COS 318: Operating Systems Message Passing

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http://www.cs.princeton.edu/courses/archive/fall10/cos318/

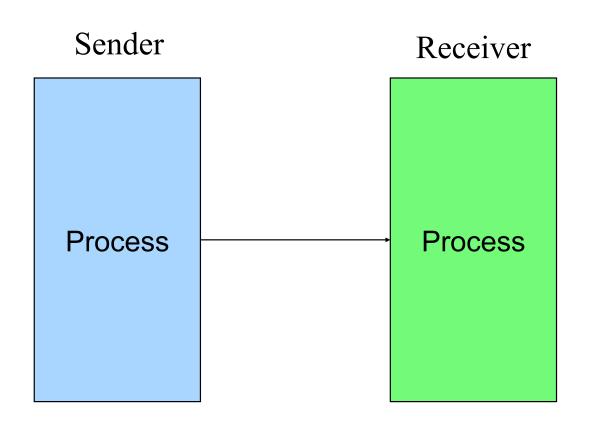


Today's Topics

- Message passing
 - Semantics
 - How to use
- Implementation issues
 - Synchronous vs. asynchronous
 - Buffering
 - Indirection
 - Exceptions

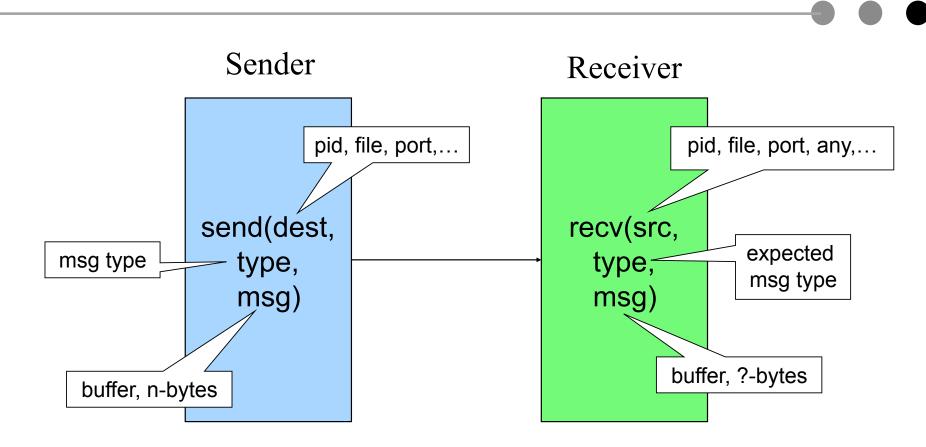


Big Picture





Send and Receive Primitives

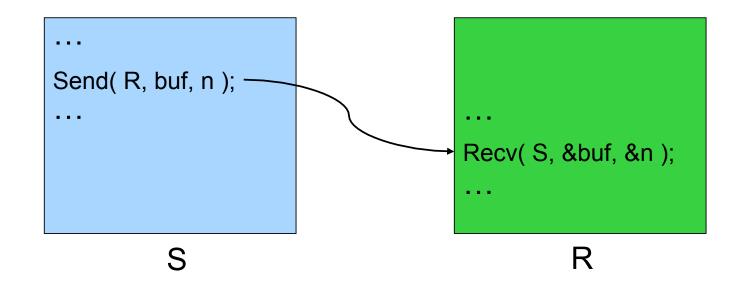


Many ways to design the message passing API



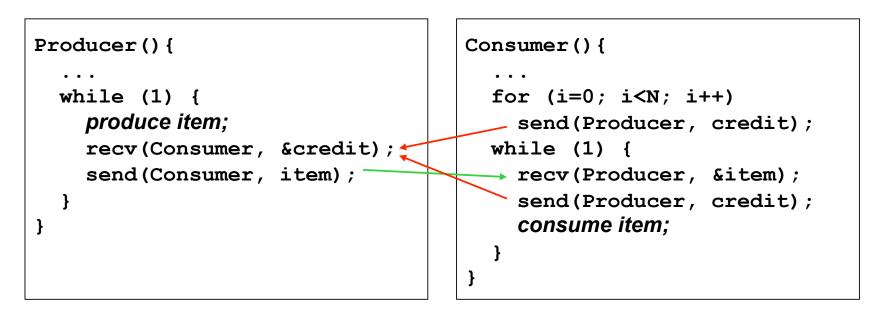
Synchronous Message Passing

- Move data between processes
 - Sender: when data is ready, send it to the receiver process
 - Receiver: when the data has arrived and when the receive process is ready to take the data, move the data
- Synchronization
 - Sender: signal the receiver process that a particular event happens
 - Receiver: block until the event has happened





Example: Producer-Consumer



Questions

- Does this work?
- Would it work with multiple producers and 1 consumer?
- Would it work with 1 producer and multiple consumers?
