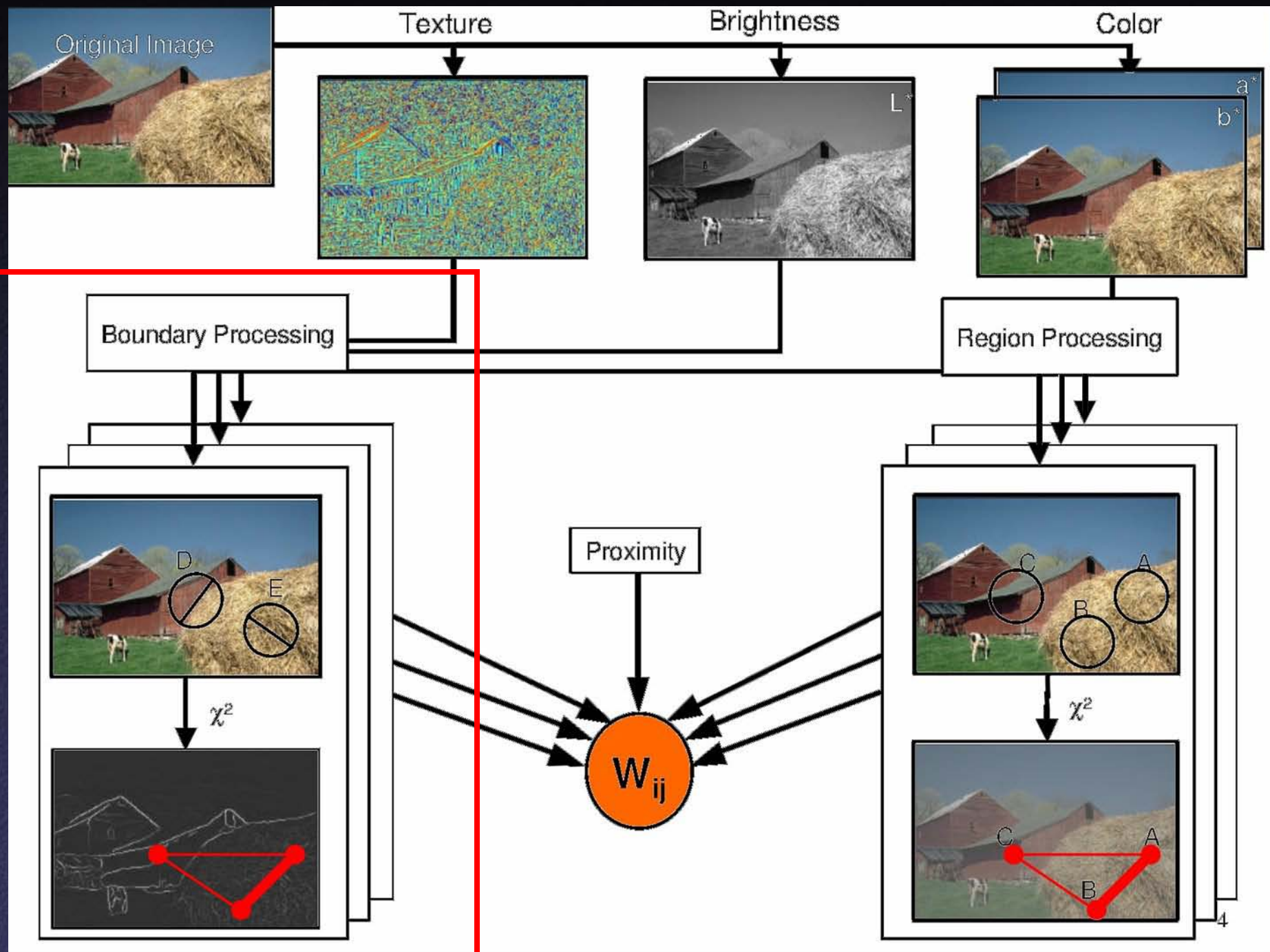
- Brightness similarity
- Color similarity
- Texture similarity

