

# Monte Carlo Integration for Image Synthesis

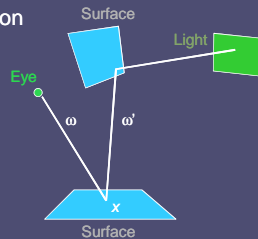
COS 526, Fall 2010  
 Tom Funkhouser  
 Slides from Rusinkiewicz, Shirley

## Outline

- Motivation
- Monte Carlo integration
- Monte Carlo path tracing
- Variance reduction techniques
- Sampling techniques
- Conclusion

## Motivation

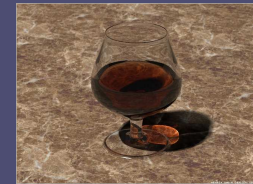
- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics



$$L_f(x, \vec{\omega}) = L_e(x, \vec{\omega}) + \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) L_f(x, \vec{\omega}') (\vec{\omega}' \cdot \vec{n}) d\vec{\omega}'$$

## Challenge

- Rendering integrals are difficult to evaluate
  - Multiple dimensions
  - Discontinuities
    - Partial occluders
    - Highlights
    - Caustics



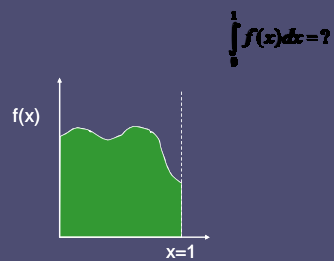
Jensen

$$L_f(x, \vec{\omega}) = L_e(x, x \rightarrow \omega) + \int_{\Omega} f_r(x, x' \rightarrow x, x \rightarrow \omega) L_f(x', x' \rightarrow \omega') V(x, x') G(x, x') d\Omega'$$

## Outline

- Motivation
- Monte Carlo integration
- Monte Carlo path tracing
- Variance reduction techniques
- Sampling techniques
- Conclusion

## Integration in 1D



Slide courtesy of Peter Shirley

### We can approximate

$$\int_a^b f(x) dx \approx \int_a^b g(x) dx$$

Slide courtesy of Peter Shirley

### Or we can average

$$\int_a^b f(x) dx \approx E(f(x))$$

Slide courtesy of Peter Shirley

### Estimating the average

$$\int_a^b f(x) dx \approx \frac{1}{N} \sum_{i=1}^N f(x_i)$$

Slide courtesy of Peter Shirley

### Other Domains

$$\int_a^b f(x) dx \approx \frac{b-a}{N} \sum_{i=1}^N f(x_i)$$

Slide courtesy of Peter Shirley

### Multidimensional Domains

- Same ideas apply for integration over ...
  - Pixel areas
  - Surfaces
  - Projected areas
  - Directions
  - Camera apertures
  - Time
  - Paths

Eye

Pixel

$$\int_{\text{Surface}} f(x) dx \approx \frac{1}{N} \sum_{i=1}^N f(x_i)$$

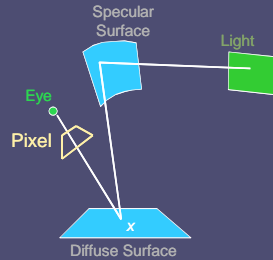
Surface

### Outline

- Motivation
- Monte Carlo integration
- Monte Carlo path tracing
- Variance reduction techniques
- Sampling techniques
- Conclusion

### Monte Carlo Path Tracing

- Integrate radiance for each pixel by sampling paths randomly

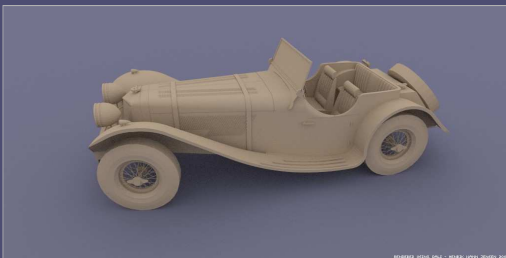


$$L_p(x, \vec{\omega}) = L_e(x, \vec{\omega}) + \int_{\Omega} f_r(x, \vec{\omega}, \vec{\omega}') L_p(x, \vec{\omega}') (\vec{\omega}' \cdot \vec{n}) d\vec{\omega}'$$

