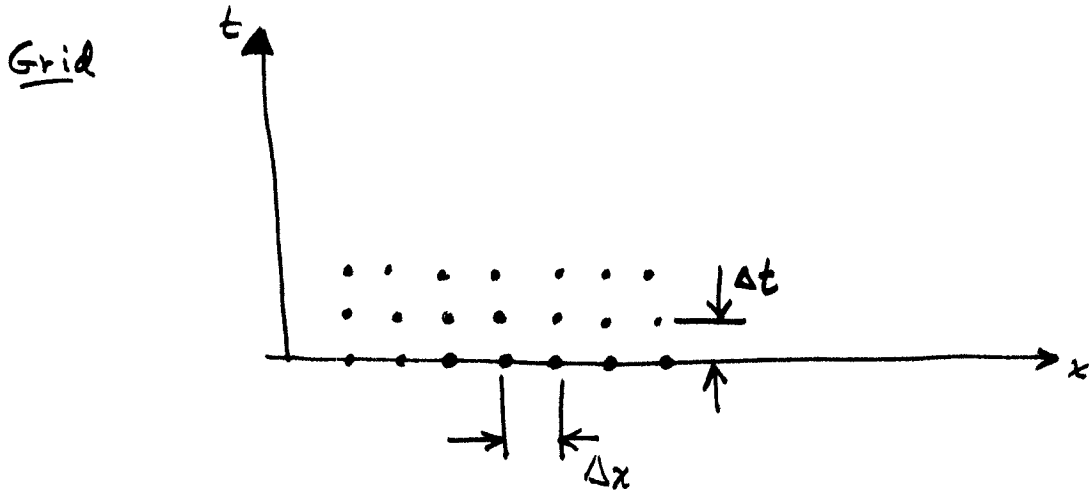


# Numerical Solution of Wave Equation

4.3.1

[Ames 92]  
[Smith 85]

$$\frac{\partial^2 y}{\partial t^2} = c^2 \frac{\partial^2 y}{\partial x^2}$$

Use central difference approximation to  $\frac{\partial^2}{\partial^2}$

$$y(x, t) = y(m \Delta x, n \Delta t) = y_{m, n}$$

$$\frac{y_{m, n+1} - 2y_{m, n} + y_{m, n-1}}{(\Delta t)^2} = c^2 \frac{y_{m+1, n} - 2y_{m, n} + y_{m-1, n}}{(\Delta x)^2}$$

future  
value

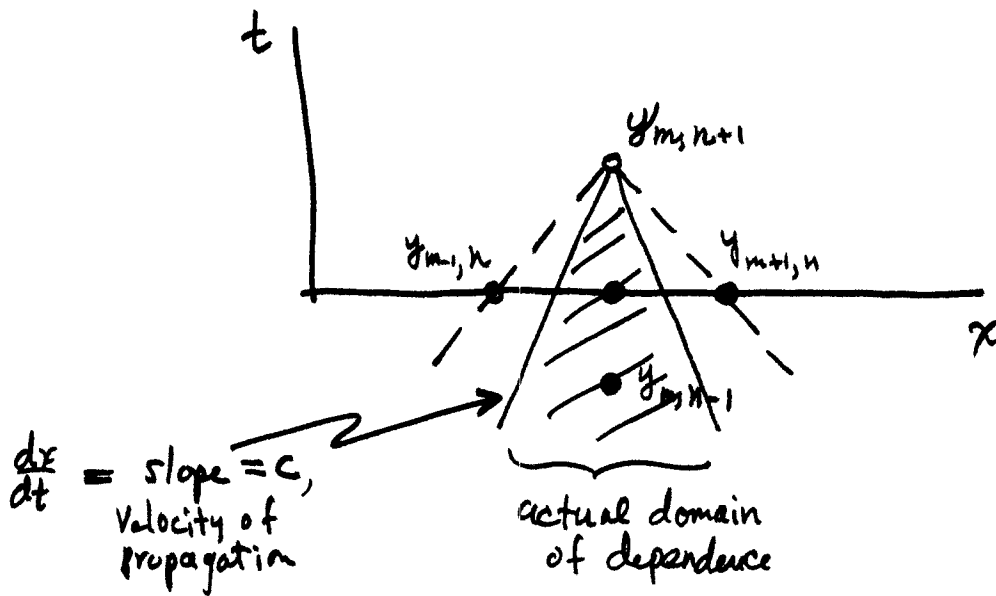
$$+ O(\Delta t)^2 \\ + O(\Delta x)^2$$

$$y_{m, n+1} = c^2 \left( \frac{\Delta t}{\Delta x} \right)^2 [y_{m+1, n} - 2y_{m, n} + y_{m-1, n}] + 2y_{m, n} - y_{m, n-1}$$

