

Constrained Optimization

COS 323

Linear Objective, Linear Constraints

Standard form: maximize objective

$$\zeta = c_1x_1 + c_2x_2 + \dots$$

with primary constraints

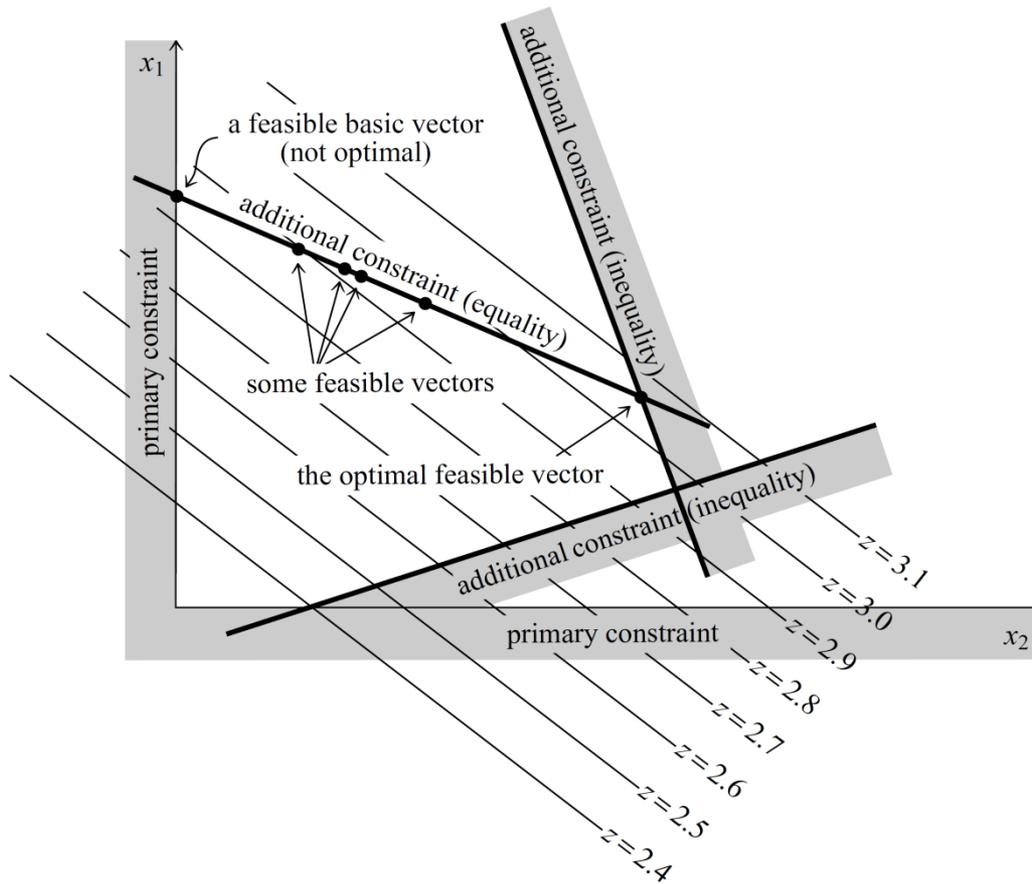
$$x_1 \geq 0, x_2 \geq 0, \dots$$

and additional constraints

$$a_{11}x_1 + a_{12}x_2 + \dots \leq b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots \leq b_2$$

Linear Programming



Simplex Method

- Slides from Robert Vanderbei

Simplex Method

- In theory: can take very long – exponential in the input length
- In practice: efficient – # of iterations typically a few times # of constraints
- There exist provably polynomial-time algorithms

General Optimization with Equality Constraints

- Minimize $f(x)$ subject to $g_i(x) = 0$
- Method of Lagrange multipliers: convert to a higher-dimensional problem
- Minimize $f(x) + \sum \lambda_i g_i(x)$ w.r.t. $(x_1 \dots x_n; \lambda_1 \dots \lambda_k)$

