

Reductions

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Desiderata

Desiderata. Classify **problems** according to their computational requirements.

Desiderata'. Suppose we could (couldn't) solve problem X efficiently. What else could (couldn't) we solve efficiently?



Give me a lever long enough and a fulcrum on which to place it, and I shall move the world. -Archimedes

Desiderata

Desiderata. Classify **problems** according to their computational requirements.

Frustrating news. Huge number of fundamental problems have defied classification for decades.

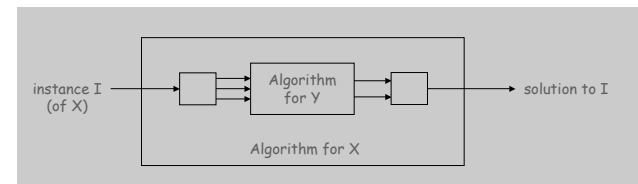
Reduction

Def. Problem X **reduces to** problem Y if given a subroutine for Y, can solve X.

↖ don't confuse with reduces from

- Cost of solving X = cost of solving Y + cost of reduction.

Ex. X = Euclidean MST, Y = Voronoi.



Reduction

Def. Problem X **reduces to** problem Y if given a subroutine for Y, can solve X.

← don't confuse with reduces from

- Cost of solving X = cost of solving Y + cost of reduction.

Consequences.

- Classify problems: establish relative difficulty between two problems.
- Design algorithms: given algorithm for Y, can also solve X.
- Establish intractability: if X is hard, then so is Y.

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Linear Time Reductions

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Linear Time Reductions

Def. Problem X **linear reduces** to problem Y if X can be solved with:

- Linear number of standard computational steps.
- One call to subroutine for Y.
- Notation: $X \leq_L Y$.

Some familiar examples.

- Median \leq_L sorting.
- Element distinctness \leq_L sorting.
- Closest pair \leq_L Voronoi.
- Euclidean MST \leq_L Voronoi.
- Arbitrage \leq_L Negative cycle detection.
- Linear programming \leq_L Linear programming in std form.

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Linear Time Reductions

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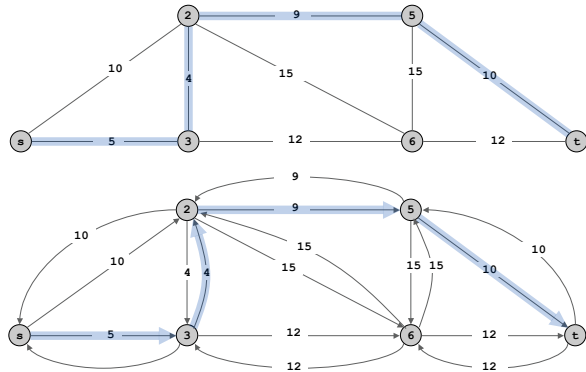
- Design algorithms: given algorithm for Y, can also solve X.
- Establish intractability: if X is hard, then so is Y.
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Shortest Paths on Graphs and Digraphs

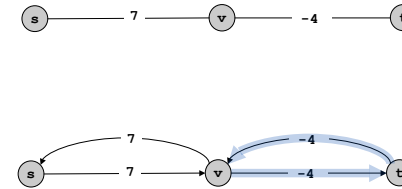
Claim. Undirected shortest path (with nonnegative weights) linearly reduces to directed shortest path.

Pf. Replace each undirected edge by two directed edges.



Shortest Paths with Negative Weights

Caveat. Reduction invalid in networks with negative weights (even if no negative cycles).



Remark. Can still solve shortest path problem in undirected graphs if no negative cycles, but need more sophisticated techniques.

reduce to weighted non-bipartite matching (!)

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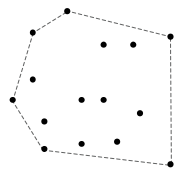
Convex Hull and Sorting

Sorting. Given N distinct integers, rearrange them in ascending order.

Convex hull. Given N points in the plane, identify the extreme points of the convex hull (in counter-clockwise order).