### Simple Monte Carlo Path Tracer

- Step 1: Choose a ray  $p = \text{camera}$ ,  $d = (\theta, \phi)$ ; assign weight = 1
- Step 2: Trace ray to find intersection with nearest surface
- Step 3: Randomly choose between emitted and reflected light
  - Step 3a: If emitted, return weight \*  $L_e$
  - Step 3b: If reflected, weight \*= reflectance. Generate ray in random direction. Go to step 2

### Monte Carlo Path Tracing



Big diffuse light source, 20 minutes

Jensen

### Monte Carlo Path Tracing

- Advantages
  - Any type of geometry (procedural, curved, ...)
  - Any type of BRDF (specular, glossy, diffuse, ...)
  - Samples all types of paths (L(SD)\*E)
  - Accuracy controlled at pixel level
  - Low memory consumption
  - Unbiased - error appears as noise in final image
- Disadvantages
  - Slow convergence
  - Noise in final image

### Monte Carlo Path Tracing

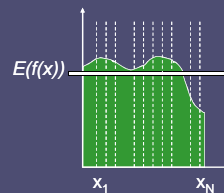


1000 paths/pixel

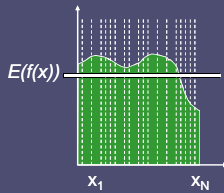
Jensen

### Variance

$$\text{var}[f(x)] = \frac{1}{N} \sum_{i=1}^N [f(x_i) - E(f(x))]^2$$



### Variance



$$\text{var}[E(f(x))] = \frac{1}{N} \text{var}[f(x)]$$

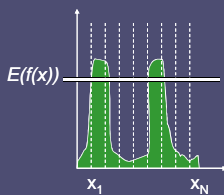
Variance decreases as 1/N  
Error decreases as 1/sqrt(N)

### Outline

- Motivation
- Monte Carlo integration
- Monte Carlo path tracing
- Variance reduction techniques
- Sampling techniques
- Conclusion

### Variance

- Problem: variance decreases with 1/N  
– Increasing # samples removes noise slowly



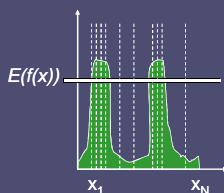
### Variance Reduction Techniques

- Importance sampling
- Stratified sampling
- Metropolis sampling
- Quasi-random

$$\int f(x) dx = \frac{1}{N} \sum_{i=1}^N f(x_i)$$

### Importance Sampling

- Put more samples where f(x) is bigger

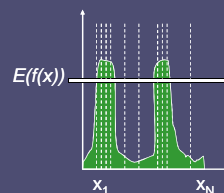


$$\int_{\Omega} f(x) dx = \frac{1}{N} \sum_{i=1}^N Y_i$$

$$Y_i = \frac{f(x_i)}{p(x_i)}$$

### Importance Sampling

- This is still unbiased



$$E[Y_i] = \int_{\Omega} Y(x) p(x) dx$$

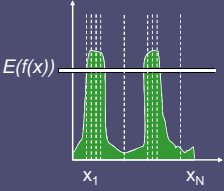
$$= \int_{\Omega} \frac{f(x)}{p(x)} p(x) dx$$

$$= \int_{\Omega} f(x) dx$$

for all N

### Importance Sampling

- Zero variance if  $p(x) \sim f(x)$



$$p(x) = c f(x)$$

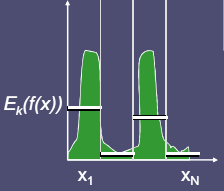
$$Y_i = \frac{f(x_i)}{p(x_i)} = \frac{1}{c}$$