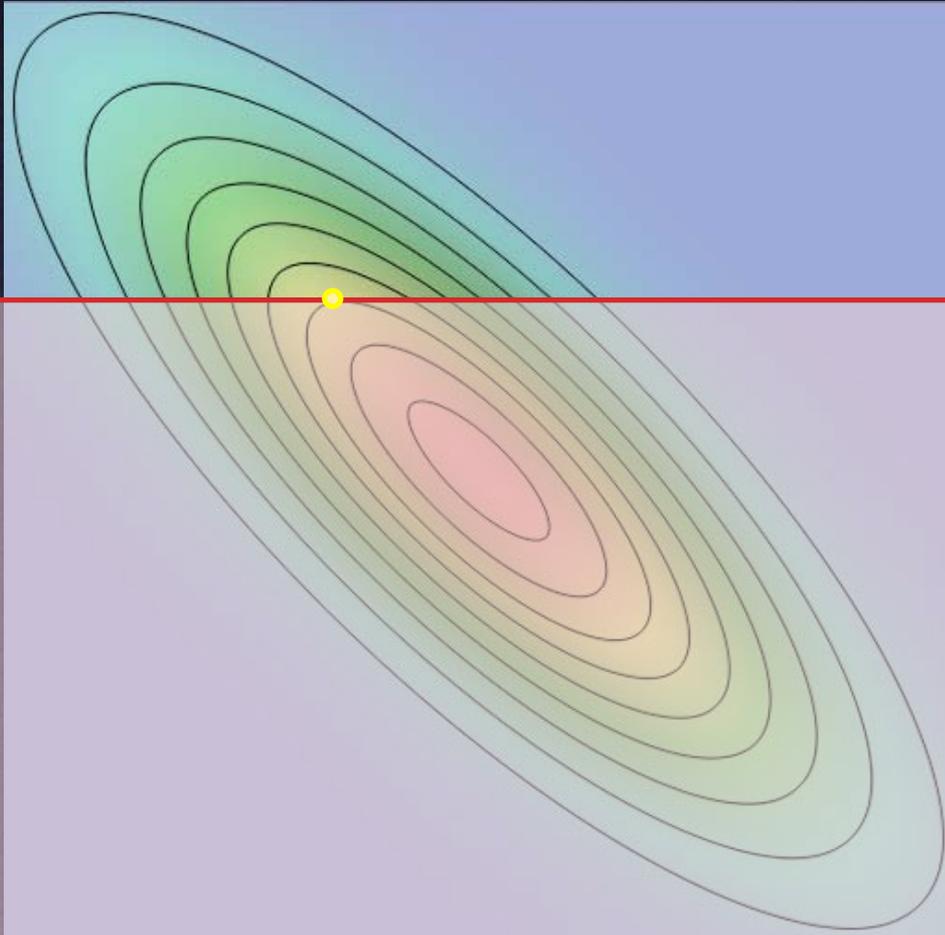
General Optimization with Inequality Constraints

- Minimize $f(x)$ subject to $h_i(x) \leq 0$
- Karush-Kuhn-Tucker (KKT) conditions
- Minimize $f(x) + \sum \lambda_i h_i(x)$ w.r.t. $(x_1 \dots x_n; \lambda_1 \dots \lambda_k)$
- Subject to $h_i(x) \leq 0, \lambda_i(x) \geq 0, \lambda_i(x) h_i(x) = 0$

KKT Conditions

minimize $f(x)$
with $h(x) \leq 0$

1. $\frac{\partial}{\partial x}(f(x) + \lambda h(x)) = 0$
2. $\frac{\partial}{\partial \lambda}(f(x) + \lambda h(x)) = 0$
3. $h(x) \leq 0$
4. $\lambda \geq 0$
5. $\lambda h(x) = 0$



Quadratic Programming

- The KKT conditions allow writing a system with **quadratic** objective and **linear** constraints as a linear program
 - Solve with simplex, etc.