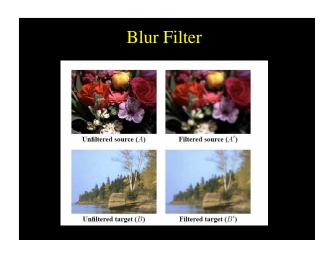


## Implementation Details

- Use approximate nearest neighbor search and Ashikhmin's *coherence search* heuristic
- Use *feature vectors* instead of pixel values
  - Feature vector can consist of RGB values plus additional "channels" such as luminance, outputs of derivative filters
- Luminance remapping to align color histograms of source and target images



## Unfiltered target (B) Filtered target (B')