$$\text{Var}(Y) = 0$$

Less variance with better importance sampling

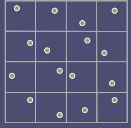
### Stratified Sampling

- Estimate subdomains separately



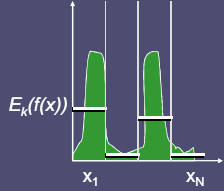


Arvo



### Stratified Sampling

- This is still unbiased

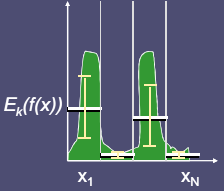


$$F_N = \frac{1}{N} \sum_{i=1}^N f(x_i)$$

$$= \frac{1}{N} \sum_{i=1}^N N_i F_i$$

### Stratified Sampling

- Less overall variance if less variance in subdomains



$$\text{Var}[F_N] = \frac{1}{N^2} \sum_{i=1}^N N_i \text{Var}[F_i]$$

### Outline

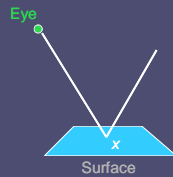
- Motivation
- Monte Carlo integration
- Monte Carlo path tracing
- Variance reduction techniques
- Sampling techniques
- Conclusion

### Simple Monte Carlo Path Tracer

- Step 1: Choose a ray  $(u, v, \theta, \phi)$ ; assign weight = 1
- Step 2: Trace ray to find intersection with nearest surface
- Step 3: Randomly choose between emitted and reflected light
  - Step 3a: If emitted, return weight \* Le
  - Step 3b: If reflected, weight \*= reflectance  
Generate ray in random direction  
Go to step 2

### Sampling Techniques

- Problem: how do we generate random points/directions during path tracing?
  - Non-rectilinear domains
  - Importance (BRDF)
  - Stratified



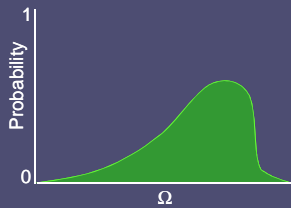
### Generating Random Points

- Uniform distribution:
  - Use random number generator



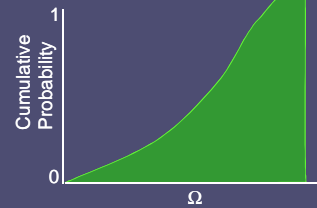
### Generating Random Points

- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



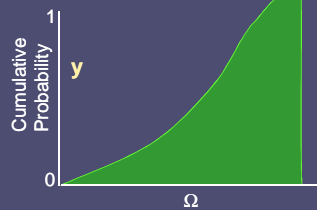
### Generating Random Points

- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



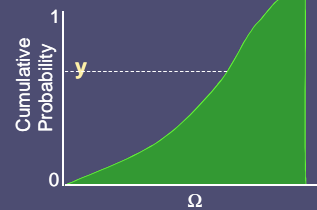
### Generating Random Points

- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



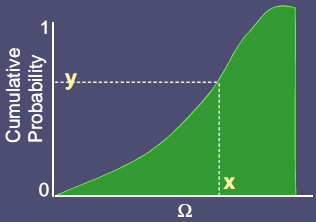
### Generating Random Points

- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



### Generating Random Points

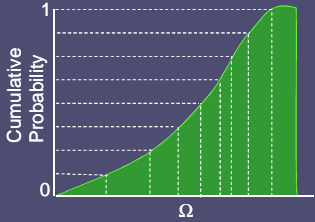
- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



A graph showing Cumulative Probability on the y-axis (ranging from 0 to 1) and  $\Omega$  on the x-axis. A green shaded area under a curve represents the cumulative distribution function. A horizontal dashed line at height  $y$  intersects the curve, and a vertical dashed line drops from that intersection point to the x-axis at position  $x$ .

### Generating Random Points

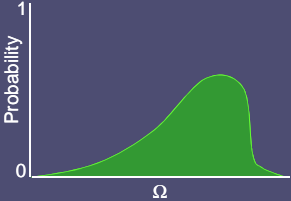
- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



A graph showing Cumulative Probability on the y-axis (ranging from 0 to 1) and  $\Omega$  on the x-axis. A green shaded area under a curve represents the cumulative distribution function. Multiple horizontal dashed lines at various heights intersect the curve, and vertical dashed lines drop from each intersection point to the x-axis, representing multiple random points generated via the inversion method.