Claim. Convex hull linearly reduces to sorting.

Pf. Graham scan algorithm.



convex hull

1251432
2861534
3988818
4190745
13546464
89885444

sorting

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Linear Time Reductions

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Sorting and Convex Hull: Lower Bound

Theorem. In quadratic decision tree model of computation, sorting N integers requires $\Omega(N \log N)$ steps.

allow tests of the form $x_i < x_j$ or $(x_j - x_i)(y_k - y_j) - (y_j - y_i)(x_k - x_i) < 0$

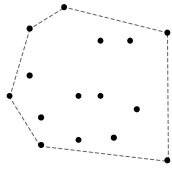
see next slide

Claim. Sorting linear reduces to convex hull.

Corollary. Any ccw-based convex hull algorithm requires $\Omega(N \log N)$ steps.

1251432
2861534
3988818
4190745
13546464
89885444

sorting



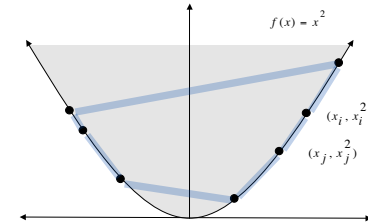
convex hull

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Sorting Linear Reduces to Convex Hull

Sorting instance. x_1, x_2, \dots, x_N

Convex hull instance. $(x_1, x_1^2), (x_2, x_2^2), \dots, (x_N, x_N^2)$



Observation. Region $\{x : x^2 \geq x\}$ is convex \Rightarrow all points are on hull.

Consequence. Starting at point with most negative x , counter-clockwise order of hull points yields items in ascending order.

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3-SUM Reduces to 3-COLLINEAR

3-SUM. Given N distinct integers, are there three that sum to 0?

3-COLLINEAR. Given N distinct points in the plane, are there 3 that all lie on the same line?

recall Assignment 2

Claim. 3-SUM \leq_L 3-COLLINEAR.

see next two slides

Conjecture. Any algorithm for 3-SUM requires $\Omega(N^2)$ time.

Corollary. Sub-quadratic algorithm for 3-COLLINEAR unlikely.

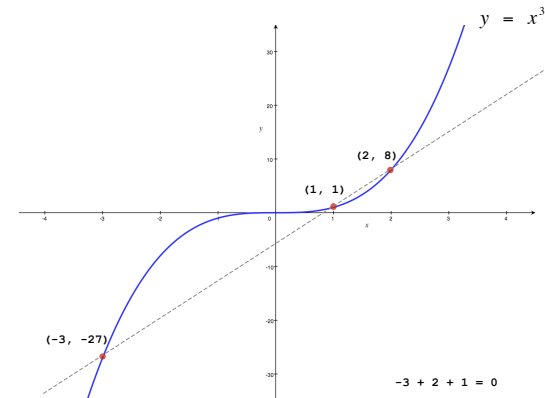
your $N^2 \log N$ algorithm from Assignment 2 was pretty good

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3-SUM Reduces to 3-COLLINEAR

Claim. 3-SUM \leq_L 3-COLLINEAR.

- 3-SUM instance: x_1, x_2, \dots, x_N
- 3-COLLINEAR instance: $(x_1, x_1^3), (x_2, x_2^3), \dots, (x_N, x_N^3)$



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3-SUM Reduces to 3-COLLINEAR

Lemma. If a , b , and c are distinct then $a + b + c = 0$ if and only if (a, a^3) , (b, b^3) , (c, c^3) are collinear.

Pf. Three points (a, a^3) , (b, b^3) , (c, c^3) are collinear iff:

$$\begin{aligned} \frac{a^3 - b^3}{a - b} = \frac{b^3 - c^3}{b - c} &\Leftrightarrow \frac{(a-b)(a^2 + ab + b^2)}{a - b} = \frac{(b-c)(b^2 + bc + c^2)}{b - c} \\ &\Leftrightarrow c^2 + bc - a^2 - ab = 0 \\ &\Leftrightarrow (c - a)(c + a + b) = 0 \\ &\Leftrightarrow c = a \quad \text{or} \quad a + b + c = 0 \end{aligned}$$

denominators are nonzero
if $a, b,$ and c are distinct

not distinct

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Linear Time Reductions

Def. Problem X **linearly reduces** to problem Y if X can be solved with:

- Linear number of standard computational steps.
- One call to subroutine for Y .

