Balanced Trees

Splay trees

2-3-4 trees

Red-black trees

B-trees

Reference: Chapter 13, Algorithms in Java, 3rd Edition, Robert Sedgewick.

Princeton University · COS 226 · Algorithms and Data Structures · Spring 2004 · Kevin Wayne · http://www.Princeton.EDU/~cos226

Splay Trees

Splay trees = self-adjusting BST.

- . Tree automatically reorganizes itself after each op.
- After inserting x or searching for x, rotate x up to root using double rotations.
- Tree remains "balanced" without explicitly storing any balance information.

Amortized guarantee: any sequence of N ops takes O(N log N) time.

- . Height of tree can be N.
- Individual op can take linear time.

Symbol Table Review

Symbol table: key-value pair abstraction.

- Insert a value with specified key.
- Search for value given key.
- Delete value with given key.

Randomized BST.

- . log N time per op (unless you get ridiculously unlucky).
- . Store subtree count in each node.
- Generate random numbers for each insert/delete op.

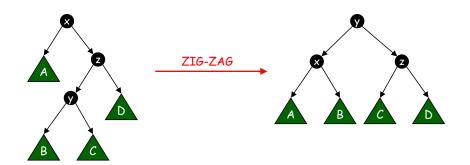
This lecture.

- . Splay trees.
- . 2-3-4 trees.
- Red-black trees.
- B-trees.

Splay Trees

Splay.

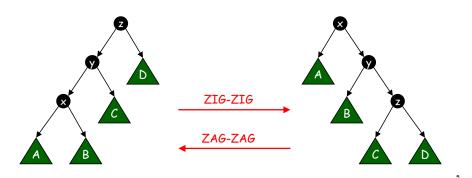
- Check two links above current node.
- ⇒ ZIG-ZAG: if orientations differ, same as root insertion.
 - ZIG-ZIG: if orientations match, do top rotation first.



Splay Trees

Splay.

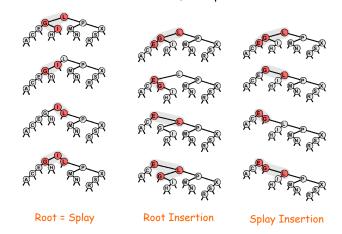
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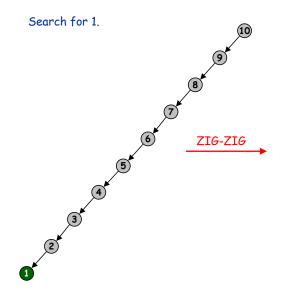
Splay Trees

Splay.

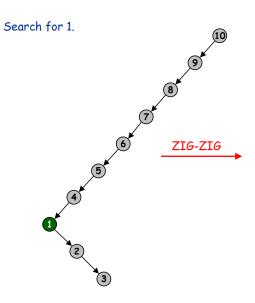
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Splay Example



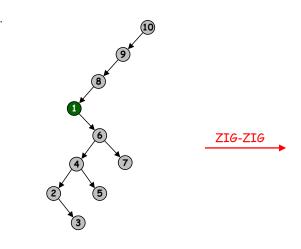
Splay Example



Splay Example Search for 1. Tigorian Splay Example Splay Example Tigorian Splay Example Tigorian Splay Example

Splay Example

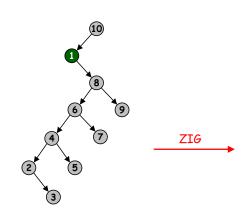
Search for 1.



9

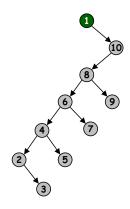
Splay Example

Search for 1.



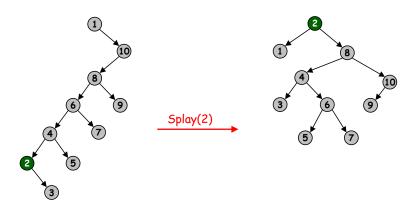
Splay Example

Search for 1.



Splay Example

Search for 2.

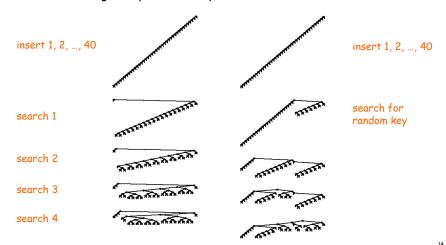


13

Splay Trees

Intuition.

- Splay rotations halve search path.
- Reduces length of path for many other nodes in tree.



Symbol Table: Implementations Cost Summary

	Worst Case			Average Case			
Implementation	Search	Insert	Delete	Search	Insert	Delete	
Sorted array	log N	Ν	Ν	log N	Ν	N	
Unsorted list	N	1	1	N	1	1	
Hashing	N	1	Ν	1*	1*	1*	
BST	N	Ν	Ν	log N	log N	sqrt(N) †	
Randomized BST	log N ‡	log N ‡	log N ‡	log N	log N	log N	
Splay	log N [§]						

- * assumes we know location of node to be deleted
- † if delete allowed, insert/search become sqrt(N)
- † probabilistic guarantee
- § amortized guarantee

Splay: sequence of any N ops in O(N log N) time.

