









6 Image-Based Representations	
7D	$F(x,y,z,\phi,\theta,\lambda,t)$ Ideal
6D	Consider only 3 frequencies (RGB)
5D	Consider only one time instant (static scene)
4D	Consider only viewpoints inside/outside scene
3D	Consider one dimension fewer directions/positions
2D	Consider viewpoints at finite set points or angles
	<b>7</b>















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