- What about multiple producers and multiple consumers?



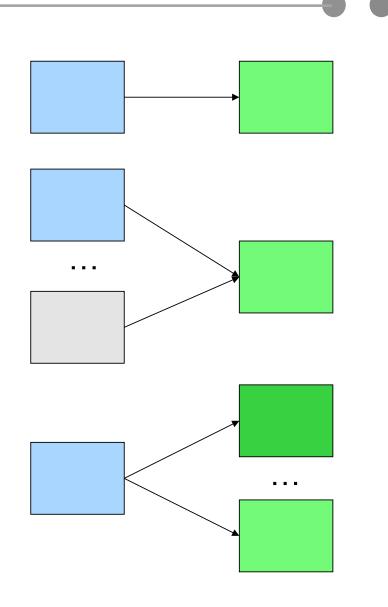
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Implementation Issues

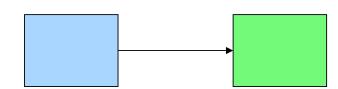
- Buffering messages
- Direct vs. indirect
- Unidirectional vs.
 bidirectional
- Asynchronous vs. synchronous
- Event handler vs. receive
- How to handle exceptions?

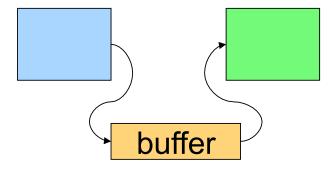




Buffering Messages

- No buffering
 - Sender must wait until the receiver receives the message
 - Rendezvous on each message
- Bounded buffer
 - Finite size
 - Sender blocks on buffer full
 - Use mesa-monitor to solve the problem
- Unbounded buffer
 - "Infinite" size
 - Sender never blocks

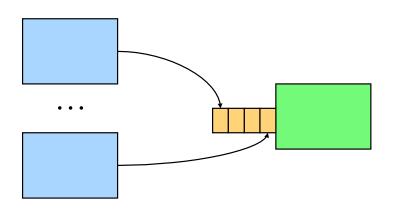


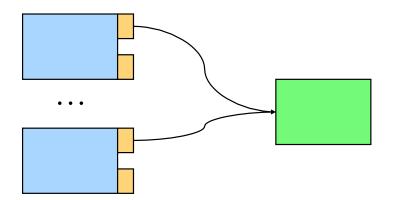




Direct Communication

- A single buffer at the receiver
 - More than one process may send messages to the receiver
 - To receive from a specific sender, it requires searching through the whole buffer
- A buffer at each sender
 - A sender may send messages to multiple receivers
 - To get a message, it also requires searching through the whole buffer