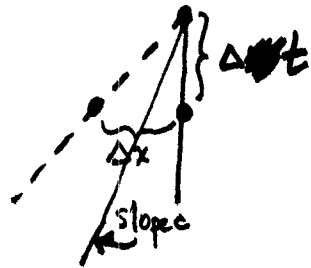
Let  $\alpha^2 = c^2 \left( \frac{\Delta t}{\Delta x} \right)^2$ , dimensionless parameter

$$y_{m, n+1} = 2(1 - \alpha^2)y_{m, n} + \alpha^2 y_{m+1, n} + \alpha^2 y_{m-1, n} - y_{m, n-1}$$

## Intuitive stability analysis:



For the numerical method to capture the correct behavior, the actual domain of dependence must lie inside the numerical domain.



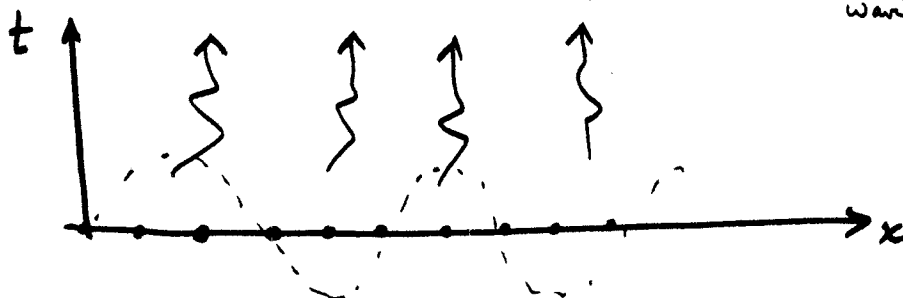
$\therefore$  it is necessary that

$$\frac{\Delta x}{\Delta t} \geq c$$

$$\boxed{\frac{c \cdot \Delta t}{\Delta x} = \lambda \leq 1}$$

# Von Neumann Stability Analysis

[Smith 85, Ex. 2.12, p. 70]  
for explicit scheme for wave eqn.



- idea:
- assume a sinusoidal component at  $t = 0$
  - study propagation in  $t$

Use complex exponential representation

$$y_{m,0} = e^{j\lambda m \Delta x}$$

must be stable  
for any  $\lambda$ .

Guess propagated waveform is of the form

$$y_{m,n} = e^{j\lambda m \Delta x} \cdot \xi^n$$

(can be justified by separation of variables)

$\xi$  is unknown, but we want  $|\xi| \leq 1$

"amplification"

this is actually only a necessary condition.  
(But it's often sufficient.)

Substitute this  $y_{mn}$  into difference eqn:

4.34

$$y_{m,n+1} = 2(1-\Delta^2)y_{mn} + \Delta^2 y_{m+1,n} + \Delta^2 y_{m-1,n} - y_{m,n-1}$$

$$\left\{ \begin{array}{l} y_{mn} = e^{j\lambda m \Delta x} \xi^n = Y \\ y_{m,n+1} = \xi \cdot Y \\ y_{m\pm 1,n} = e^{\pm j\lambda \Delta x} \cdot Y \\ y_{m,n-1} = \xi^{-1} \cdot Y \end{array} \right.$$

$$\xi \cdot Y = 2(1-\Delta^2)Y + \Delta^2(e^{j\lambda \Delta x} + e^{-j\lambda \Delta x}) \cdot Y - \xi^{-1}Y$$

$$\xi = 2(1-\Delta^2) + 2\Delta^2 \cos(\lambda \Delta x) - \xi^{-1}$$

$$\xi = 2 + 2\Delta^2(\underbrace{\cos \lambda \Delta x - 1}_{2\sin^2 \frac{\lambda \Delta x}{2}}) - \xi^{-1}$$

$$\xi^2 - 2\left[1 - 2\Delta^2 \sin^2 \frac{\lambda \Delta x}{2}\right]\xi + 1 = 0$$