Ahead: Can we do all ops in log N time guaranteed?

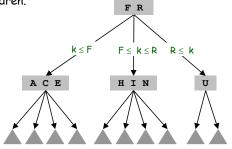
2-3-4 Trees

2-3-4 tree.

- . Scheme to keep tree balanced.
- Generalize node to allow multiple keys.

Allow 1, 2, or 3 keys per node.

- . 2-node: one key, two children.
- . 3-node: two keys, three children.
- 4-node: three keys, four children.



2-3-4 Trees: Search and Insert

SEARCH.

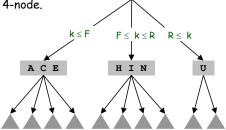
- Compare search key against keys in node.
- Find interval containing search key.
- Follow associated link (recursively).

INSERT.

• Search to bottom for key.

2-node at bottom: convert to 3-node.3-node at bottom: convert to 4-node.

. 4-node at bottom: ??



17

2-3-4 Trees: Splitting Four Nodes

Transform tree on the way DOWN.

• Ensure that last node is not a 4-node.

Local transformation to split 4-nodes:









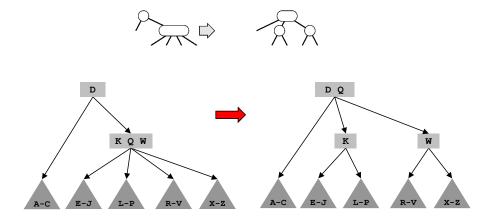
Invariant: current node is not a 4-node.

- One of two above transformations must apply at next node.
- Insertion at bottom is easy since it's not a 4-node.

18

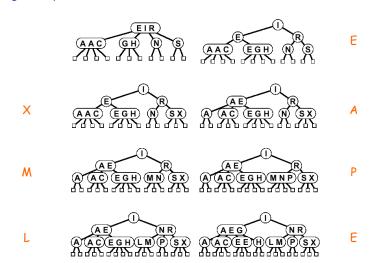
2-3-4 Trees: Splitting a Four Node

Splitting a four node: move middle key up.



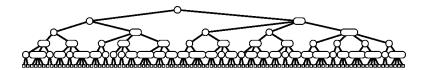
2-3-4 Trees

Tree grows up from the bottom.



Balance in 2-3-4 Trees

All paths from top to bottom have exactly the same length.



Tree height.

• Worst case: Ig N all 2-nodes

• Best case: $log_4 N = 1/2 lg N$ all 4-nodes

. Between 10 and 20 for a million nodes.

. Between 15 and 30 for a billion nodes.

Comparison within nodes not accounted for.

2-3-4 Trees: Implementation?

Direct implementation complicated because of:

- Maintaining multiple node types.
- Implementation of getChild.
- . Large number of cases for split.

```
private Node insert(Node h, String key, Object value) {
   Node x = h;
   while (x != null) {
        x = x.getChild(key);
        if (x.is4Node()) x.split();
   }
   if (x.is2Node()) x.make3Node(key, value);
   else if (x.is3Node()) x.make4Node(key, value);
}
```

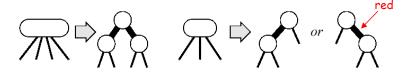
Fantasy Code

21

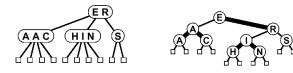
Red-Black Trees

Represent 2-3-4 trees as binary trees.

. Use "internal" edges for 3- and 4- nodes.



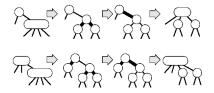
• Correspondence between 2-3-4 trees and red-black trees.



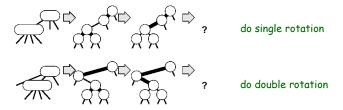
Not 1-1 because 3-nodes swing either way.

Splitting Nodes in Red-Black Trees

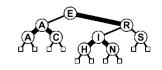
Two cases are easy: switch colors.



Two cases require rotations.

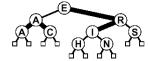




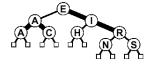


inserting G

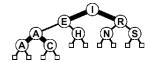
change colors



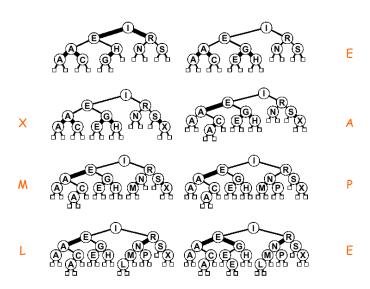
right rotate R \rightarrow



left rotate $E \rightarrow$



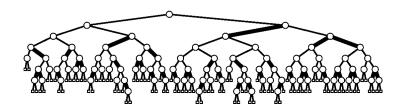
Red-Black Tree Construction



25

Balance in Red-Black Trees

Length of longest path is at most twice the length of shortest path.