Consequences.

- Design algorithms: given algorithm for Y , can also solve X .
- Establish intractability: if X is hard, then so is Y .
- Classify problems: establish relative difficulty between two problems.

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Primality and Compositeness

PRIME. Given an integer x (represented in binary), is x prime?

COMPOSITE. Given an integer x , does x have a nontrivial factor?

Claim. $\text{PRIME} \leq_L \text{COMPOSITE}$.

```
public static boolean isPrime(BigInteger x) {
    if (isComposite(x)) return false;
    else return true;
}
```

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Primality and Compositeness

PRIME. Given an integer x (represented in binary), is x prime?

COMPOSITE. Given an integer x , does x have a nontrivial factor?

Claim. $\text{COMPOSITE} \leq_L \text{PRIME}$.

```
public static boolean isComposite(BigInteger x) {
    if (isPrime(x)) return false;
    else return true;
}
```

Conclusion. COMPOSITE and PRIME have same complexity.

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Reduction Gone Wrong

Caveat.

- System designer specs the interfaces for project.
- One programmer might implement `isComposite()` using `isPrime()`.
- Other programmer might implement `isPrime()` using `isComposite()`.
- Be careful to avoid infinite reduction loops in practice.

```
public static boolean isComposite(BigInteger x) {  
    if (isPrime(x)) return false;  
    else return true;  
}
```

```
public static boolean isPrime(BigInteger x) {  
    if (isComposite(x)) return false;  
    else return true;  
}
```

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Polynomial-Time Reductions

Poly-Time Reduction

Def. Problem X **polynomially reduces to** problem Y if arbitrary instances of problem X can be solved using:

- Polynomial number of standard computational steps, plus
- One call to subroutine for Y.

Notation. $X \leq_p Y$.

Ex. Assignment problem \leq_p LP.

Ex. 3-SAT \leq_p 3-COLOR.

Ex. Any linear reduction.

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Poly-Time Reductions

Goal. Classify and separate problems according to relative difficulty.

- Those that can be solved in polynomial time.
- Those that (probably) require exponential time.

Establish tractability. If $X \leq_p Y$ and Y can be solved in poly-time, then X can be solved in poly-time.

Establish intractability. If $Y \leq_p X$ and Y cannot be solved in poly-time, then X cannot be solved in poly-time.

Transitivity. If $X \leq_p Y$ and $Y \leq_p Z$ then $X \leq_p Z$.

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Assignment Problem

Assignment problem. Assign n jobs to n machines to minimize total cost, where c_{ij} = cost of assigning job j to machine i .

	1'	2'	3'	4'	5'
1	3	8	9	15	10
2	4	10	7	16	14
3	9	13	11	19	10
4	8	13	12	20	13
5	1	7	5	11	9

cost = 3 + 10 + 11 + 20 + 9 = 53

	1'	2'	3'	4'	5'
1	3	8	9	15	10
2	4	10	7	16	14
3	9	13	11	19	10
4	8	13	12	20	13
5	1	7	5	11	9

cost = 8 + 7 + 20 + 8 + 11 = 44

Applications. Match jobs to machines, match personnel to tasks, match Princeton students to writing seminars.