Product of roots  $\xi_1 \cdot \xi_2 = 1$

not both 1, so roots should be complex:

$$b^2 - 4ac = 4\left(1 - 2\Delta^2 \sin^2 \frac{\lambda \Delta x}{2}\right)^2 - 4 \leq 0$$

$$\Rightarrow \left(1 - 2\Delta^2 \sin^2 \frac{\lambda \Delta x}{2}\right)^2 \leq 1$$

$$\Rightarrow \pm \left(1 - 2\Delta^2 \sin^2 \frac{\lambda \Delta x}{2}\right) \leq 1 \quad (+ \text{condition is trivially true})$$

$$\Rightarrow \Delta^2 \sin^2 \frac{\lambda \Delta x}{2} \leq 1$$

$$\Rightarrow \Delta^2 \leq 1/\sin^2 \left(\frac{\lambda \Delta x}{2}\right) \quad \underline{\text{all } \lambda!}$$

$$\Rightarrow \boxed{|\Delta^2| \leq 1} \Rightarrow \boxed{|\Delta| \leq 1} \quad (\text{also sufficient})$$

this wave equation approximation is consistent,

$$\frac{y_{m,n+1} - 2y_{m,n} + y_{m,n-1}}{k^2} = c^2 \frac{y_{m+1,n} - 2y_{m,n} + y_{m-1,n}}{h^2} + \underbrace{O(k^2) + O(k^2)}_{\substack{\downarrow \\ 0 \\ \text{as } k, h \rightarrow 0}}$$

Local truncation error

∴ when  $|a| \leq 1$  this stable & convergent → (by Lax's thm.)

Another example: the diffusion eqn. approximation  
(p. 4.1.11)

$$\frac{y_{i,j+1} - y_{i,j}}{k} = \frac{y_{i-1,j} - 2y_{i,j} + y_{i+1,j}}{h^2} + \underbrace{O(k) + O(k^2)}_{\substack{\rightarrow 0 \\ \Rightarrow \text{consistent}}}$$

[Smith 85, Ex. 2.11, p. 69]

von Neumann's method:

$$y_{i,j+1} = r y_{i-1,j} + (1-2r) y_{i,j} + r y_{i+1,j}$$

$$\xi \cdot Y = r (e^{j\lambda\Delta x} + e^{-j\lambda\Delta x}) \cdot Y + (1-2r) \cdot Y$$

$$\xi = 2r(\cos(\lambda\Delta x) - 1) + 1$$

$$|\xi| = |1 - 4r \sin^2 \frac{\lambda\Delta x}{2}| \leq 1$$

$$\Rightarrow r \leq \frac{1}{2 \sin^2 \frac{\lambda\Delta x}{2}} \quad \text{all } \lambda$$

$$\Rightarrow \boxed{r \leq \frac{1}{2}}$$

stable & convergent here

Example of Inconsistency [Smith 85, Ex 2.7, p. 42] 4.36  
[Amus 92, p. 71-2, 64]

Richardson in 1910 suggested using central difference approximation for  $\partial y / \partial t$  to approximate diffusion eqn.

$$\frac{\partial y}{\partial t} = \frac{y_{i,j+1} - y_{i,j-1}}{2\Delta} + O(\Delta^2) = \frac{y_{i+1,j} - 2y_{i,j} + y_{i-1,j}}{\Delta^2} + O(\Delta^2)$$

this turns out to be always unstable!

DuFort & Frankel in 1953 suggested replacing  $y_{ij}$  on RHS using  $\frac{1}{2} (y_{i,j+1} + y_{i,j-1}) \approx y_{ij}$

this results in a difference eqn. that is always stable.