## Mid-level cues

- Contour continuity
- Convexity
- Parallelism
- Symmetry

## High-level cues

- Object knowledge
- Scene structure



Original Image

Texture

Brightness

Color

$L^*$

$a^*$

$b^*$

Boundary Processing

Region Processing

Proximity

$W_{ij}$

$\chi^2$

$\chi^2$

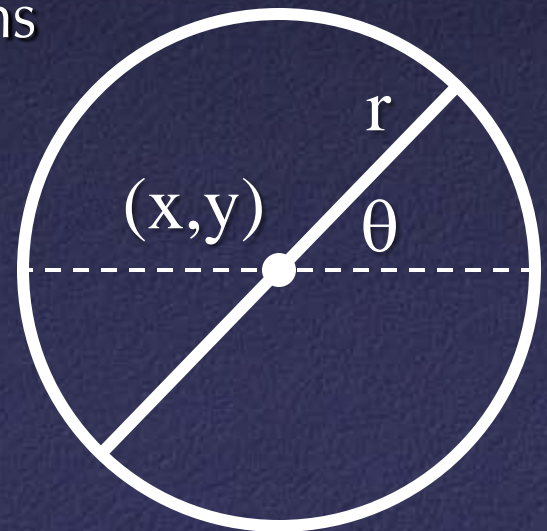
4



# Brightness and Color Contrast

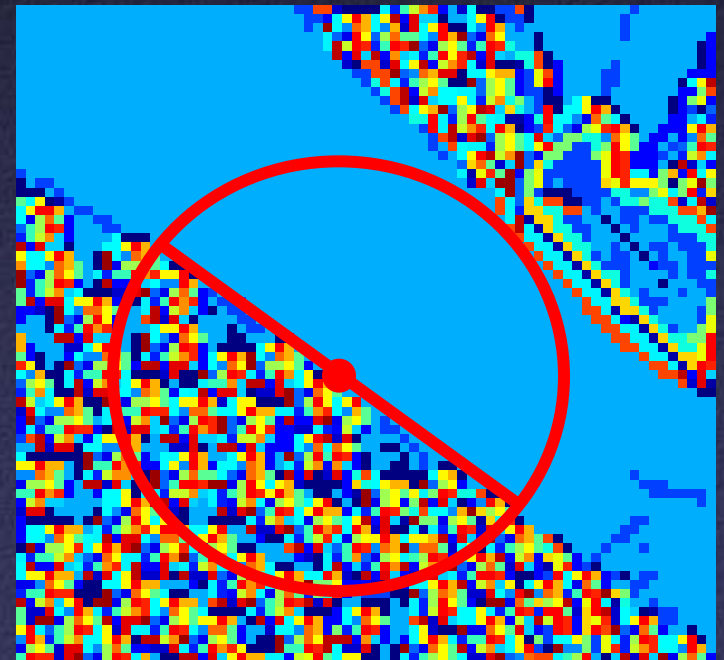
- 1976 CIE L\*a\*b\* colorspace
- Brightness Gradient  $BG(x,y,r,\theta)$   
 $\chi^2$  difference in L\* distribution
- Color Gradient  $CG(x,y,r,\theta)$   
 $\chi^2$  difference in a\* and b\* distributions