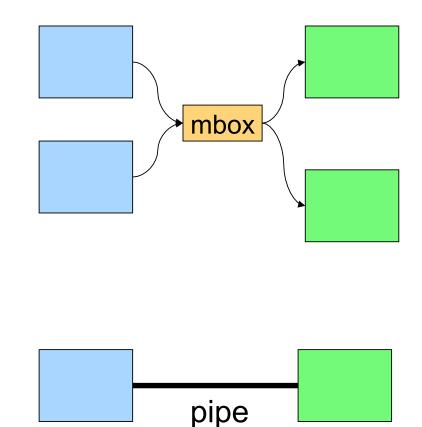






Indirect Communication

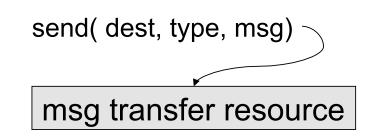
- Use mailbox as the abstraction
 - Allow many-to-many communication
 - Require open/close a mailbox
- Buffering
 - A buffer, its mutex and condition variables should be at the mailbox
- Message size
 - Not necessarily. One can break a large message into packets
- Mailbox vs. pipe
 - A mailbox allows many to many communication
 - A pipe implies one sender and one receiver





Synchronous vs. Asynchronous: Send

- Synchronous
 - Block on if resource is busy
 - Initiate data transfer
 - Block until data is out of its source memory
- Asynchronous
 - Block if resource is busy
 - Initiate data transfer and return
 - Completion
 - Require applications to check status
 - Notify or signal the application



```
status = async_send( dest, type, msg )
```

```
if !send_complete( status )
    wait for completion;
```

```
use msg data structure;
```

. . .



Synchronous vs. Asynchronous: Receive

- Synchronous
 - Return data if there is a message

msg transfer resource

```
➤ recv( src, type, msg )
```



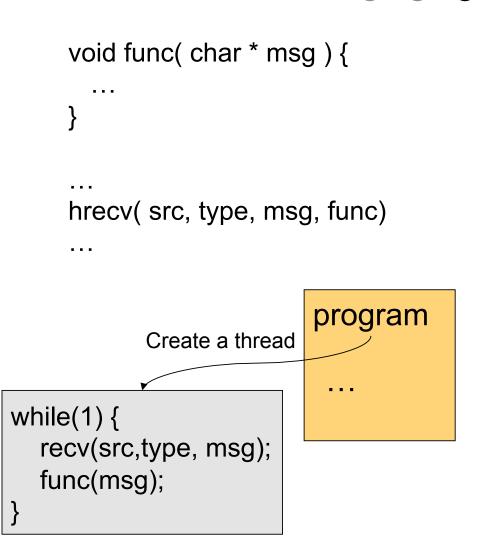
- Return data if there is a message
- Return status if there is no message (probe)

while (probe(src) != HaveMSG)
 wait for msg arrival
recv(src, type, msg);
consume msg;



Event Handler vs. Receive

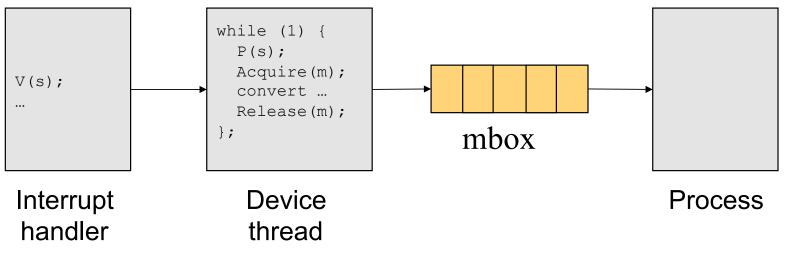
- hrecv(src, type, msg, func)
 - msg is an arg of func
 - Execute "func" on a message arrival
- Which one is more powerful?
 - Recv with a thread can emulate a Handler
 - Handler can be used to emulate recv by using Monitor
- Pros and Cons





Example: Keyboard Input

- How do you implement keyboard input?
 - Need an interrupt handler
 - Generate a mbox message from the interrupt handler
- Suppose a keyboard device thread converts input characters into an mbox message
 - How would you synchronize between the keyboard interrupt handler and device thread?
 - How can a device thread convert input into mbox messages?