---

Actually, this replacement introduces the term

$$\frac{2y_{ij} - (y_{i,j+1} + y_{i,j-1}))}{\Delta^2} = -\left(\frac{\Delta^2}{\Delta^2}\right) \frac{\partial^2 y}{\partial t^2} + O\left(\frac{\Delta^4}{\Delta^2}\right)$$

because  $\frac{2y_{ij} - (y_{i,j+1} + y_{i,j-1}))}{\Delta^2} = -\frac{\partial^2 y}{\partial t^2} + O(\Delta^2)$   
- p. 4.1.9

If  $\frac{\Delta}{\Delta} = \nu = \text{const.}$ , and  $\Delta \rightarrow 0$ , this approximation is consistent with the partial differential eqn.

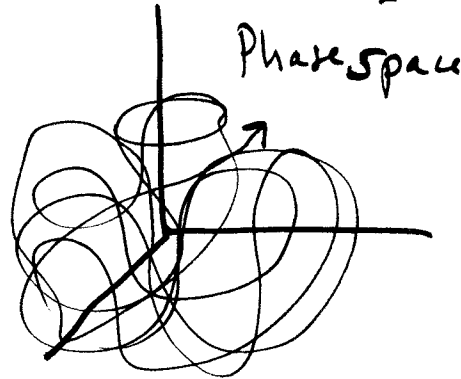
$$\frac{\partial y}{\partial t} = \frac{\partial^2 y}{\partial x^2} - \nu^2 \frac{\partial^2 y}{\partial t^2},$$

- not the original diffusion eqn.!

The Fermi-Pasta-Ulam Experiment (1955) [FP65]  
[GT96]

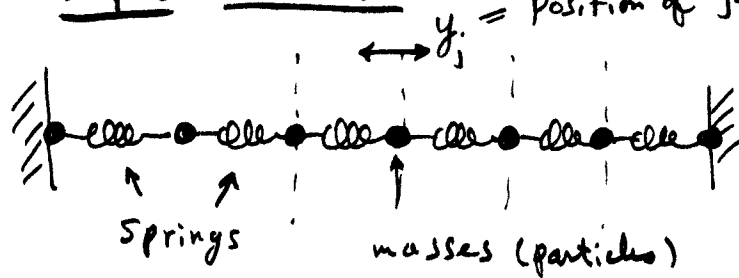
the expectation

"Ergodic"  $\rightarrow$  all regions traversed equally often if system is nonlinear.



this idea shattered... lead to solitons.

their model was coupled oscillators



$$\text{Force on particle } j = m \cdot a = m \frac{\partial^2 y_j}{\partial t^2} = -K(y_j - y_{j+1}) - K(y_j - y_{j-1})$$

restoring forces,  
K is spring constant

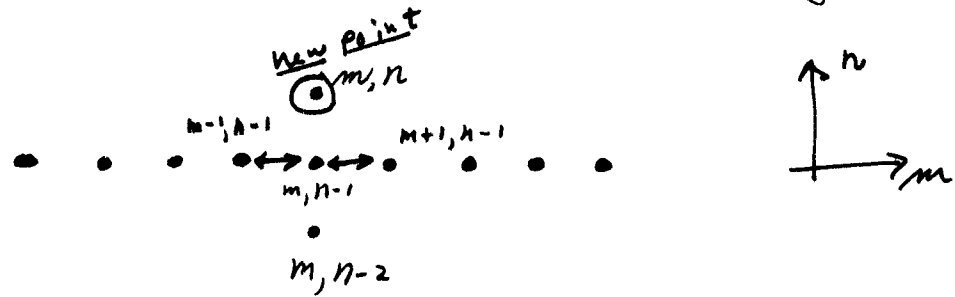
$$\frac{\partial^2 y_j}{\partial t^2} = -\frac{K}{m} [2y_j - y_{j-1} - y_{j+1}]$$

$$\frac{\partial^2 y_j}{\partial t^2} = \frac{K}{m} \underbrace{[y_{j+1} + y_{j-1} - 2y_j]}_{\approx \frac{\partial^2 y_j}{\partial x^2}}$$

approximates wave eqn.

to incorporate nonlinear coupling terms, FPU  
add forces dependant on square or cube of  
inter-particle distances.

