

COS 318 Project 2

Non-Preemptive Scheduling

Precept 2

Agenda

- Questions from design review / emails
- Miscellaneous
- Grading criteria
- GDB on bochs (CJ Bell)

Blocking Semantics

- When a thread required a LOCKED lock, it gets blocked, not coming back to ready queue
- when a thread releases a lock, it unlocks the first waiting thread
- `lock_release()` does not imply `do_yield()`
- When a thread is unblocked, it is not executed until all unblocked tasks at the time have yielded

Example Code

Thread 1:

```
lock_init(&lock);  
lock_acquire(&lock);  
do_yield();  
lock_release(&lock);  
do_exit();
```

Thread 4:

```
lock_acquire(&lock);  
lock_release(&lock);  
do_exit();
```

Thread 2:

```
while(TRUE) {  
    do_yield();  
}
```

Thread 3:

```
do_yield();  
lock_acquire(&lock);  
lock_release(&lock);  
do_exit();
```


Example Code

Thread 1:

```
lock_init(&lock);  
lock_acquire(&lock);  
do_yield();  
lock_release(&lock);  
do_exit();
```

Thread 2:

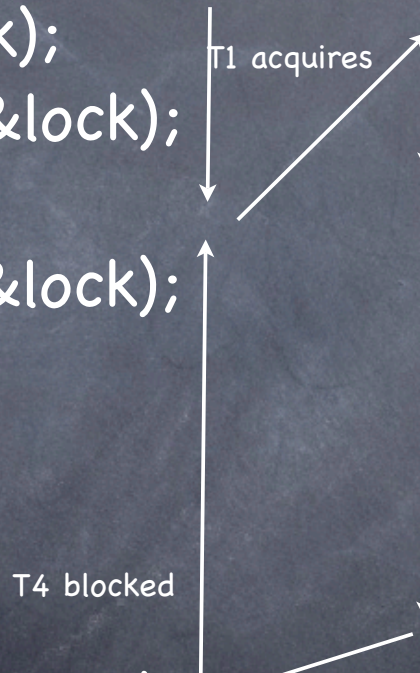
```
while(TRUE) {  
    do_yield();  
}
```

Thread 3:

```
do_yield();  
lock_acquire(&lock);  
lock_release(&lock);  
do_exit();
```

Thread 4:

```
lock_acquire(&lock);  
lock_release(&lock);  
do_exit();
```



Example Code

Thread 1:

```
lock_init(&lock);  
lock_acquire(&lock);  
do_yield();  
lock_release(&lock);  
do_exit();
```

Thread 2:

```
while(TRUE) {  
    do_yield();  
}
```

Thread 4:

```
lock_acquire(&lock);  
lock_release(&lock);  
do_exit();
```

Thread 3:

```
do_yield();  
lock_acquire(&lock);  
lock_release(&lock);  
do_exit();
```

T1 releases
unblocked T4

T3 blocked

T4 releases
unblocked T3



Lock Implementation

- Simple lock implementation: LOCKED, UNLOCKED
- Do not have to handle deadlock
- Think what you should do when:
 - two threads are blocked waiting for the same lock? Follow FIFO rule
 - Some other process tries to acquire the lock before the unblocked process starts running

PCB

- PCBs are statically allocated in memory for this project
- No recycling of memory space of any kind
 - stack, pcb, locks.....
- You may add whatever you feel necessary
 - start address of a program
 - kernel thread or user process

Context Switching

- `kernel_entry()`
 - Used to switch between user process and the kernel for system calls
 - saves and restores user registers
- `scheduler_entry()`
 - used to switch between kernel threads and user processes that are in kernel
 - saves and restores system registers
- `yield()` system call (in `syslib`)
 - goes through `kernel_entry()` to switch to kernel mode
 - goes through `scheduler_entry()` to switch to another process/thread

Example

- Process P → Thread T
 - yield() system call → kernel_entry
 - save registers, load kernel stack (working on kernel stack now)
 - do_yield()
 - load user stack, restore user registers
 - do_yield()
 - enqueue P to ready queue
 - scheduler_entry()
 - save P's kernel registers
 - scheduler()
 - load T's kernel registers
 - ret

First time to switch to a task

- There is no return address on stack
- How do you find where to return to?
 - ask scheduler to jump to the entry point of the program if it is the first time to run
 - what else?

Inline Assembly

- General format:

```
__asm__(  
    "instruction"  
    "instruction"  
    ...  
    "instruction"  
    : "=flags"  
    : "=flags"  
    : "=flags"  
);
```

- volatile : `__asm__ volatile`
- flags: refer to the resource page provided on project website

Grading Criteria

- Total: 10 points + 1 extra credit point
- Kernel threads and scheduling: 3 points
- Processes and system calls: 3 points
- Mutual exclusion: 2 points
- Timing a context switch: 1 point
- Coding style, comments, and README: 1 point
- If your program runs on bochs, but does not run on fishbowl, 1 point penalty at most

GDB for bochs

👁 Thanks, CJ