$$\chi^2(g, h) = \frac{1}{2} \sum_i \frac{(g_i - h_i)^2}{g_i + h_i}$$



# Texture Contrast

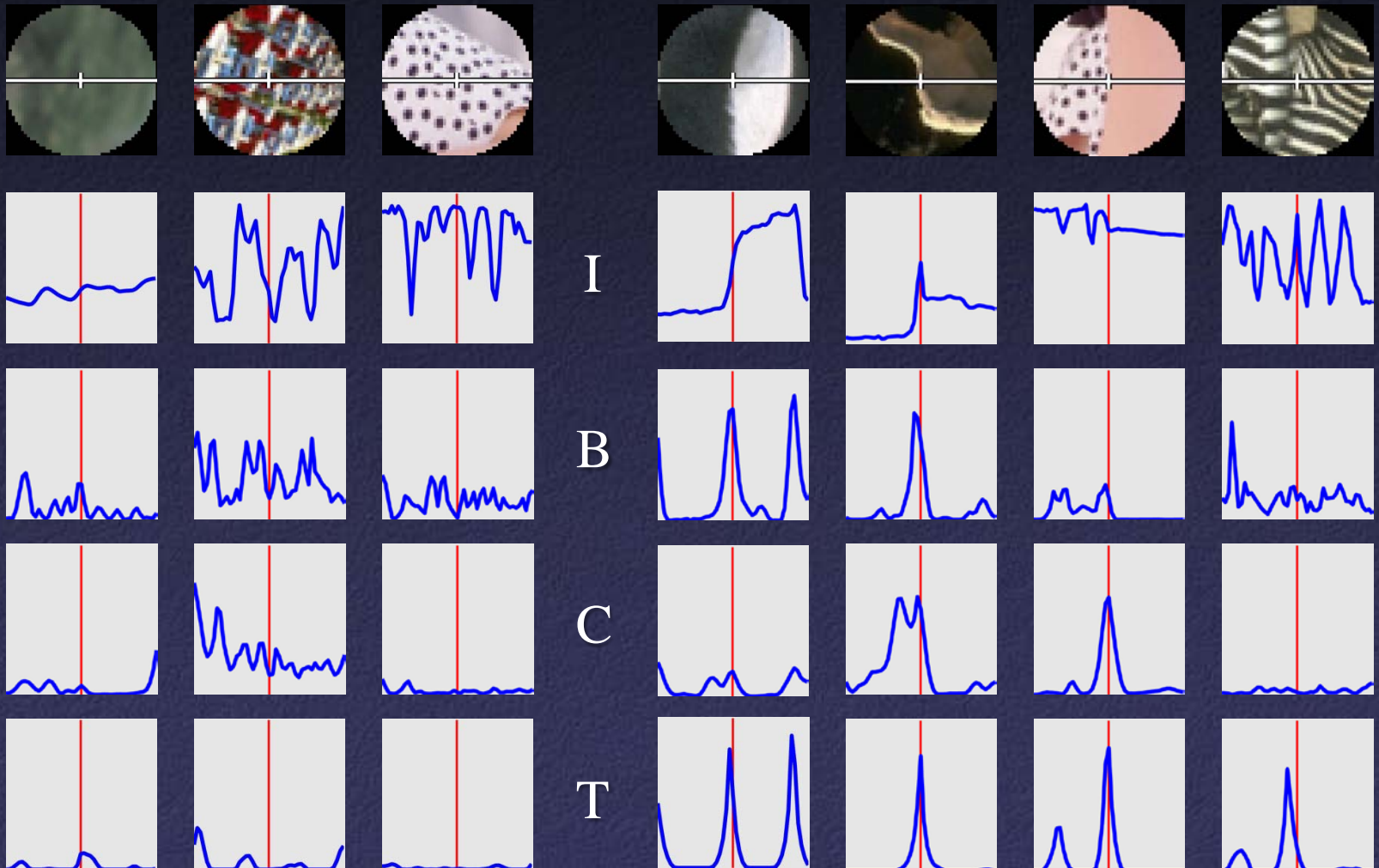
- Texture Gradient  $TG(x,y,r,\theta)$ 
  - $\chi^2$  difference of texton histograms
  - Textons are vector-quantized filter outputs (through k-means)