We'll do the same in our solution of wave equation:

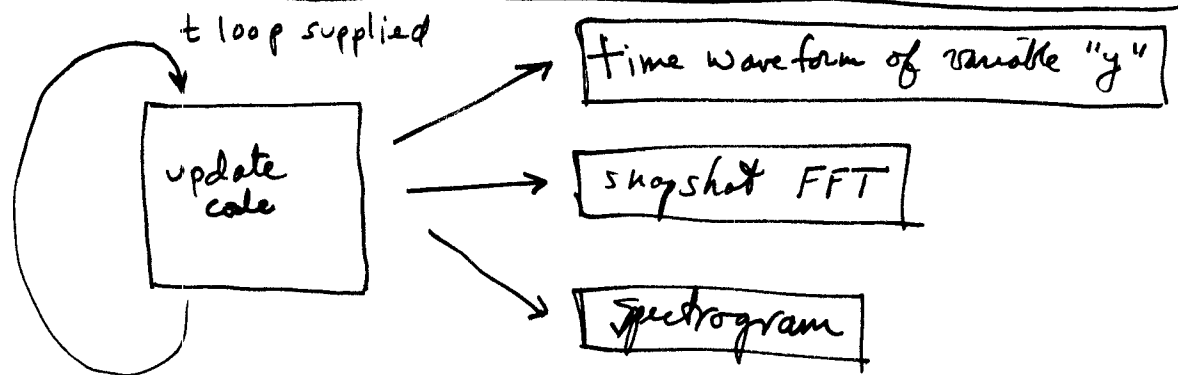


$$y_{m,n} = \underbrace{\quad\quad\quad}_{\text{linear part}} + \alpha \underbrace{\quad\quad\quad}_{\text{nonlinear part}}$$

Start with all energy in mode 0:



EIN





I was observing the motion of a boat which was rapidly drawn along a narrow channel by a pair of horses, when the boat suddenly stopped—not so the mass of water in the channel which it had put in motion; it accumulated round the prow of the vessel in a state of violent agitation, then suddenly leaving it behind, rolled forward with great velocity, assuming the form of a large solitary elevation, a rounded, smooth and well-defined heap of water, which continued its course along the channel apparently without change of form or diminution of speed. I followed it on horseback, and overtook it still rolling on at a rate of some eight or nine miles an hour, preserving its original figure some thirty feet long and a foot to a foot and a half in height. Its height gradually diminished, and after a chase of one or two miles I lost it in the windings of the channel. Such, in the month of August 1834, was my first chance interview with that singular and beautiful phenomenon . . . .

J. Scott-Russell, 1844  
in A.C. Scott et al. [SCM73]

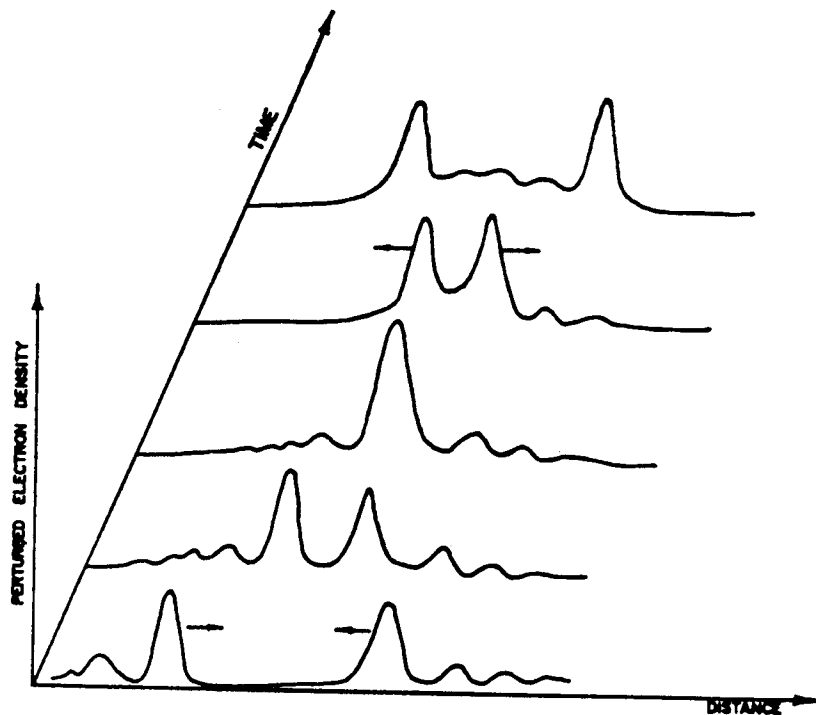


Fig. 4. Nondestructive collision of ion-acoustic plasma pulses.