Assignment Problem Reduces to Linear Programming

LP formulation. $x_{ij} = 1$ if job j assigned to machine i .

$$\begin{aligned} \min \quad & \sum_{1 \leq i \leq n} \sum_{1 \leq j \leq n} c_{ij} x_{ij} \\ \text{s. t.} \quad & \sum_{1 \leq j \leq n} x_{ij} = 1 \quad 1 \leq i \leq n \\ & \sum_{1 \leq i \leq n} x_{ij} = 1 \quad 1 \leq j \leq n \\ & x_{ij} \geq 0 \quad 1 \leq i, j \leq n \end{aligned}$$

Theorem. [Birkhoff 1946, von Neumann 1953] All extreme points of the above polytope are {0-1}-valued.

Corollary. Assignment problem reduces to LP; can solve in poly-time.

we assume LP returns an extreme point solution

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3-Satisfiability

Literal: A Boolean variable or its negation.

$$x_i \text{ or } \overline{x_i}$$

Clause. A disjunction of 3 distinct literals.

$$C_j = x_1 \vee \overline{x_2} \vee x_3$$

Conjunctive normal form. A propositional formula Φ that is the conjunction of clauses.

$$\Phi = C_1 \wedge C_2 \wedge C_3 \wedge C_4$$

3-SAT. Given a CNF formula Φ consisting of k clauses over n literals, does it have a satisfying truth assignment?

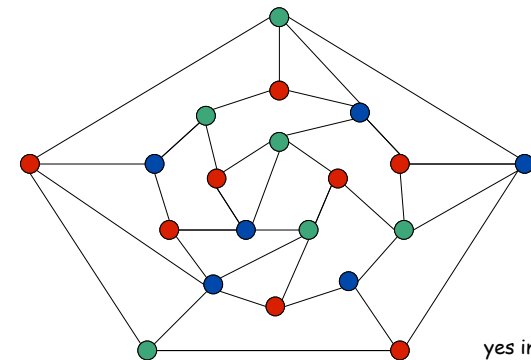
$$(\overline{x_1} \vee x_2 \vee x_3) \wedge (x_1 \vee \overline{x_2} \vee x_3) \wedge (\overline{x_1} \vee \overline{x_2} \vee \overline{x_3}) \wedge (\overline{x_1} \vee \overline{x_2} \vee x_4) \wedge (\overline{x_2} \vee x_3 \vee x_4)$$

Solution: $x_1 = \text{true}$, $x_2 = \text{true}$, $x_3 = \text{false}$, $x_4 = \text{true}$

Key application. Electronic design automation (EDA).

Graph 3-Colorability

3-COLOR. Given a graph, is there a way to color the vertices red, green, and blue so that no adjacent vertices have the same color?



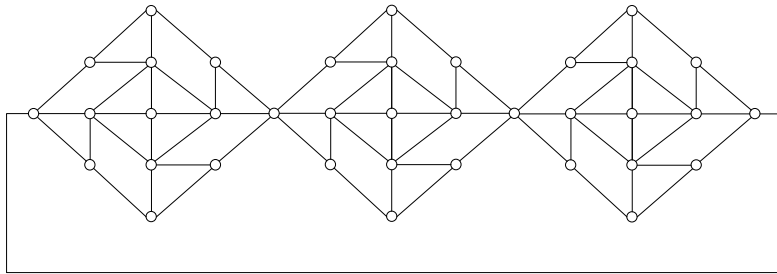
yes instance

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Graph 3-Colorability

3-COLOR. Given a graph, is there a way to color the vertices red, green, and blue so that no adjacent vertices have the same color?



Graph 3-Colorability

Claim. $3\text{-SAT} \leq_p 3\text{-COLOR}$.

Pf. Given 3-SAT instance Φ , we construct an instance of 3-COLOR that is 3-colorable iff Φ is satisfiable.

Construction.

- i. Create one vertex for each literal.
- ii. Create 3 new vertices T, F, and B; connect them in a triangle, and connect each literal to B.
- iii. Connect each literal to its negation.
- iv. For each clause, attach a gadget of 6 vertices and 13 edges.