### Generating Random Points

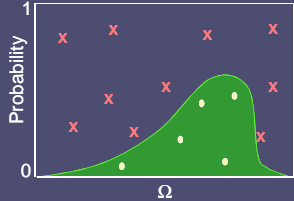
- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



A graph showing Probability on the y-axis (ranging from 0 to 1) and  $\Omega$  on the x-axis. A green shaded area under a bell-shaped curve represents the probability density function.

### Generating Random Points

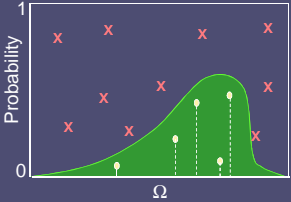
- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



A graph showing Probability on the y-axis (ranging from 0 to 1) and  $\Omega$  on the x-axis. A green shaded area under a bell-shaped curve represents the probability density function. Several red 'x' marks are scattered above the curve, and several white dots are scattered below the curve, representing generated points.

### Generating Random Points

- Specific probability distribution:
  - Function inversion
  - Rejection
  - Metropolis



A graph showing Probability on the y-axis (ranging from 0 to 1) and  $\Omega$  on the x-axis. A green shaded area under a bell-shaped curve represents the probability density function. Several red 'x' marks are scattered above the curve, and several white dots are scattered below the curve. Vertical dashed lines connect some of the white dots to the curve, and horizontal dashed lines connect some of the red 'x' marks to the curve, illustrating the rejection process.

### Combining Multiple PDFs

- Balance heuristic
  - Use combination of samples generated for each PDF
  - Number of samples for each PDF chosen by weights
  - Near optimal

### Monte Carlo Extensions

- Unbiased
  - Bidirectional path tracing
  - Metropolis light transport
- Biased, but consistent
  - Noise filtering
  - Adaptive sampling
  - Irradiance caching

### Monte Carlo Extensions

- Unbiased
  - Bidirectional path tracing
  - Metropolis light transport
- Biased, but consistent
  - Noise filtering
  - Adaptive sampling
  - Irradiance caching



RenderPark

### Monte Carlo Extensions

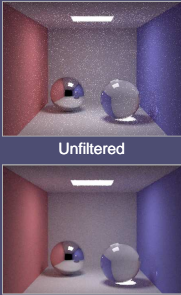
- Unbiased
  - Bidirectional path tracing
  - Metropolis light transport
- Biased, but consistent
  - Noise filtering
  - Adaptive sampling
  - Irradiance caching



Heinrich

### Monte Carlo Extensions

- Unbiased
  - Bidirectional path tracing
  - Metropolis light transport
- Biased, but consistent
  - Noise filtering
  - Adaptive sampling
  - Irradiance caching



Unfiltered

Filtered

Jensen

### Monte Carlo Extensions

- Unbiased
  - Bidirectional path tracing
  - Metropolis light transport
- Biased, but consistent
  - Noise filtering
  - Adaptive sampling
  - Irradiance caching



Fixed

Adaptive

Ohbuchi

### Monte Carlo Extensions

- Unbiased
  - Bidirectional path tracing
  - Metropolis light transport
- Biased, but consistent
  - Noise filtering
  - Adaptive sampling
  - Irradiance caching



Jensen



## Summary

- Monte Carlo Integration Methods
  - Very general
  - Good for complex functions with high dimensionality
  - Converge slowly (but error appears as noise)
- Conclusion
  - Preferred method for difficult scenes
  - Noise removal (filtering) and irradiance caching (photon maps) used in practice

## More Information

- Books
  - *Realistic Ray Tracing*, Peter Shirley
  - *Realistic Image Synthesis Using Photon Mapping*, Henrik Wann Jensen
- Theses
  - *Robust Monte Carlo Methods for Light Transport Simulation*, Eric Veach
  - *Mathematical Models and Monte Carlo Methods for Physically Based Rendering*, Eric La Fortune
- Course Notes
  - *Mathematical Models for Computer Graphics*, Stanford, Fall 1997
  - *State of the Art in Monte Carlo Methods for Realistic Image Synthesis*, Course 29, SIGGRAPH 2001