Exception: Process Termination

- R waits for a message from S, but S has terminated
 - Problem: R may be blocked forever



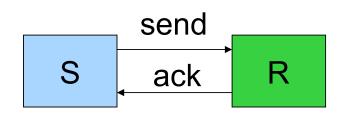
- S sends a message to R, but R has terminated
 - Problem: S has no buffer and will be blocked forever





Exception: Message Loss

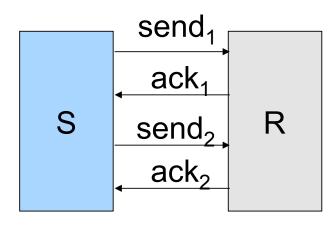
- Use ack and timeout to detect and retransmit a lost message
 - Require the receiver to send an ack message for each message
 - Sender blocks until an ack message is back or timeout status = send(dest, msg, timeout);
 - If timeout happens and no ack, then retransmit the message
- Issues
 - Duplicates
 - Losing ack messages





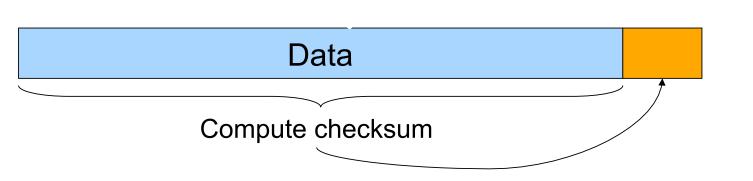
Exception: Message Loss, cont'd

- Retransmission must handle
 - Duplicate messages on receiver side
 - Out-of-sequence ack messages on sender side
- Retransmission
 - Use sequence number for each message to identify duplicates
 - Remove duplicates on receiver side
 - Sender retransmits on an out-ofsequence ack
- Reduce ack messages
 - Bundle ack messages
 - Receiver sends noack messages: can be complex
 - Piggy-back acks in send messages





Exception: Message Corruption





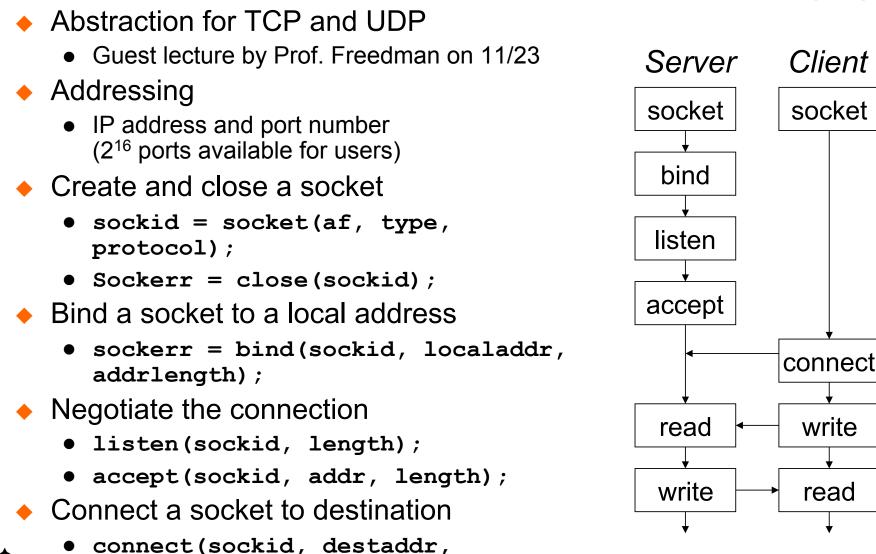
- Compute a checksum over the entire message and send the checksum (e.g. CRC code) as part of the message
- Recompute a checksum on receive and compare with the checksum in the message

Correction

- Trigger retransmission
- Use correction codes to recover



Example: Sockets API





addrlength);

Summary

- Message passing
 - Move data between processes
 - Implicit synchronization
 - API design is important
- Implementation issues
 - Synchronous method is most common
 - Asynchronous method provides overlapping but requires careful design considerations
 - Indirection makes implementation flexible
 - Exception needs to be carefully handled