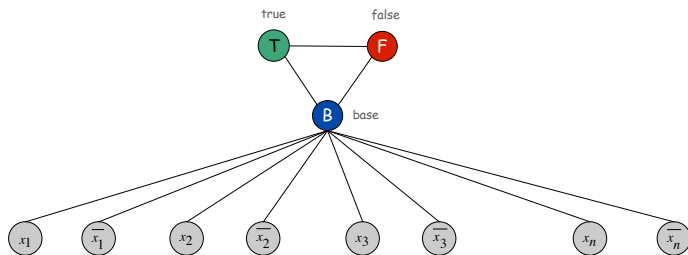
to be described next

Graph 3-Colorability

Claim. Graph is 3-colorable iff Φ is satisfiable.

Pf. \Rightarrow Suppose graph is 3-colorable.

- Consider assignment that sets all T literals to true.
- (ii) ensures each literal is T or F.

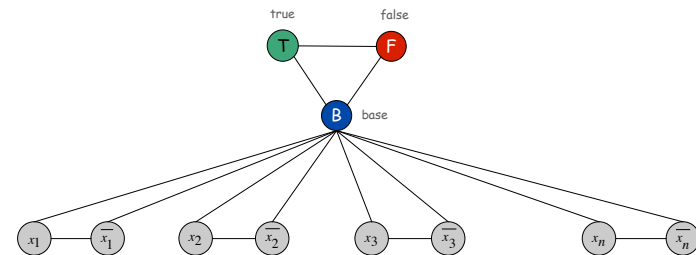


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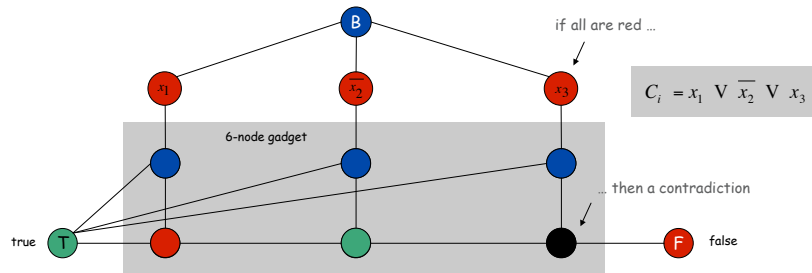
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- Consider assignment that sets all T literals to true.
- (ii) ensures each literal is T or F.
- (iii) ensures a literal and its negation are opposites.
- (iv) ensures at least one literal in each clause is T.

(if not, then G wouldn't be 3-colorable, a contradiction)



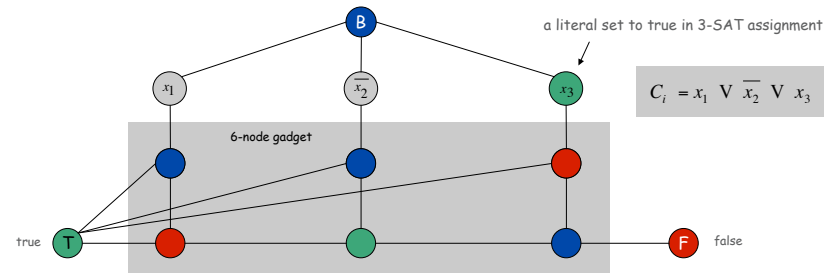
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Graph 3-Colorability

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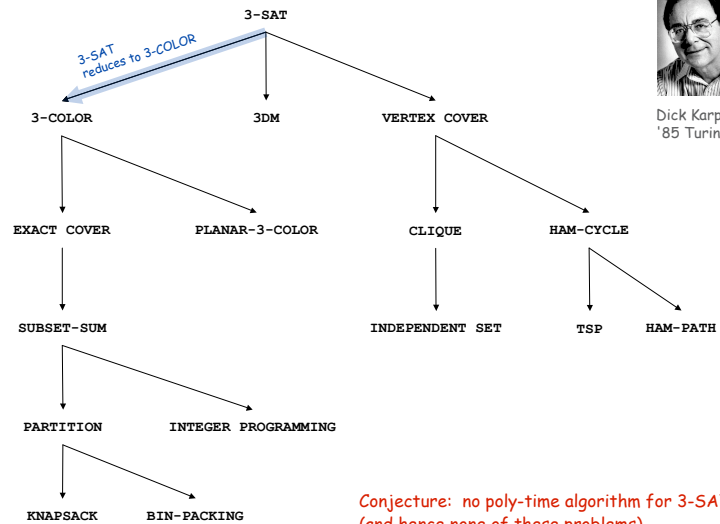
Pf. \Leftarrow Suppose 3-SAT formula Φ is satisfiable.