# Boundary Classification

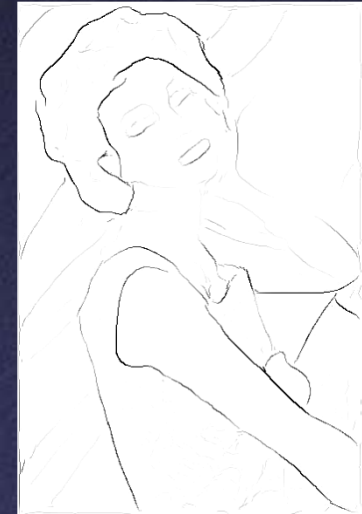
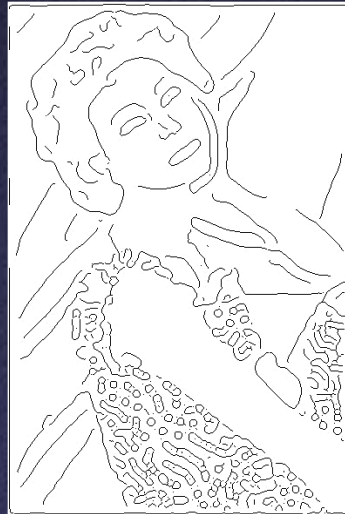
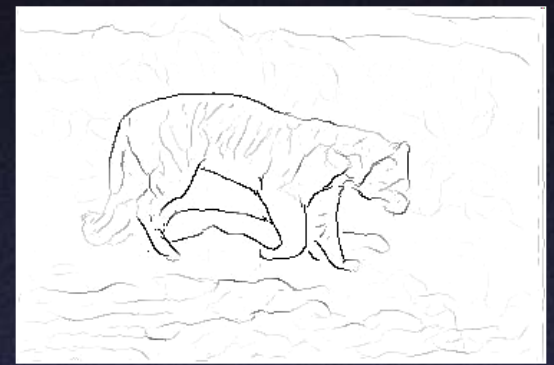
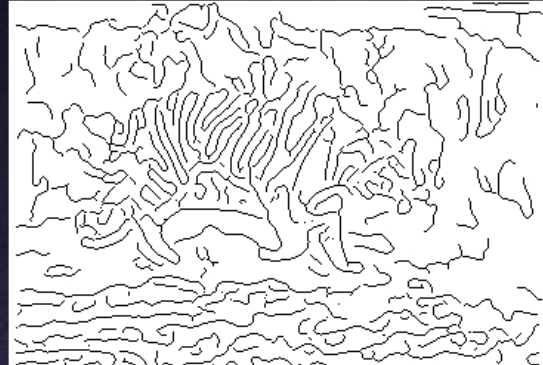
non-boundaries

boundaries





# Combining Cues



Image

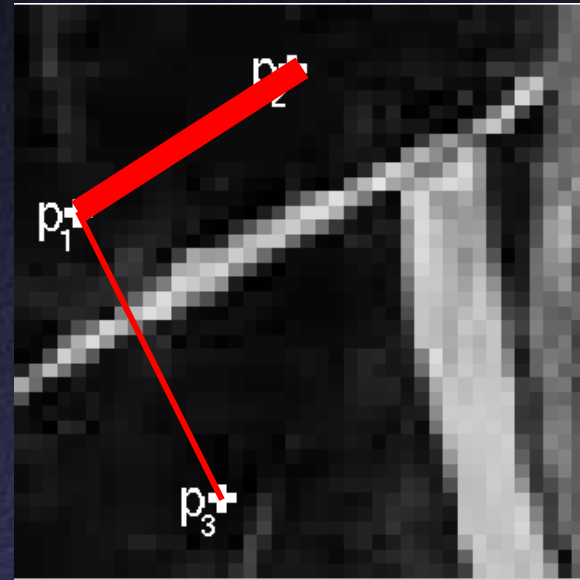
Canny

Pb

[Martin, Fowlkes, Malik, *Learning to Detect Natural Image Boundaries Using Local Brightness, Color, and Texture Cues*, PAMI 2004]

# Affinity using Intervening Contour

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$W(p_1, p_2) \gg W(p_1, p_3)$  as  $p_1$  and  $p_2$  are more likely to belong to the same region than are  $p_1$  and  $p_3$ , which are separated by a strong boundary.



