

## COS 302: Introduction to Artificial Intelligence

Homework #7  
Machine learning

Fall 2003  
Due: Tuesday, January 13

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### Part I: Written Exercises

Turn these in on or before the due date in room 001A Computer Science. Approximate point values are given in parentheses. Be sure to show your work and justify all of your answers.

1. (32) Consider the following dataset consisting of five training examples followed by three test examples:

$x_1$	$x_2$	$x_3$	$y$
<i>training</i>			
-	+	+	-
+	+	+	+
-	+	-	+
-	-	+	-
+	+	-	+
<i>test</i>			
+	-	-	?
-	-	-	?
+	-	+	?

There are three attributes (or features or dimensions),  $x_1$ ,  $x_2$  and  $x_3$ , taking the values + and -. The label (or class) is given in the last column denoted  $y$ ; it also takes the two values + and -.

Simulate each of the following four learning algorithms on this dataset. In each case, show the final hypothesis that is induced, and show how it was computed. Also, say what its prediction would be on the three test examples.

For parts c and d, see the Chapter 20 errata below.

- The *decision tree algorithm* discussed in class and R&N. For this algorithm, use the information gain (entropy) impurity measure as a criterion for choosing an attribute to split on. Grow your tree until all nodes are pure, but do not attempt to prune the tree.
- AdaBoost*. For this algorithm, you should interpret label values of + and - as the real numbers +1 and -1. Use decision stumps as weak hypotheses, and assume that the weak learner always computes the decision stump with minimum error on the training set weighted by  $D_t$ . (Recall that a decision stump is a one-level decision tree; see R&N p. 666.)
- Support vector machines*. For this algorithm, you should interpret both label and attribute values of + and - as the real numbers +1 and -1. Also, you can use the additional information that the first three examples are support vectors, but the others are not, so that  $\alpha_4$  and  $\alpha_5$  are both zero in R&N Eq. (20.17). This means that you can maximize this equation over  $\alpha_1$ ,  $\alpha_2$  and  $\alpha_3$  using calculus. (Note that if any of these variables turn out to be negative, there's a problem.) When you have found a solution vector  $\mathbf{w}$ , check it by showing that  $y_i(\mathbf{w} \cdot \mathbf{x}_i) \geq 1$ , and that equality holds for the support vectors, i.e., the first three examples. (The notation here is as in class and R&N.)

- d. *Neural networks.* For this algorithm, use a single-layer neural net consisting of just a single perceptron at the output, no hidden layers, and the three features at the input level. Attribute values of + and − should be interpreted as the real numbers +1 and −1, while label values of + and − should be interpreted as 1 and 0. You can disregard the “bias weight” (denoted  $W_0$  in R&N), i.e., assume it is fixed to be zero. Assume that the neural net is trained for a single epoch that runs through the training data once in the order given. Use a learning rate of  $\alpha = 0.1$ , and start with all weights equal to zero.

2. (15) In class, we looked at the following dataset:

$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	$x_8$	$y$
1	1	0	0	0	1	0	1	1
1	0	0	0	0	0	0	0	0
0	0	0	1	1	1	1	0	0
0	1	0	0	1	0	0	0	0
1	0	0	0	0	1	0	1	0
0	1	1	0	1	1	0	1	1
1	1	0	1	0	1	0	1	1
0	1	0	1	0	1	0	0	1
0	0	0	0	0	0	1	1	0

It was noticed that the label  $y$  is 1 if and only if  $x_2$  and  $x_6$  are both equal to 1. Since attributes and labels are  $\{0, 1\}$ -valued, we can write this rule succinctly as  $y = x_2x_6$ . In general, such a product of any number of attributes is called a *monomial*. (This includes the “empty” monomial, which, being a product of no variables, is always equal to 1.)

Throughout this problem, you can assume that the attributes and labels are all  $\{0, 1\}$ -valued.

- Describe a simple algorithm that, given a dataset, will efficiently (in polynomial time) find a monomial consistent with it, assuming that one exists.
- What is the total number of monomials that can be defined on  $n$  attributes?
- Use the bound derived in class (or the results in R&N) to compute an upper bound on the generalization error of the monomial that was found to be consistent with the dataset above. Derive a bound that holds with 95% confidence (so that  $\delta = 0.05$ ).
- In the example above where  $n = 8$ , how many examples would be needed to be sure the generalization error of a consistent monomial is at most 10% with 95% confidence?

## Part II: Programming

The programming part of this assignment is described at:

<http://www.cs.princeton.edu/courses/cs302/assignments/learning/index.html>

## Chapter 20 Errata

There are a couple of errors in Chapter 20 of R&N.

First of all, the equation second from the bottom on page 741 that now reads:

$$= Err \times \frac{\partial}{\partial W_j} g \left( y - \sum_{j=0}^n W_j x_j \right)$$

should instead read:

$$= Err \times \frac{\partial}{\partial W_j} \left( y - g \left( \sum_{j=0}^n W_j x_j \right) \right).$$

Secondly, the paragraph describing SVM's at the very bottom of page 749 continuing at the top of 751 is not quite correct, but some explanation is required to describe what the problem is. In class, we implicitly required the hyperplane sought by the SVM algorithm to pass through the origin. This resulted in a hypothesis of the form

$$\text{sign}(\mathbf{w} \cdot \mathbf{x}).$$

In other treatments of SVM's, however, the hyperplane is often *not* required to pass through the origin. Thus, the computed hypothesis has the form

$$\text{sign}(\mathbf{w} \cdot \mathbf{x} + b),$$

so that the hyperplane is defined both by the vector  $\mathbf{w}$  and the scalar  $b$ .

The treatment in R&N is not quite correct for either of these cases. For the through-the-origin case, their treatment would be correct if the constraint  $\sum_i \alpha_i y_i = 0$  were omitted. With the omission of this constraint, their treatment is the same as was presented in class. For the not-through-the-origin case, the treatment in R&N would be correct if Eq. (20.18) were replaced by

$$h(\mathbf{x}) = \text{sign} \left( \sum_i \alpha_i y_i (\mathbf{x} \cdot \mathbf{x}_i) + b \right),$$

for some  $b$  that can be written in terms of the other variables (details omitted). For this class (including Problem 1c above), we will only consider the through-the-origin case.