- Color all true literals T and false literals F.
- Color vertex below green vertex F, and vertex below that B.
- Color remaining middle row vertices B.
- Color remaining bottom vertices T or F as forced.



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More Poly-Time Reductions

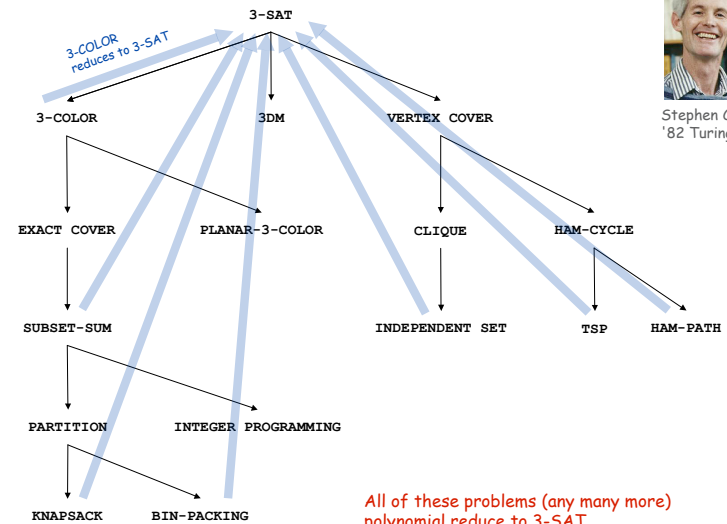


Dick Karp
'85 Turing award

Conjecture: no poly-time algorithm for 3-SAT.
(and hence none of these problems)

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Cook's Theorem

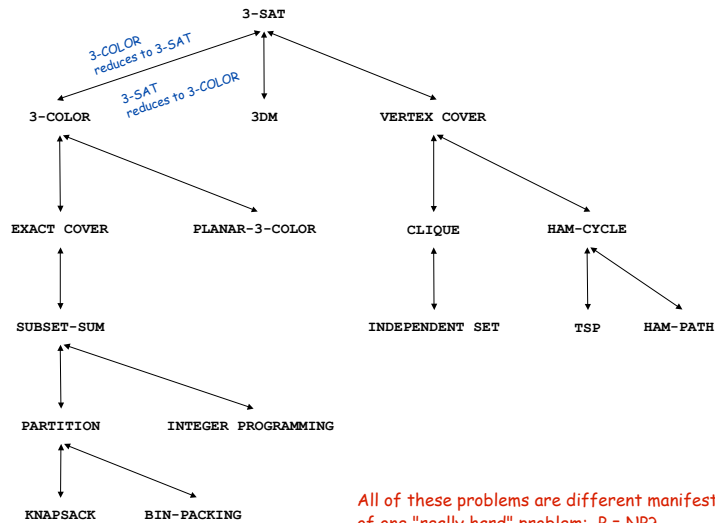


Stephen Cook
'82 Turing award

All of these problems (any many more)
polynomial reduce to 3-SAT.

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Cook + Karp



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Summary

Reductions are important in theory to:

- Establish tractability.
- Establish intractability.
- Classify problems according to their computational requirements.

Reductions are important in practice to:

- Design algorithms.
- Design reusable software modules.
 - stack, queue, sorting, priority queue, symbol table, set, graph
 - shortest path, regular expressions, linear programming
- Determine difficulty of your problem and choose the right tool.
 - use exact algorithm for tractable problems
 - use heuristics for intractable problems

e.g., bin packing

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