Solitons

plasmas  
elastic rods  
pressure waves in liquid-gas bubble mixtures  
phonon packets in nonlinear crystals  
shallow water  
nonlinear optical fibers  
Josephson junction  
electrical lattices ... etc.

H. IZeki et al. in [SCM73]

# History of Soliton Experiment & Theory

4.3.10

1834 Scott-Russell on Roebuck, in canal

↓

1895 Korteweg & de Vries write differential equation for shallow water (KdV equ.)

↓

{ 1953 Seeger, Donth, & Kochendörfer }  
1962 Perring & Skyrme } observed nondestructive collisions

↓

1965 Zabusky & Kruskal Solitons in plasma

↓

1973 Ablowitz, Kaup, Newell, Segur (analytical) inverse scattering method

⋮

leads to current explosion of work in nonlinear systems.

FPU  
1955

## Linear systems

{ Laplace's Equ.  
Poisson's Equ.  
Diffusion Equ.  
Wave Equ.  
Schrödinger Equ.  
⋮

main feature is SUPERPOSITION

of  
Solutions

## Nonlinear systems

- Logistic, e.g.
- KdV
- many nonlinear variants of Schrödinger Equ.
- many saturating systems
- more realistic variants of oversimplified physical systems

Solitons

chaos

much more complex & interesting than linear eqns.



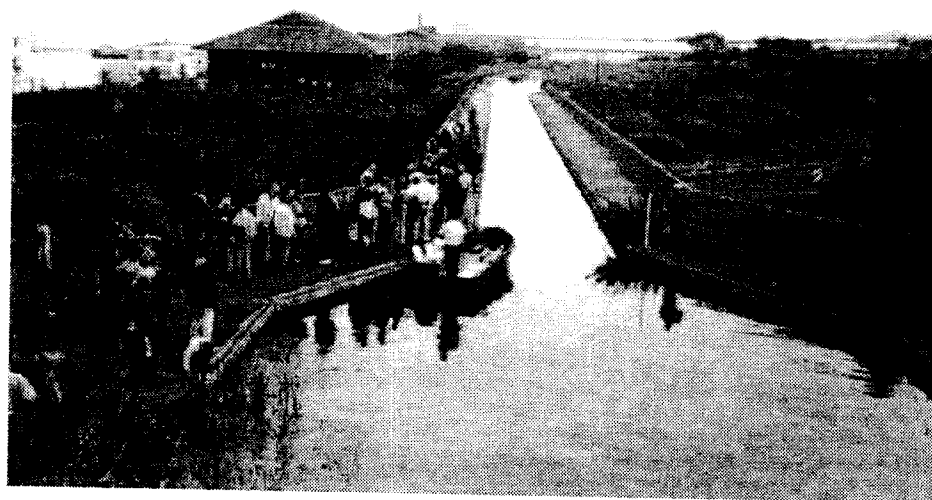
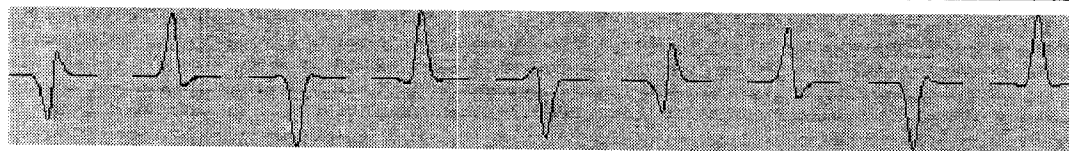
*Soliton on the Scott Russell Aqueduct on the Union Canal near Heriot-Watt University, 12 July 1995.*

Full Size Version

[Solitons Home Page](#)



*Dugald Duncan/Heriot-Watt University, Edinburgh/dugald@ma.hw.ac.uk*



The Scott Russell Aqueduct on the Union Canal near Heriot-Watt University, 12 July 1995.

For the technically minded, the aqueduct is 89.3 m long, 4.13m wide, and 1.52m deep.