Tree height.

. Worst case: 2 lg N.

Comparison within nodes ARE counted.

Symbol Table: Implementations Cost Summary

	Worst Case			Average Case			
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Sorted array	log N	N	N	log N	Ν	N	
Unsorted list	Ν	1	1	N	1	1	
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BST	Ν	N	N	log N	log N	sqrt(N) †	
Randomized BST	log N ‡	log N ‡	log N ‡	log N	log N	log N	
Splay	log N [§]	log N [§]	log N [§]	log N [§]	log N §	log N [§]	
Red-Black	log N	log N	log N	log N	log N	log N	

^{*} assumes hash map is random for all keys † if delete allowed, insert/search become sqrt(N) ‡ probabilistic guarantee § amortized guarantee

Red-Black Trees in Practice

Red-black trees vs. splay trees.

- Fewer rotations than splay trees.
- One extra bit per node for color. \leftarrow possible to eliminate

Red-black trees vs. hashing.

- Hashing code is simpler and usually faster.
- . Arithmetic to compute hash vs. comparison.
- Hashing performance guarantee is weaker.
- . BSTs have more flexibility and can support wider range of ops.

Red-black trees are widely used as system symbol tables.

- Java: TreeMap, TreeSet.
- C++ STL: map, multimap, multiset.

29

31

B-Trees

B-Tree generalize 2-3-4 trees by allowing up to M links per node.

. Split full nodes on the way down.

Main application: file systems.

- Reading a page into memory from disk is expensive.
- . Accessing info on a page in memory is free.
- Goal: minimize # page accesses.
- Node size M = page size.

Space-time tradeoff.

- M large ⇒ only a few levels in tree.
- M small ⇒ less wasted space.
- Typical M = 1000, N < 1 trillion.

Bottom line: number of PAGE accesses is log_MN per op.

. 3 or 4 in practice!

Symbol Table: Java Libraries

Java has built-in library for red-black tree symbol table.

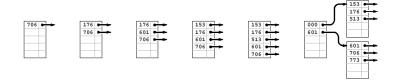
• TreeMap = red-black tree implementation.

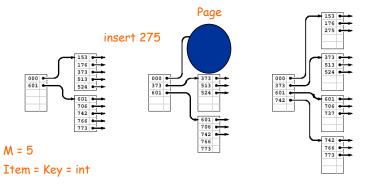
```
import java.util.TreeMap;
public class TreeMapDemo {
   public static void main(String[] args) {
      TreeMap st = new TreeMap();
      st.put("www.cs.princeton.edu", "128.112.136.11");
      st.put("www.princeton.edu", "128.112.128.15");
      st.put("www.simpsons.com", "209.052.165.60");
      System.out.println(st.get("www.cs.princeton.edu"));
   }
}
```

Duplicate policy.

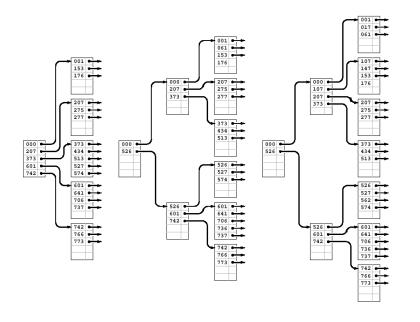
- Java TreeMap forbids two elements with the same key.
- . Sedgewick implementations allows duplicate keys.

B-Tree Example





B-Tree Example (cont)



Symbol Table: Implementations Cost Summary

	Worst Case			Average Case		
Implementation	Search	Insert	Delete	Search	Insert	Delete
Sorted array	log N	N	N	log N	N/2	N/2
Unsorted list	Ν	1	1	N	1	1
Hashing	N	1	N	1*	1*	1*
BST	Ν	N	N	log N	log N	sqrt(N) †
Randomized BST	log N ‡	log N ‡	log N ‡	log N	log N	log N
Splay	log N [§]	log N §	log N [§]	log N [§]	log N §	log N §
Red-Black	log N	log N	log N	log N	log N	log N
B-Tree	1	1	1	1	1	1
page accesses						

B-Tree: Number of PAGE accesses is $log_M N$ per op.

B-Tree in the Wild

File systems.

- Window HPFS (high performance file system).
- Mac HFS (hierarchical file system).
- Linux: ReiserFS, XFS, Ext3FS, JFS. ← journaling

Databases.

- Most common index type in modern databases.
- ORACLE, DB2, INGRES, SQL, PostgreSQL, ...

Variants.

- B trees: Bayer-McCreight (1972, Boeing)
- B+ trees: all data in external nodes.
- . B* trees: keeps pages at least 2/3 full.
- R-trees for spatial searching: GIS, VLSI.

Summary

Goal: ST implementation with log N guarantee for all ops.

- Probabilistic: randomized BST.
- Amortized: splay tree, hashing.
- Worst-case: red-black tree. From re-doubling
- Algorithms are variations on a theme: rotations when inserting.

Abstraction extends to give search algorithms for huge files.

B-tree.